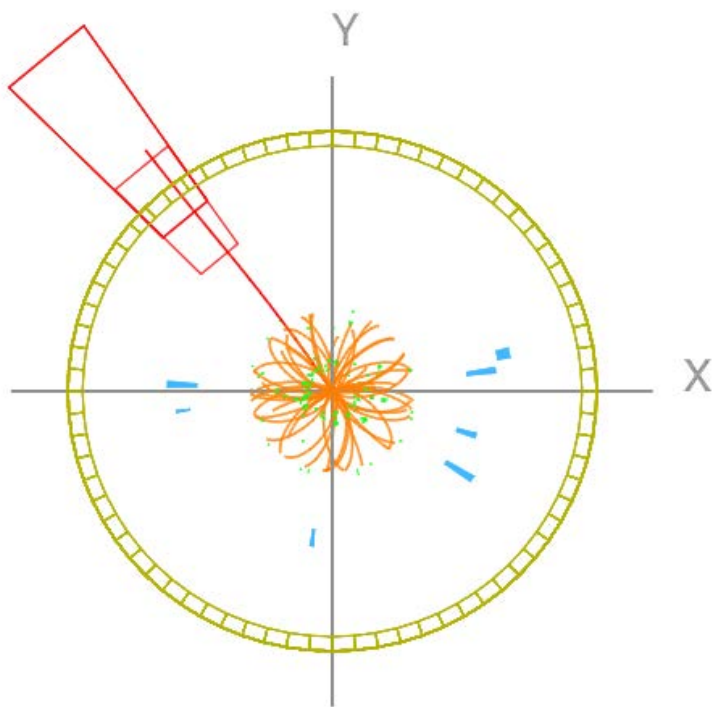
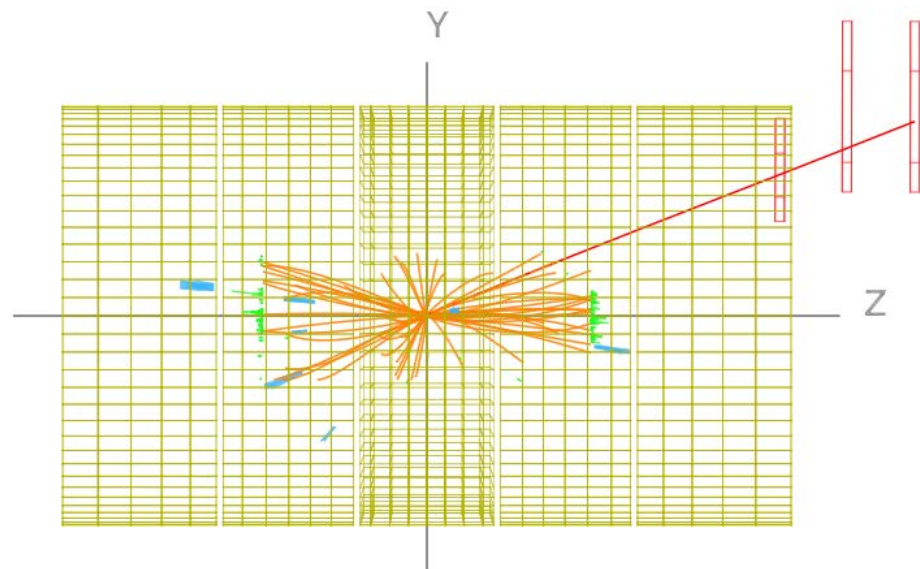


# CMS-W2D2

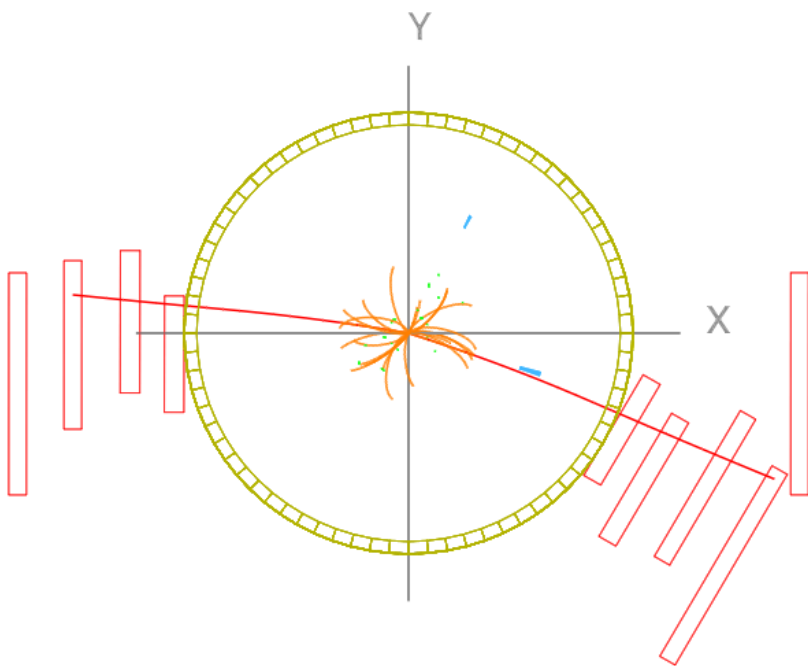
Measurement for  
Masterclass-in-a-box  
Data Set 1



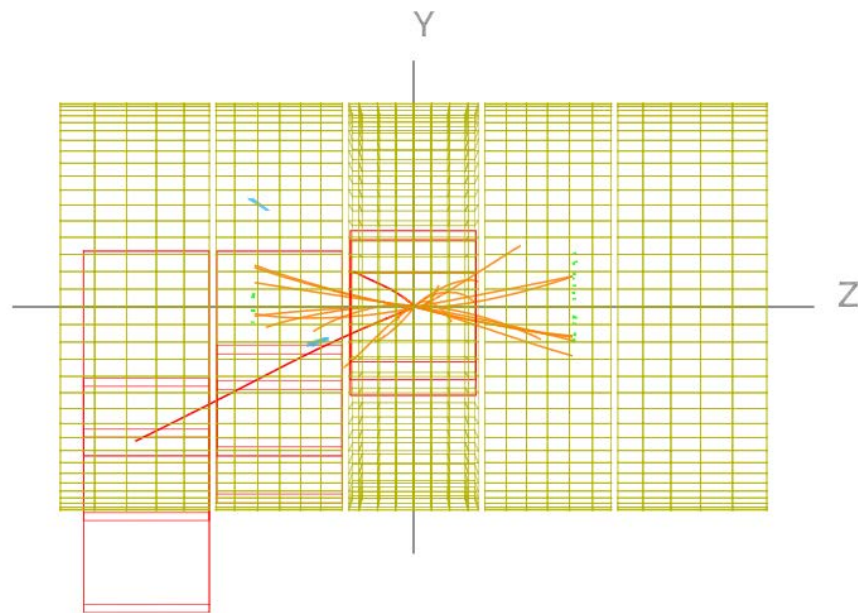
x-y view: measure  $\phi$



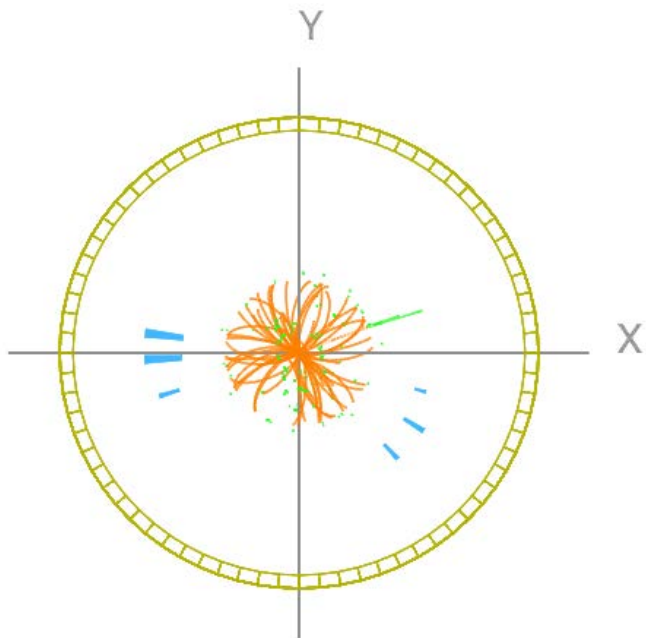
z-y view: measure  $\theta$



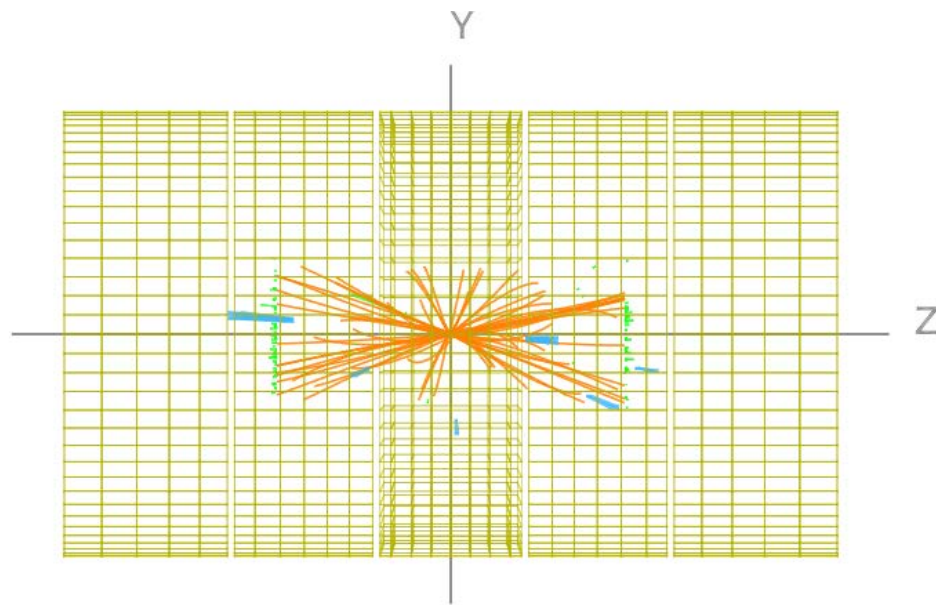
x-y view: measure  $\phi$



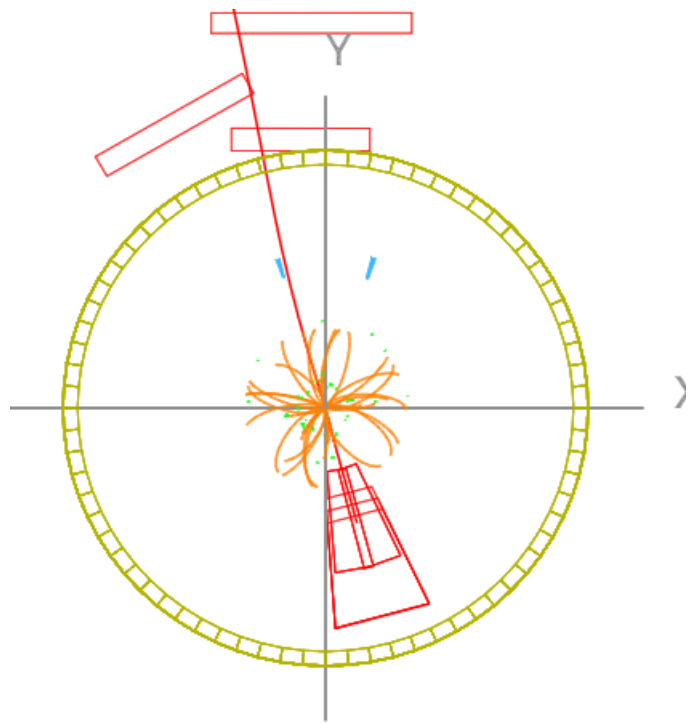
z-y view: measure  $\theta$



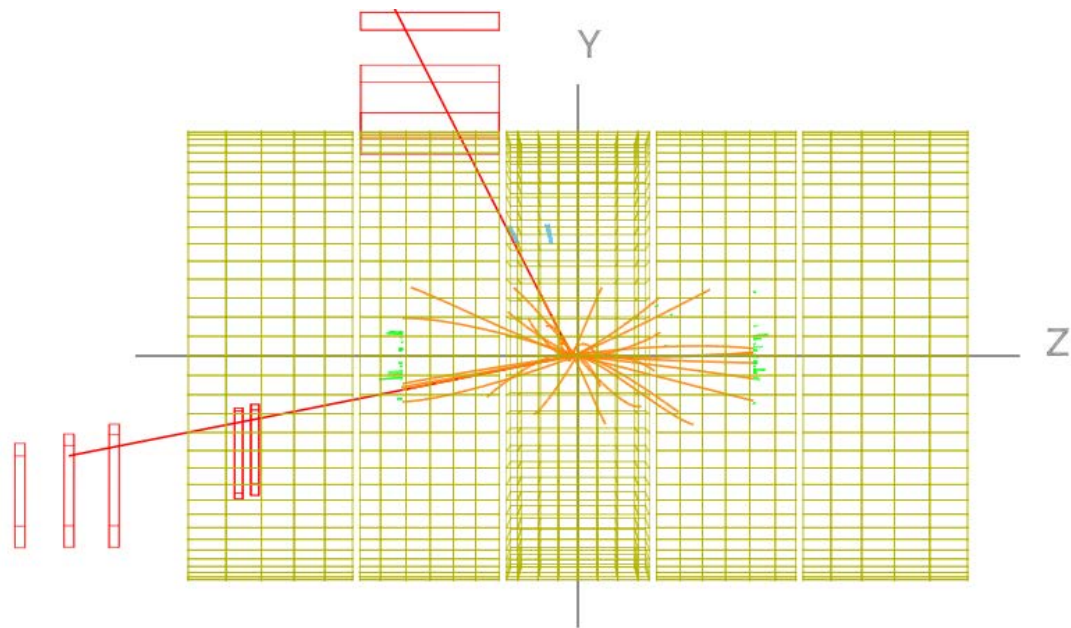
x-y view: measure  $\phi$



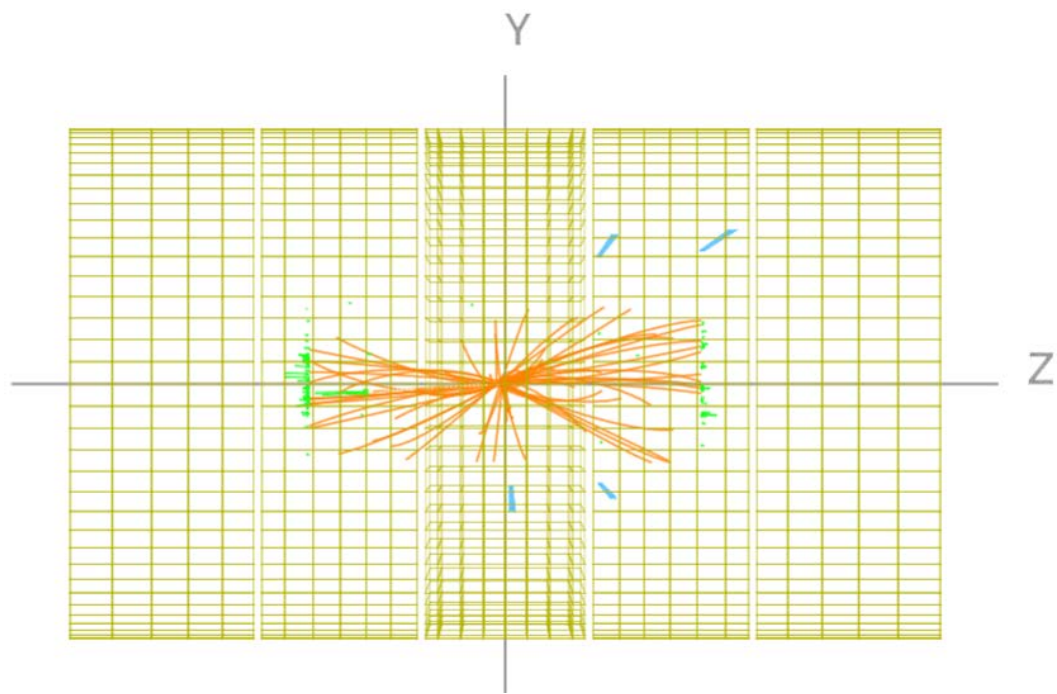
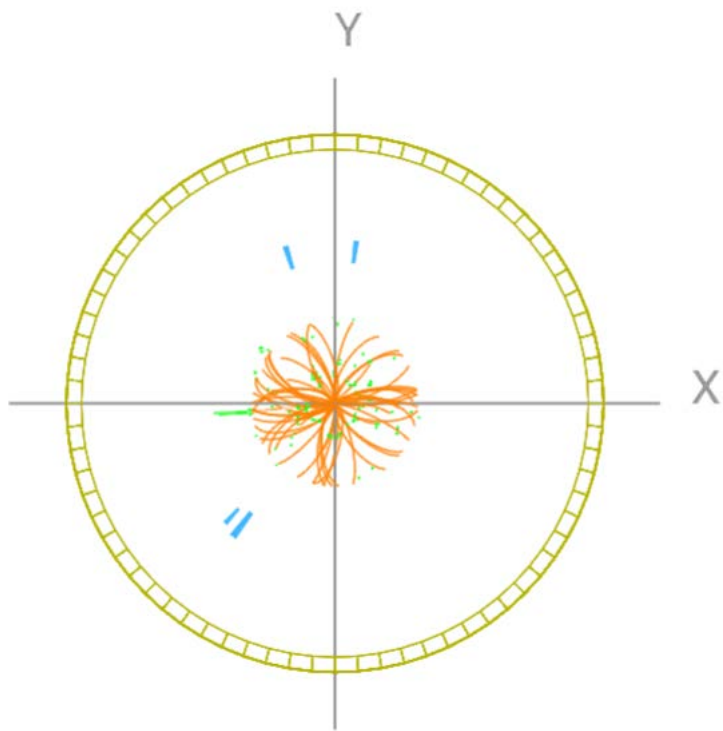
z-y view: measure  $\theta$



x-y view: measure  $\phi$

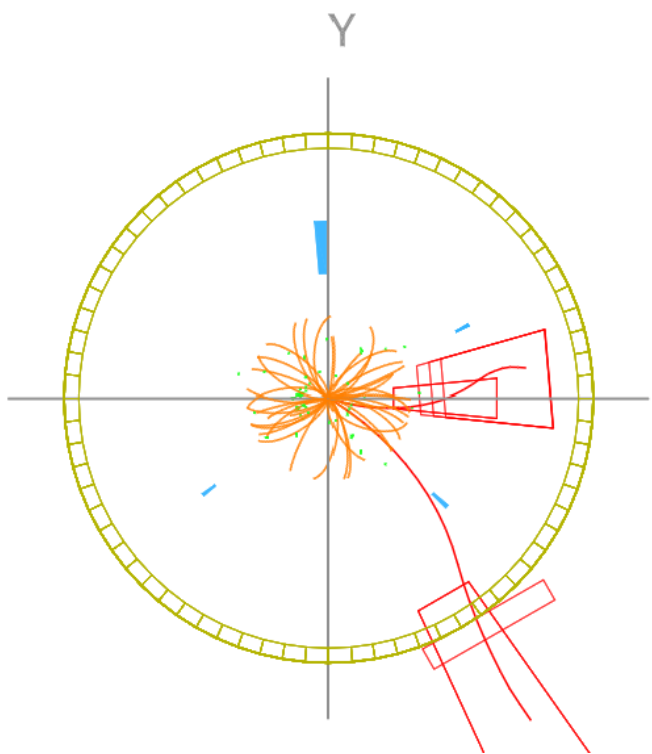


z-y view: measure  $\theta$

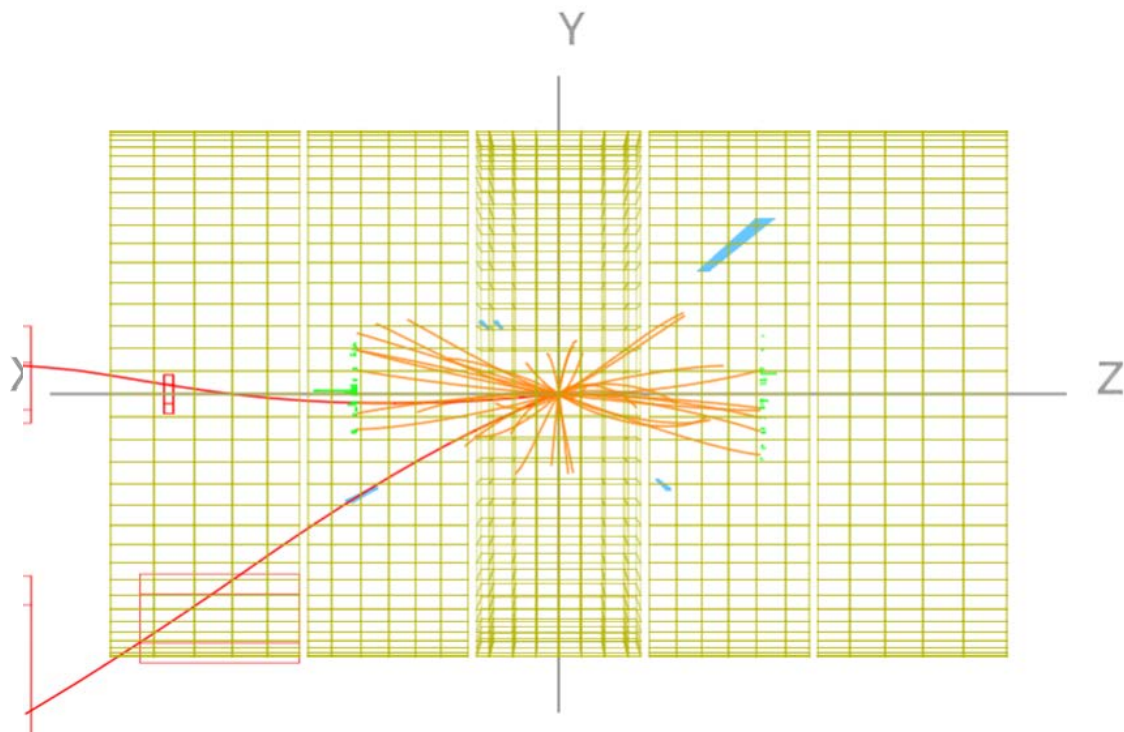


x-y view: measure  $\phi$

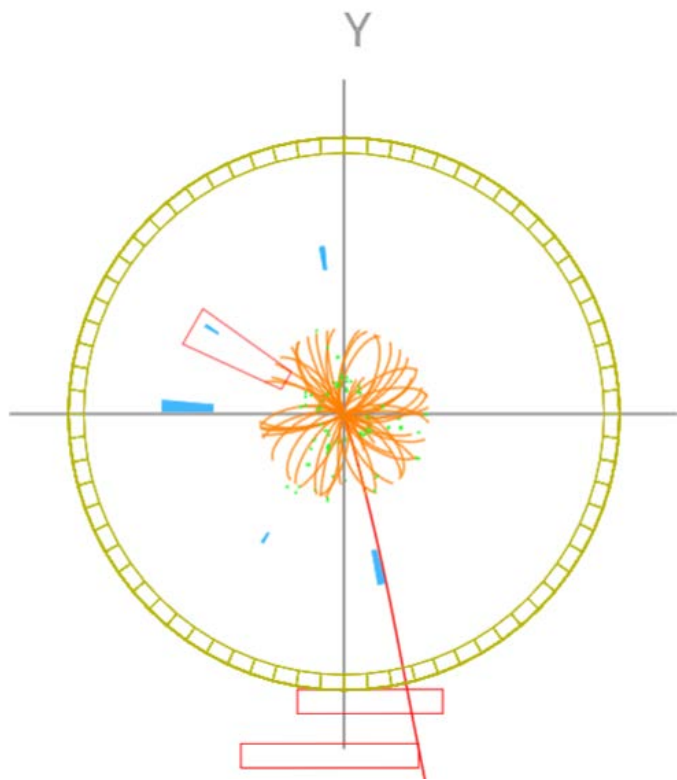
z-y view: measure  $\theta$



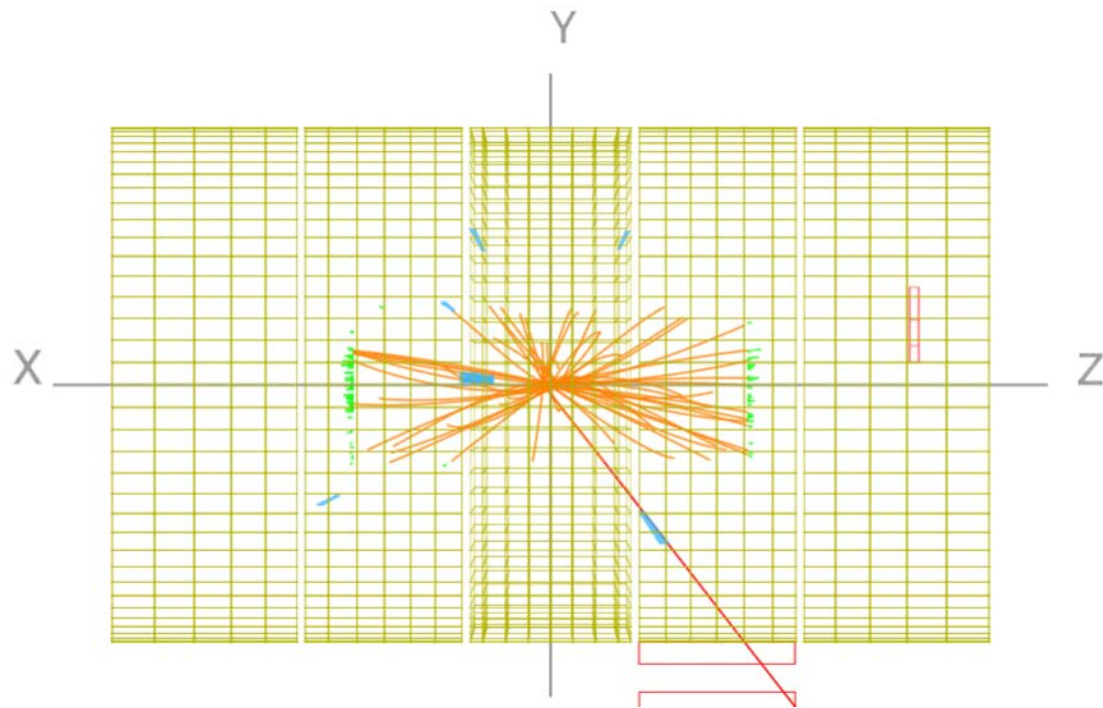
x-y view: measure  $\phi$



z-y view: measure  $\theta$

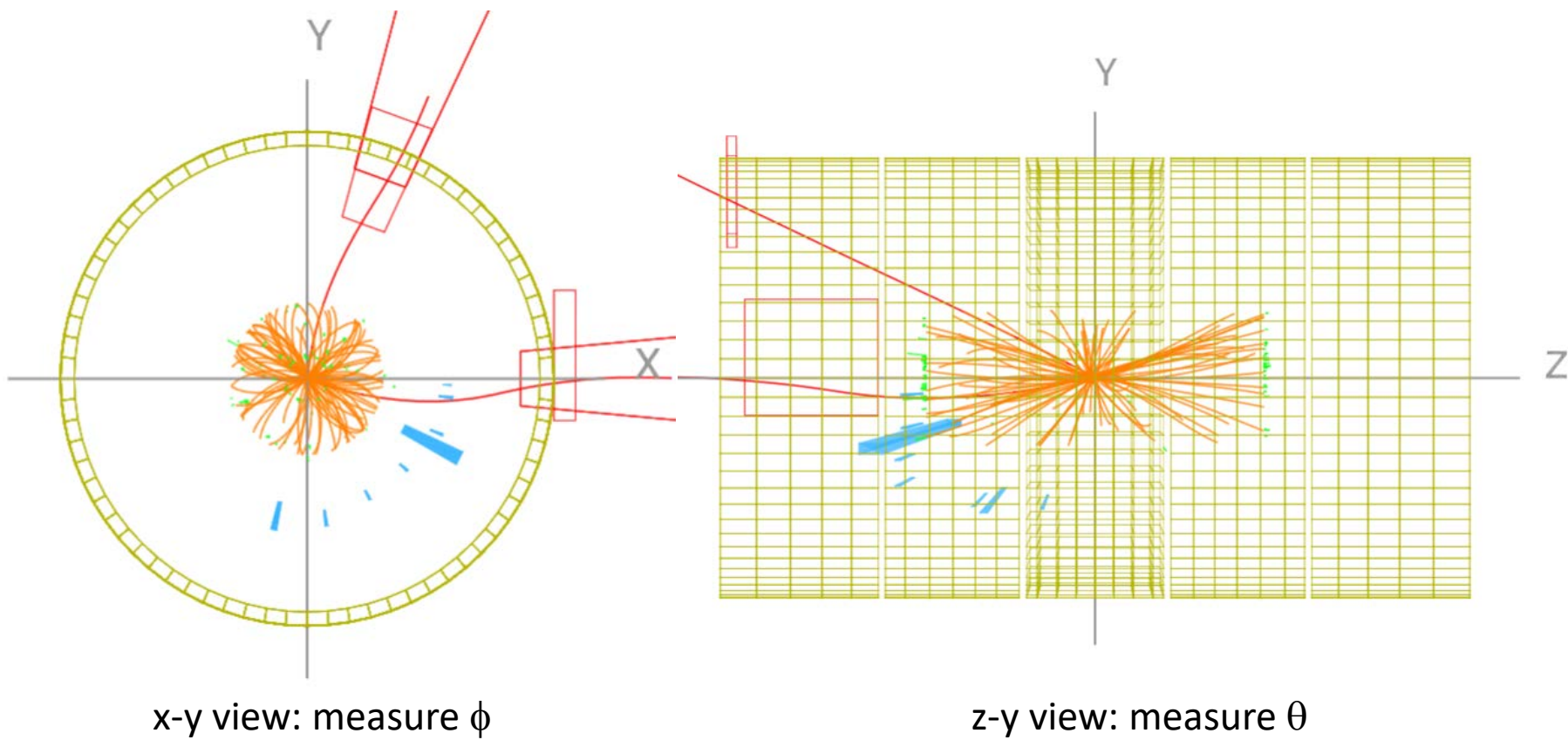


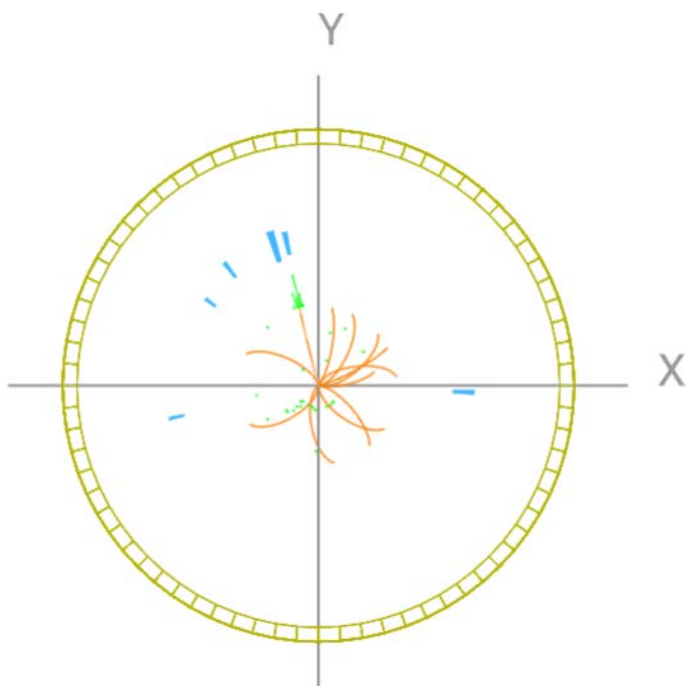
x-y view: measure  $\phi$



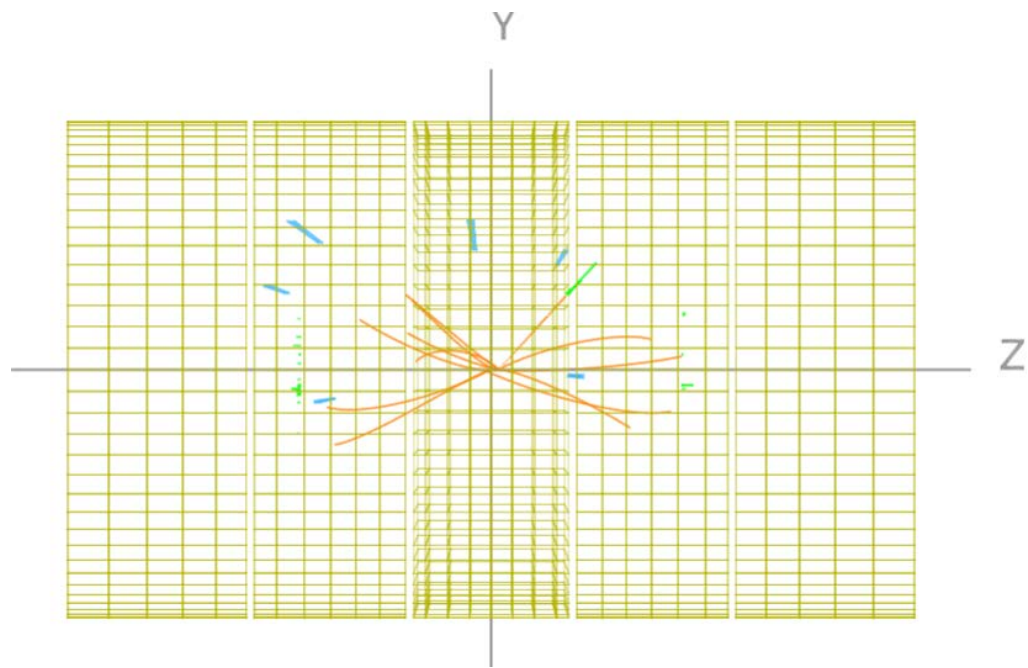
z-y view: measure  $\theta$



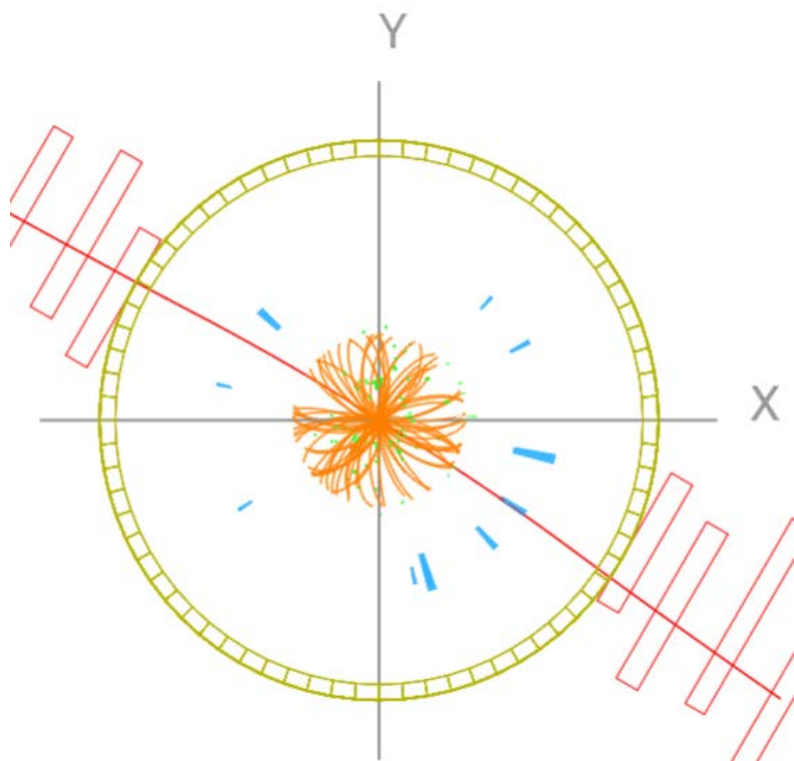




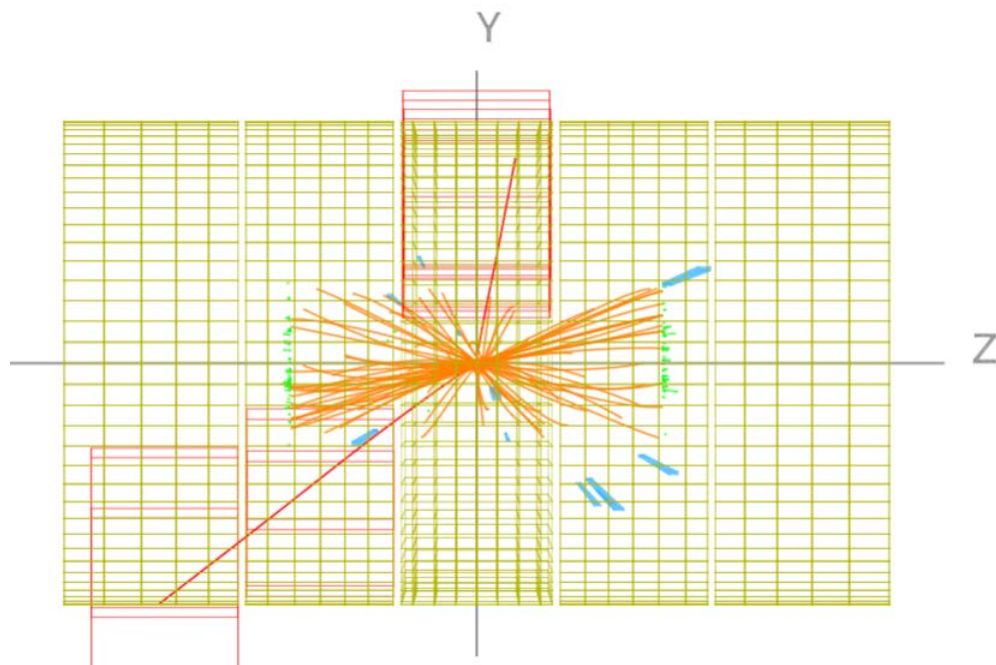
x-y view: measure  $\phi$



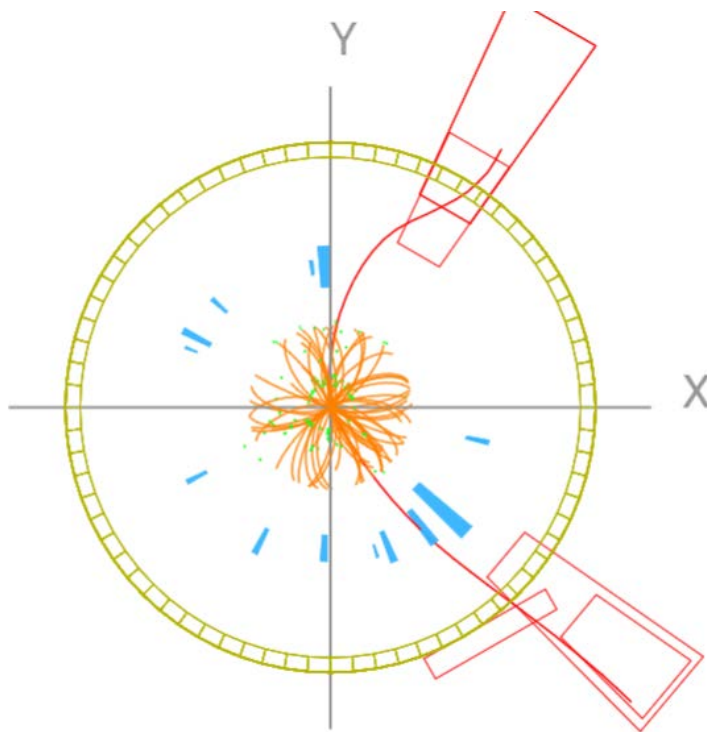
z-y view: measure  $\theta$



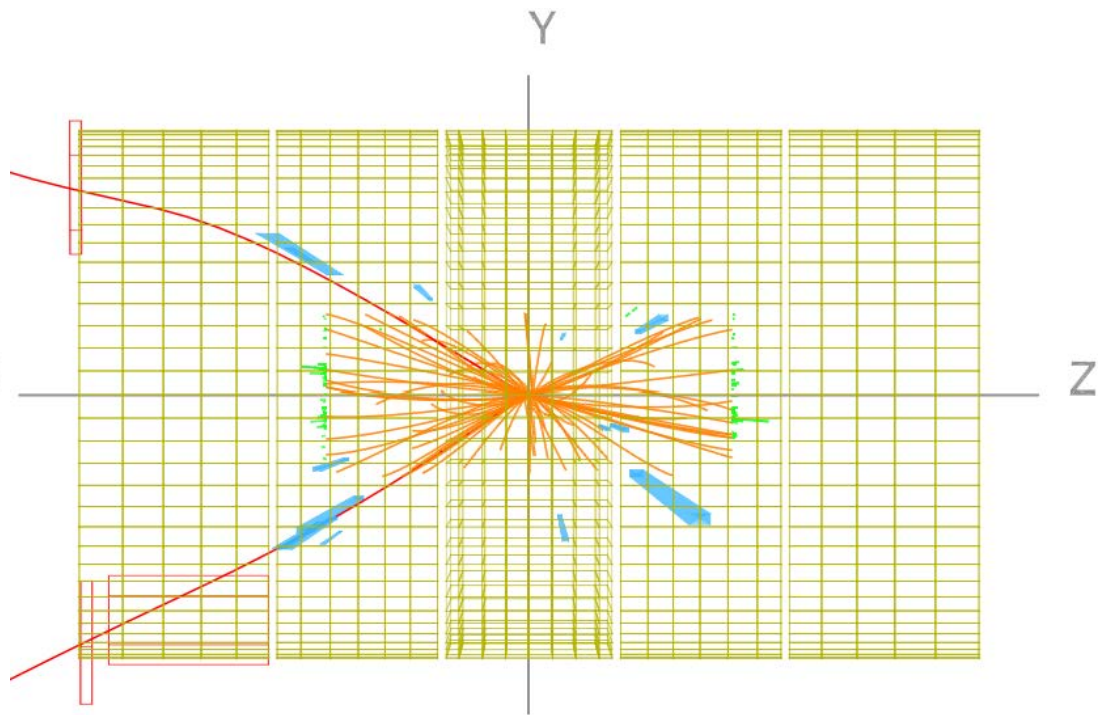
x-y view: measure  $\phi$



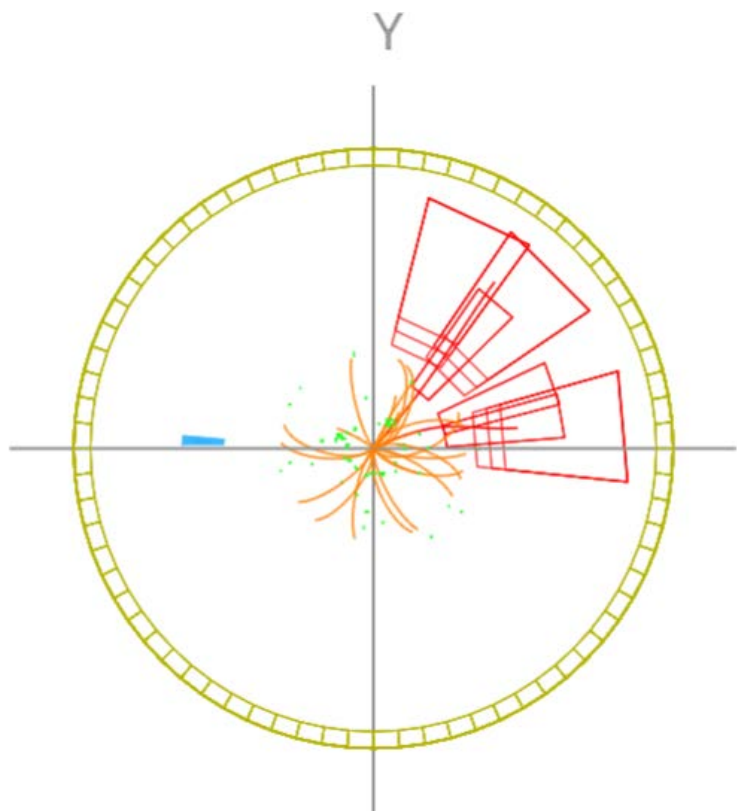
z-y view: measure  $\theta$



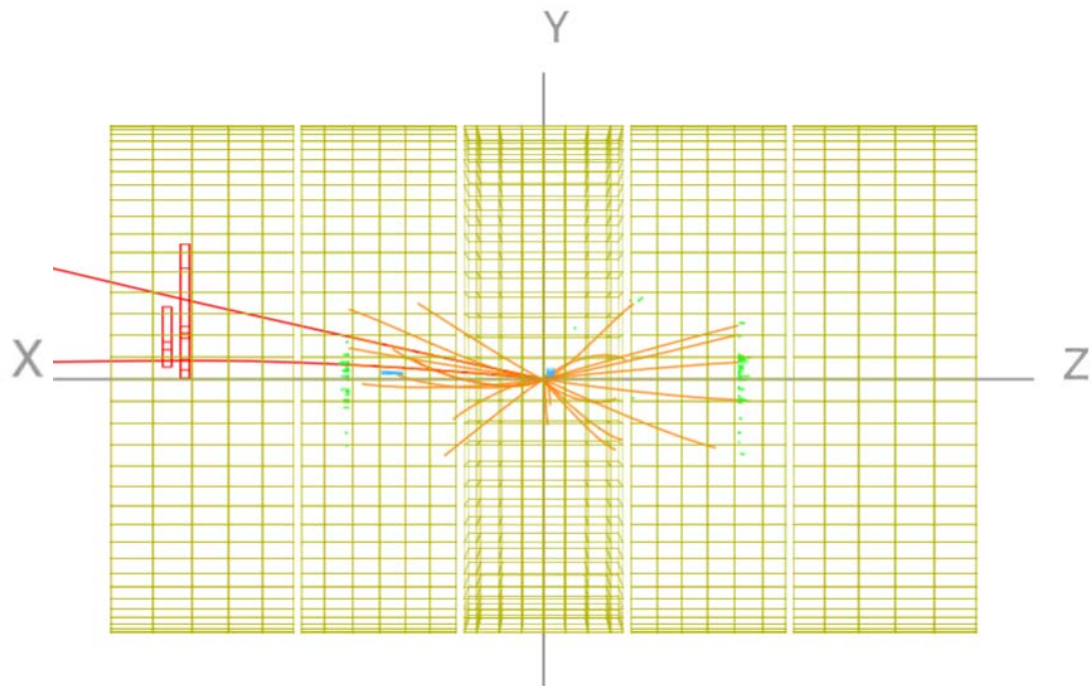
x-y view: measure  $\phi$



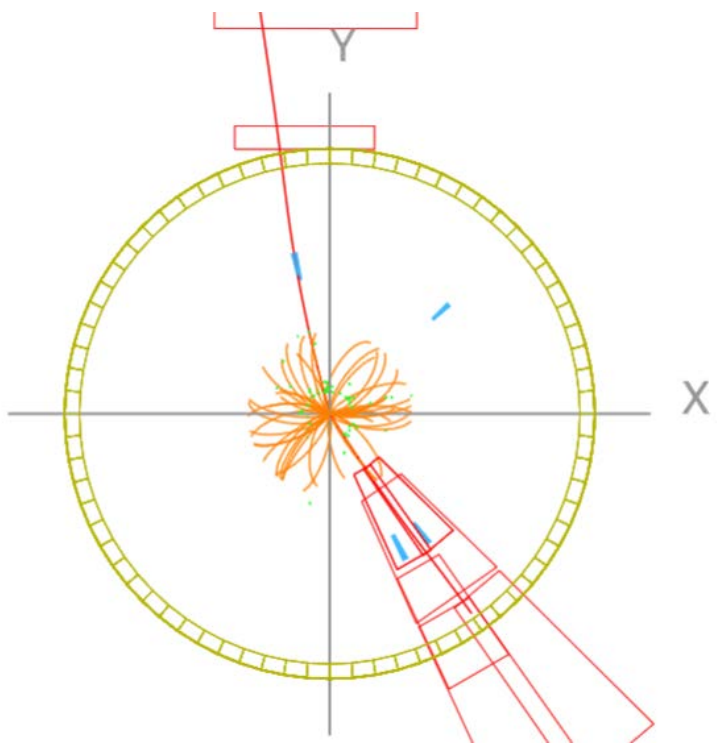
z-y view: measure  $\theta$



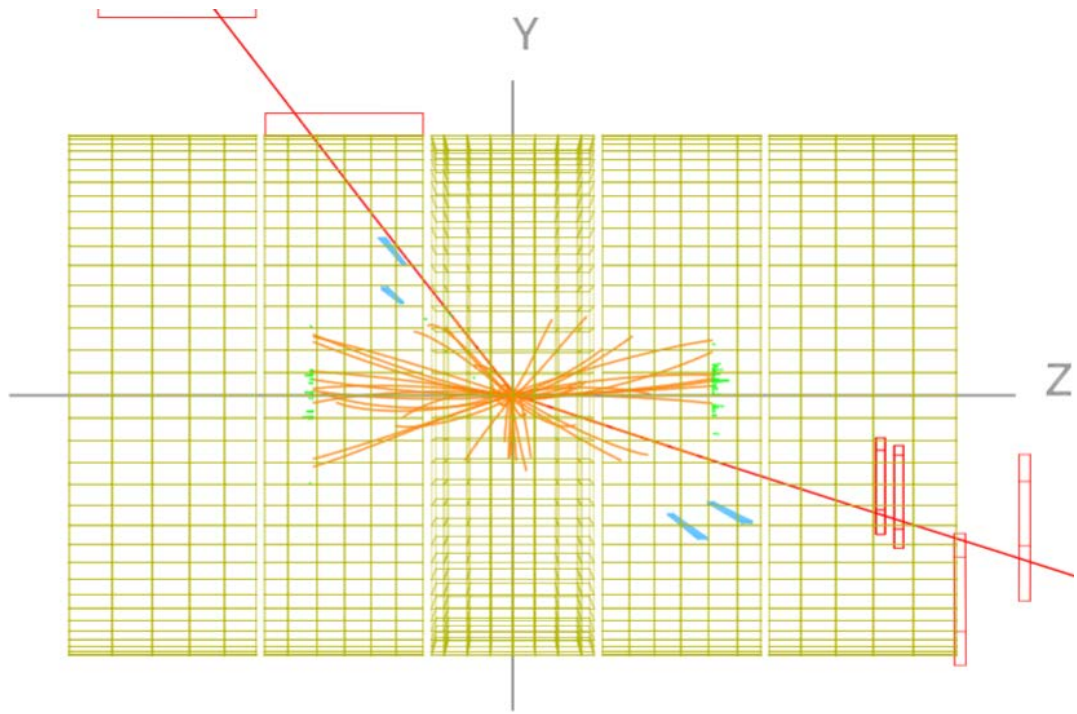
x-y view: measure  $\phi$



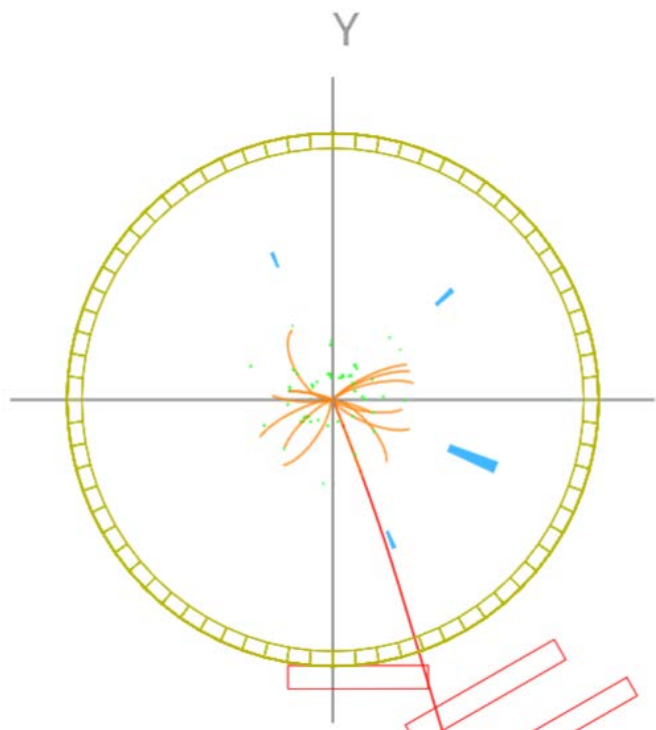
z-y view: measure  $\theta$



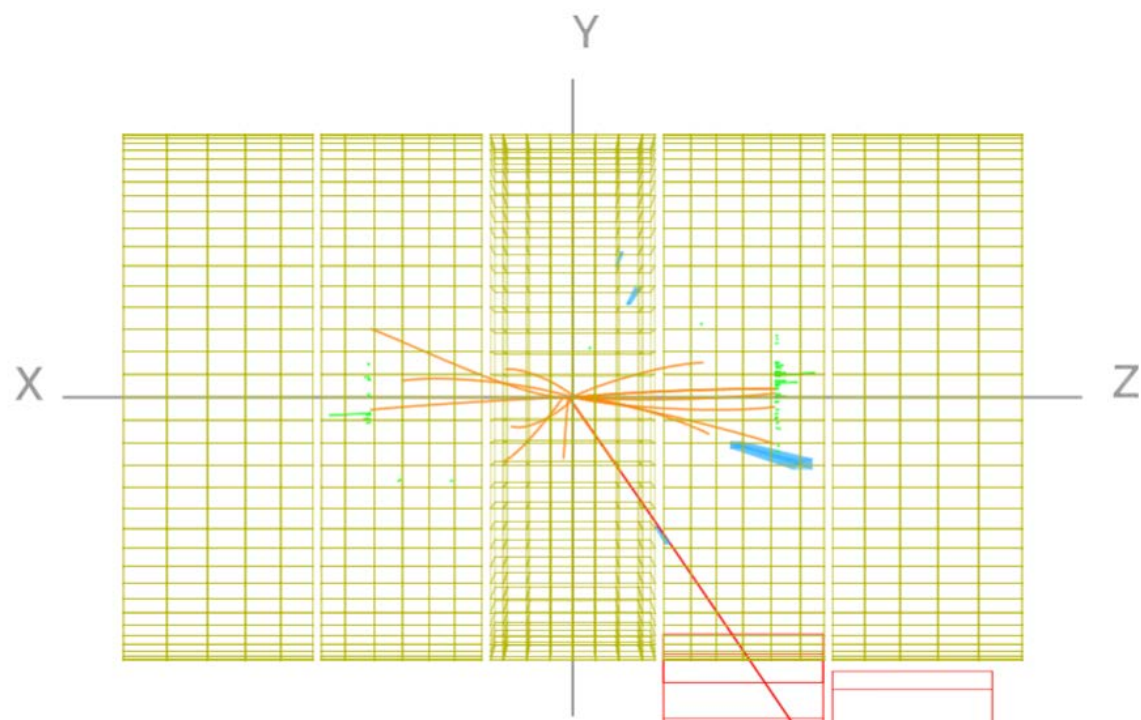
x-y view: measure  $\phi$



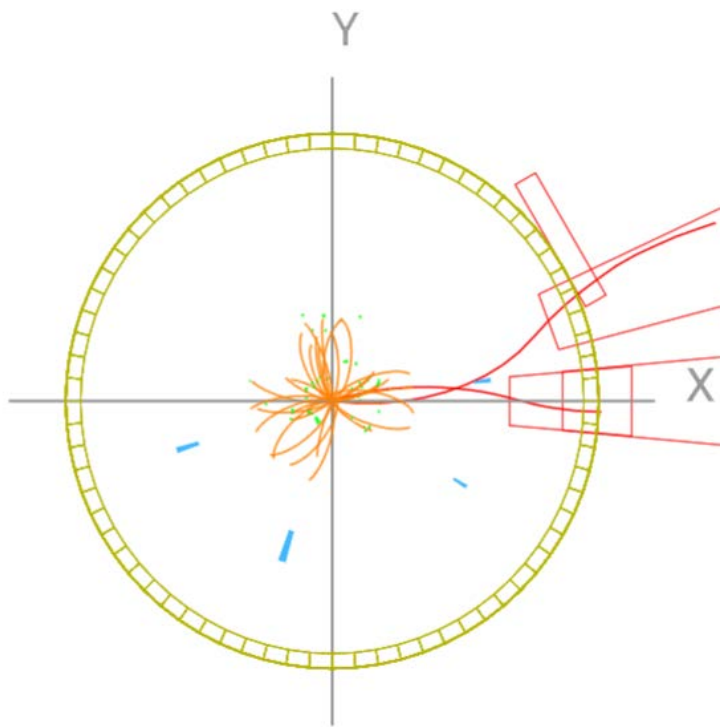
z-y view: measure  $\theta$



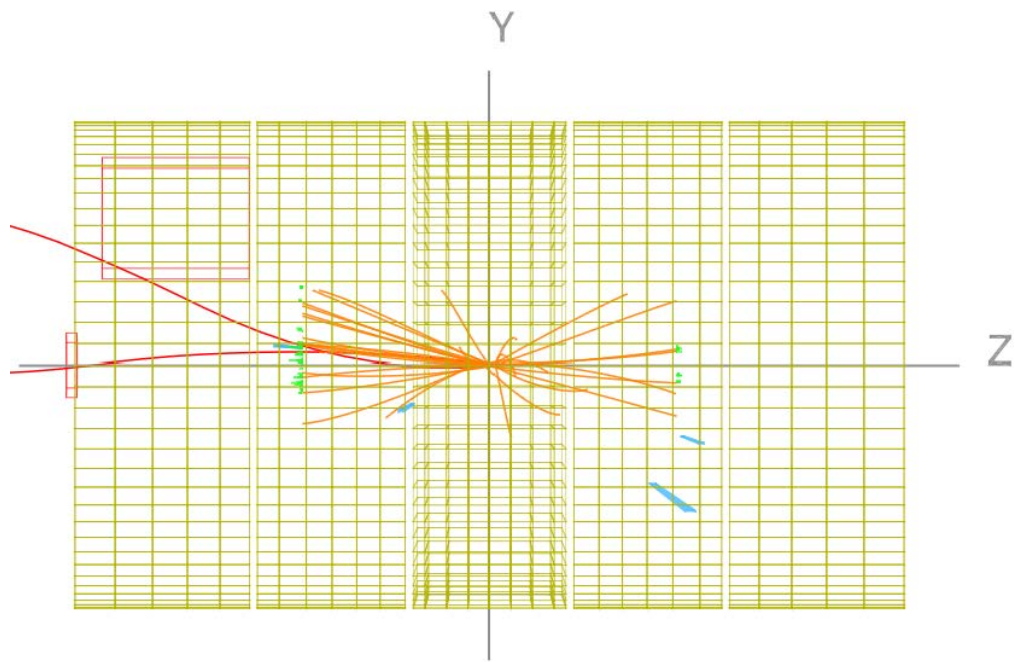
x-y view: measure  $\phi$



z-y view: measure  $\theta$

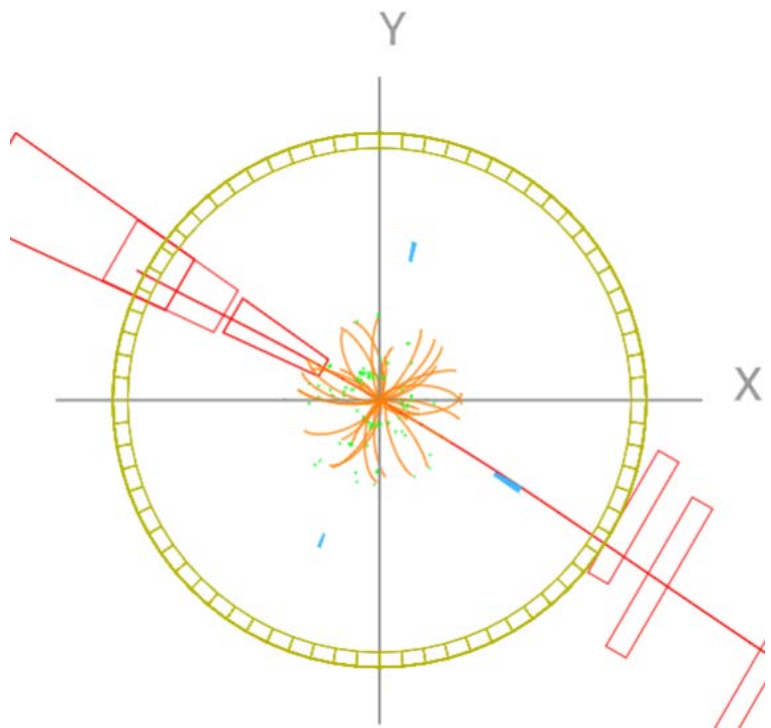


x-y view: measure  $\phi$

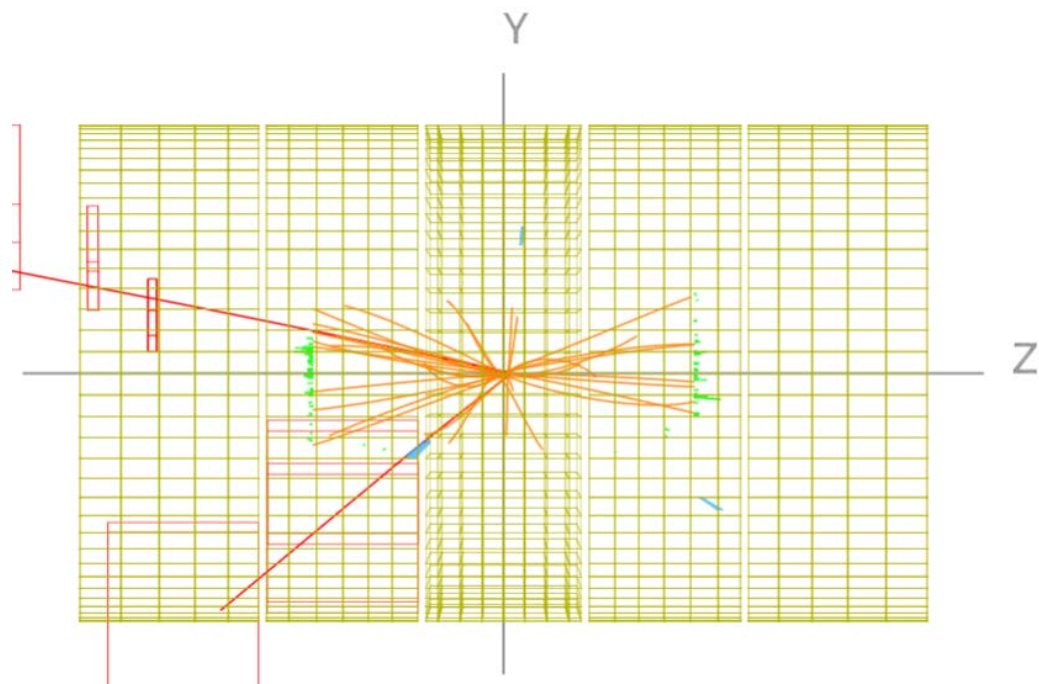


z-y view: measure  $\theta$

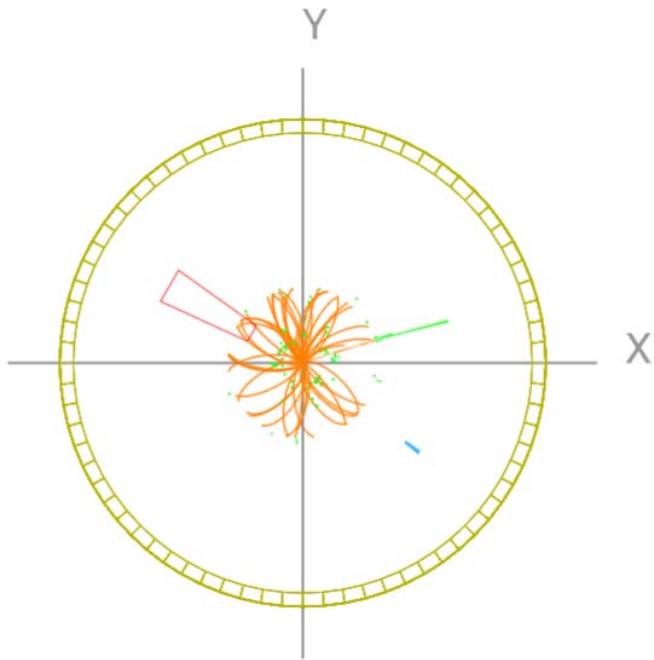




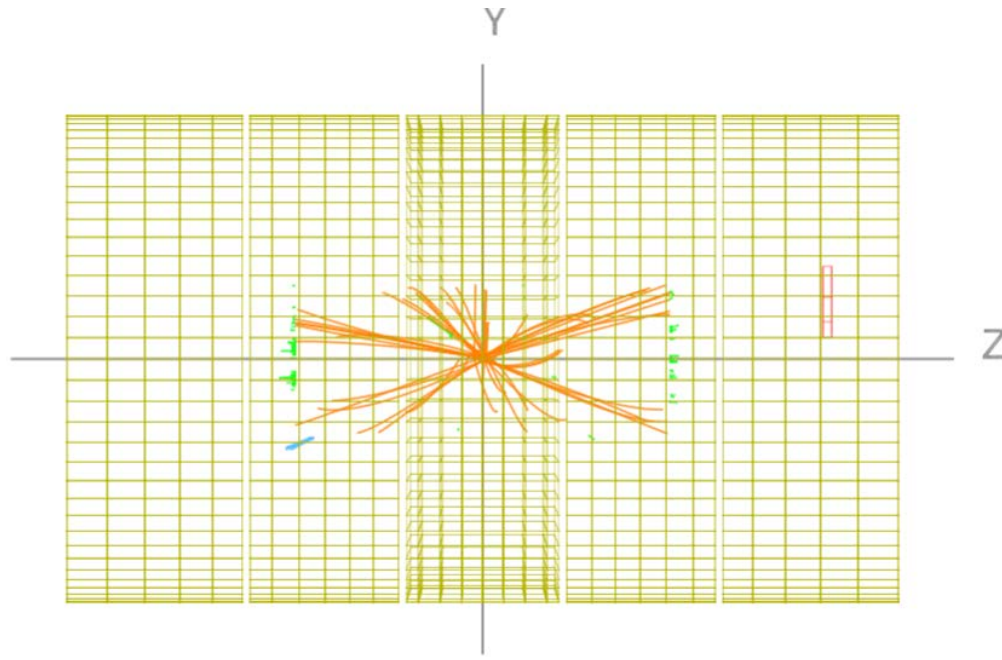
x-y view: measure  $\phi$



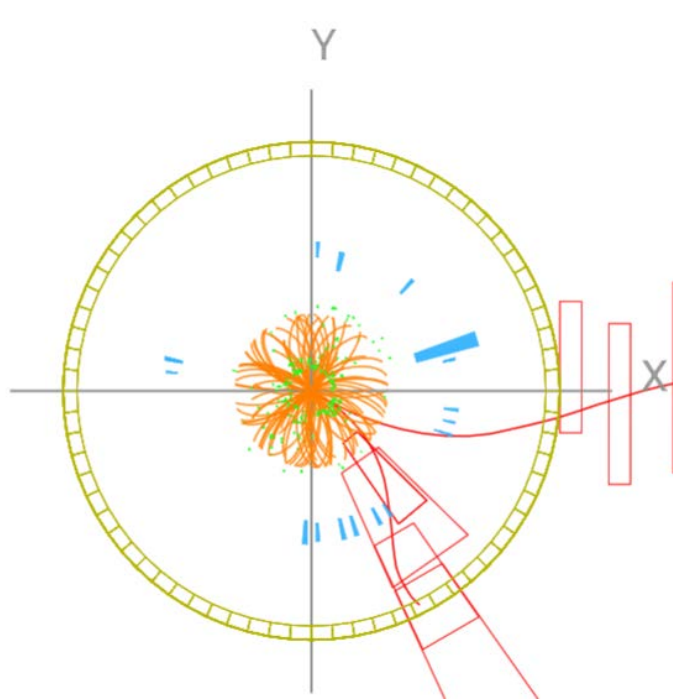
z-y view: measure  $\theta$



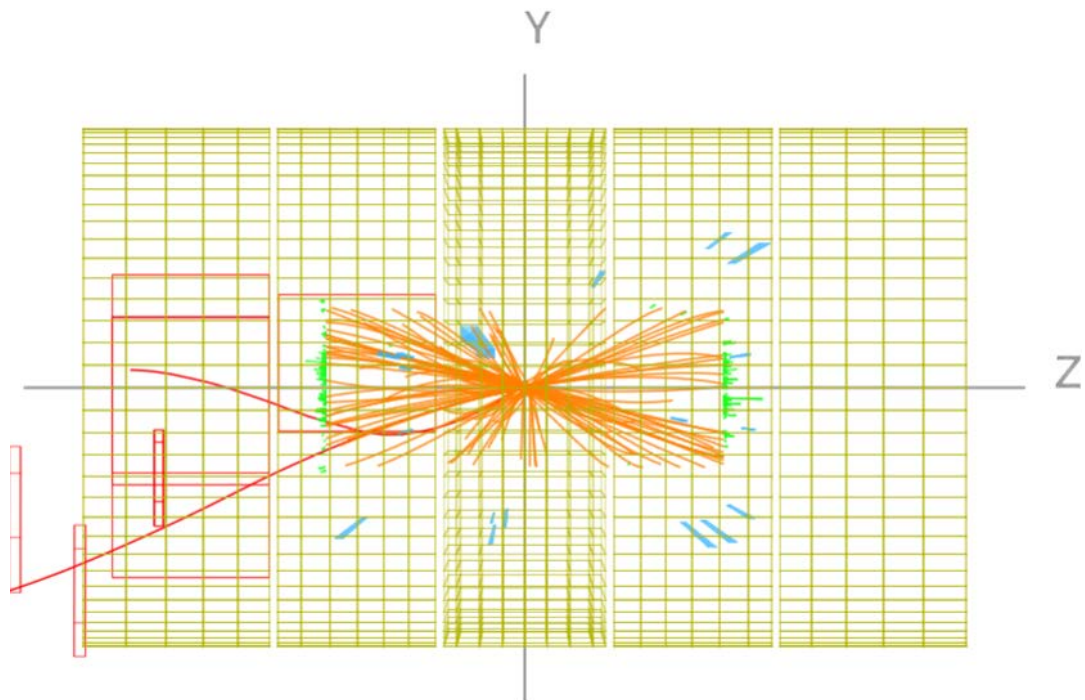
x-y view: measure  $\phi$



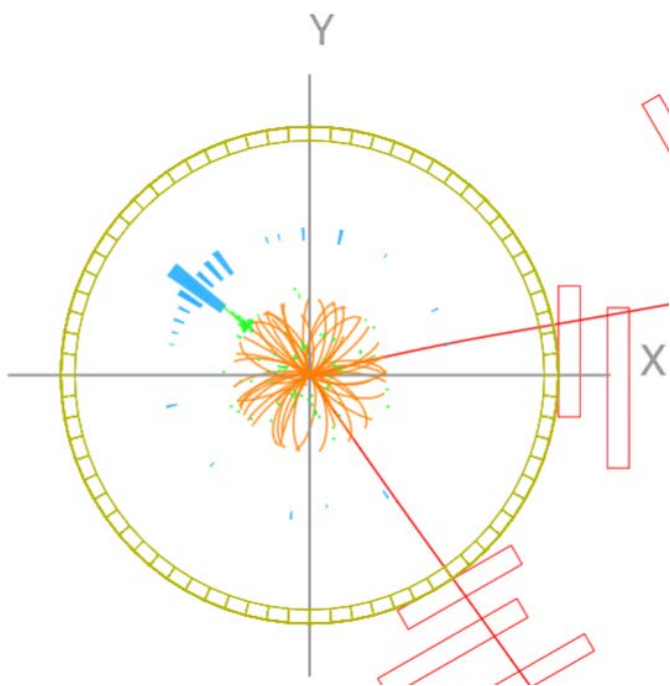
z-y view: measure  $\theta$



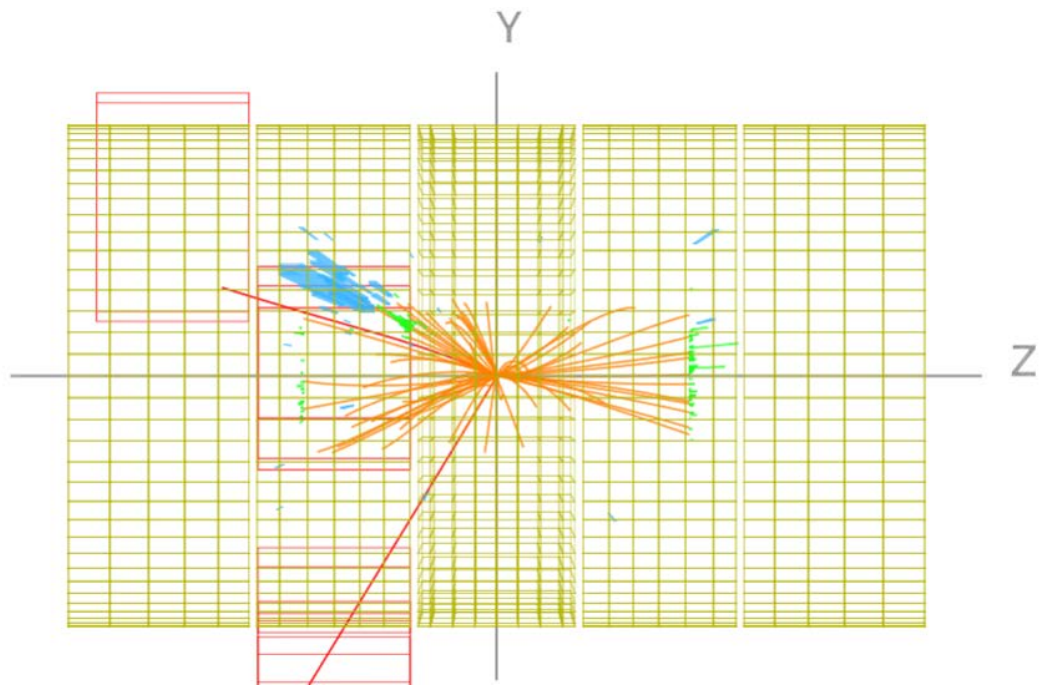
x-y view: measure  $\phi$



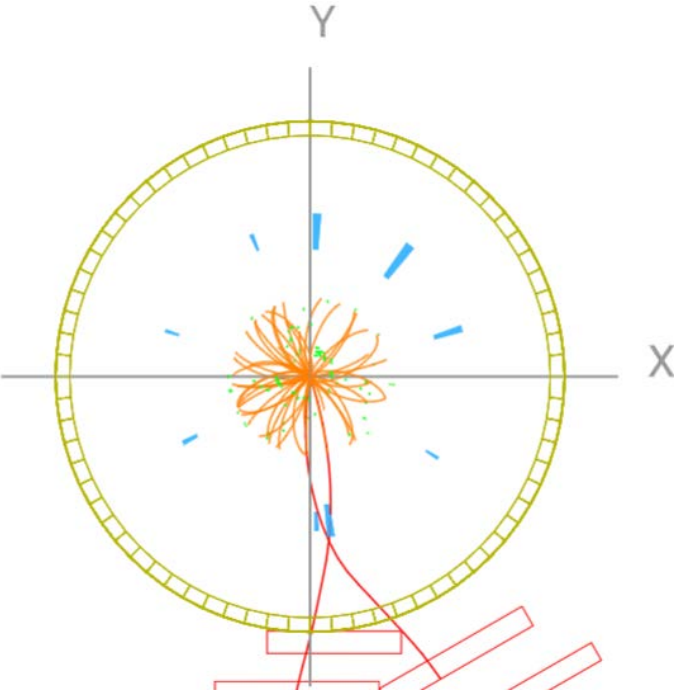
z-y view: measure  $\theta$



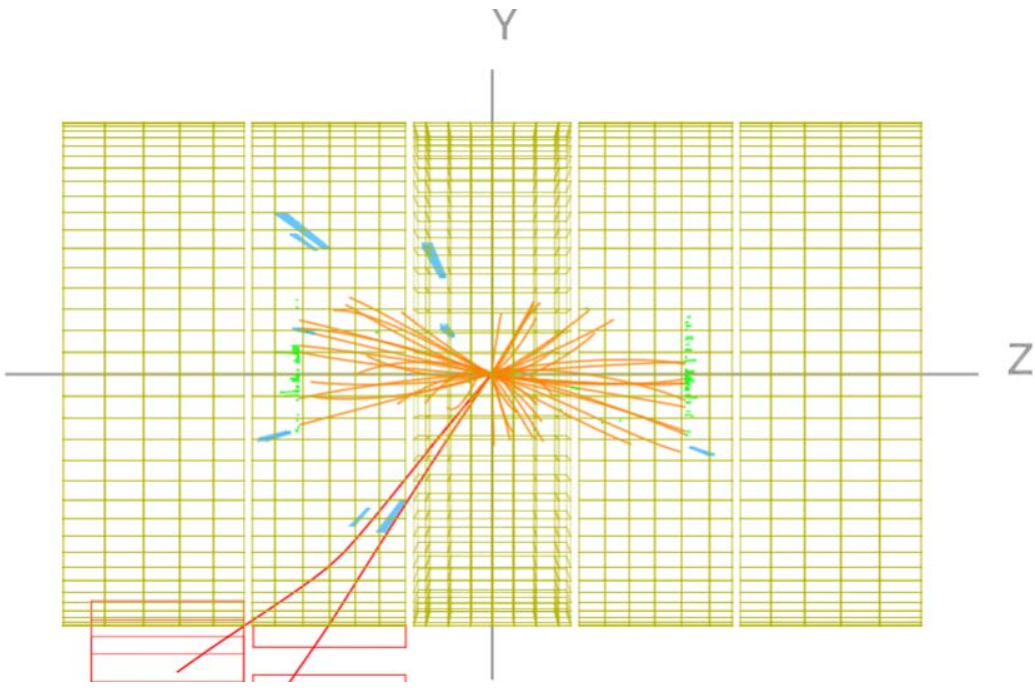
x-y view: measure  $\phi$



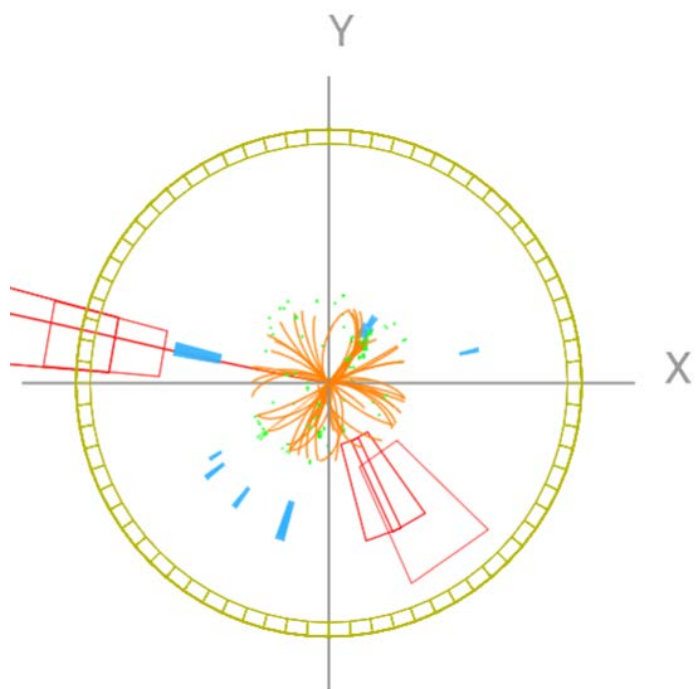
z-y view: measure  $\theta$



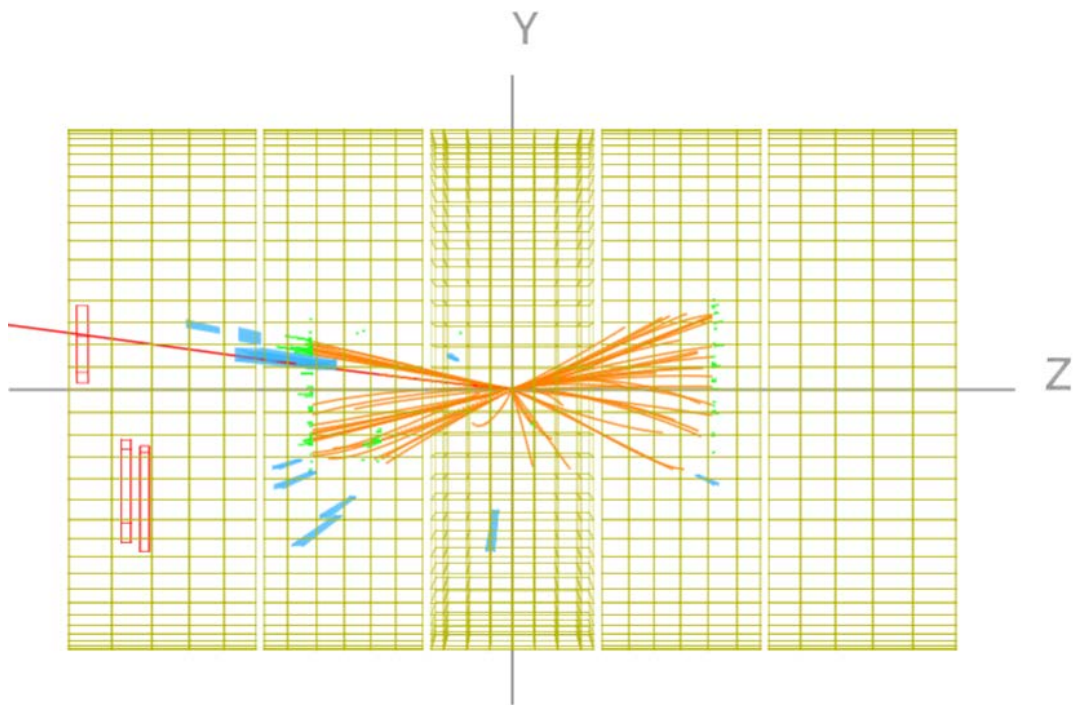
x-y view: measure  $\phi$



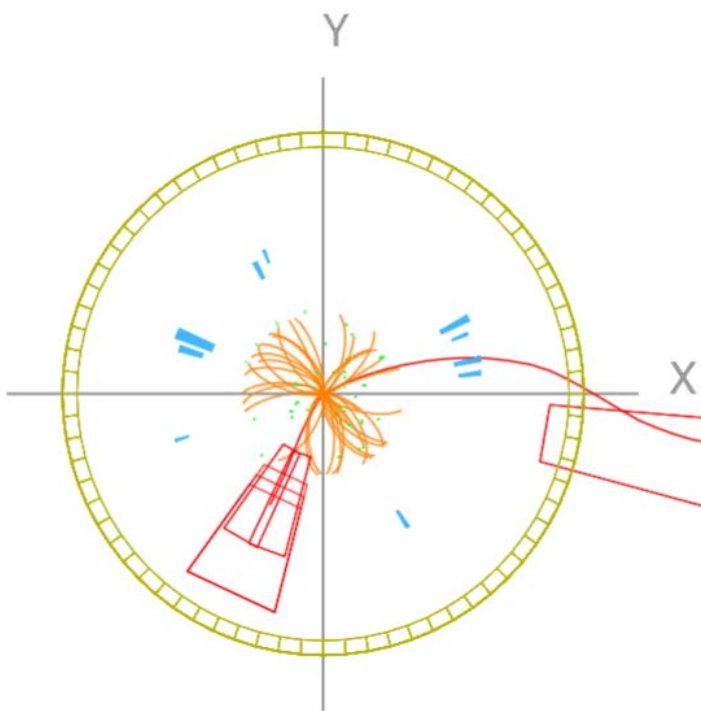
z-y view: measure  $\theta$



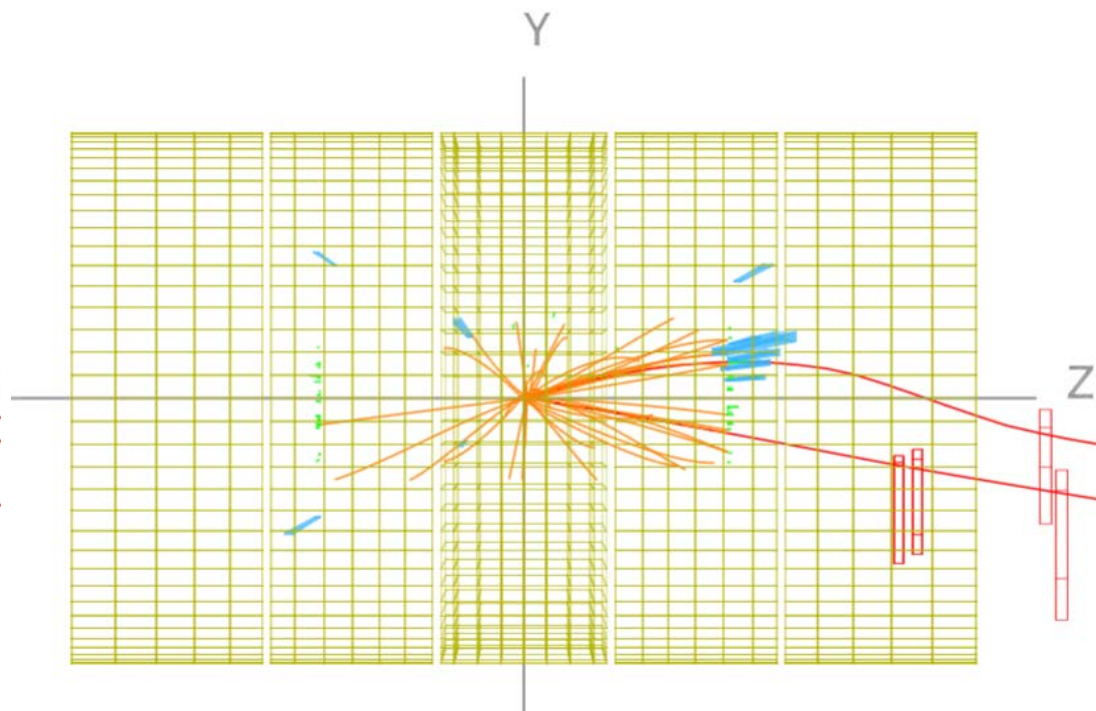
x-y view: measure  $\phi$



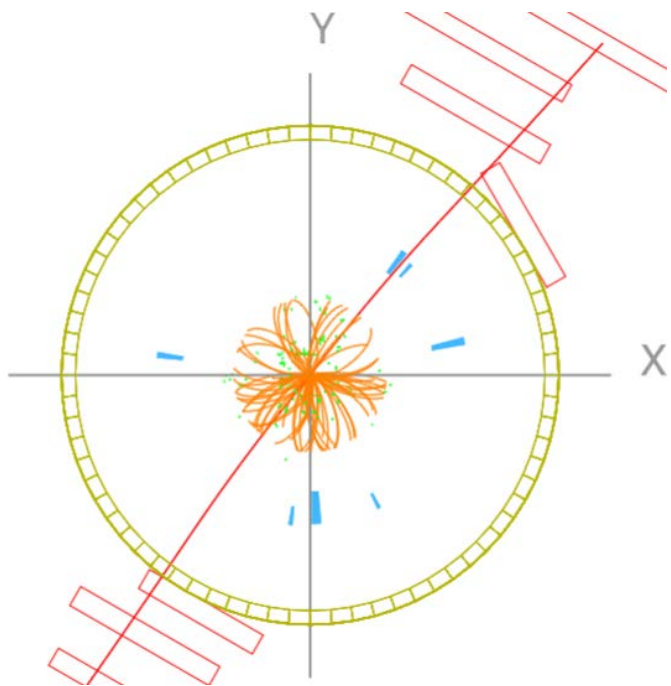
z-y view: measure  $\theta$



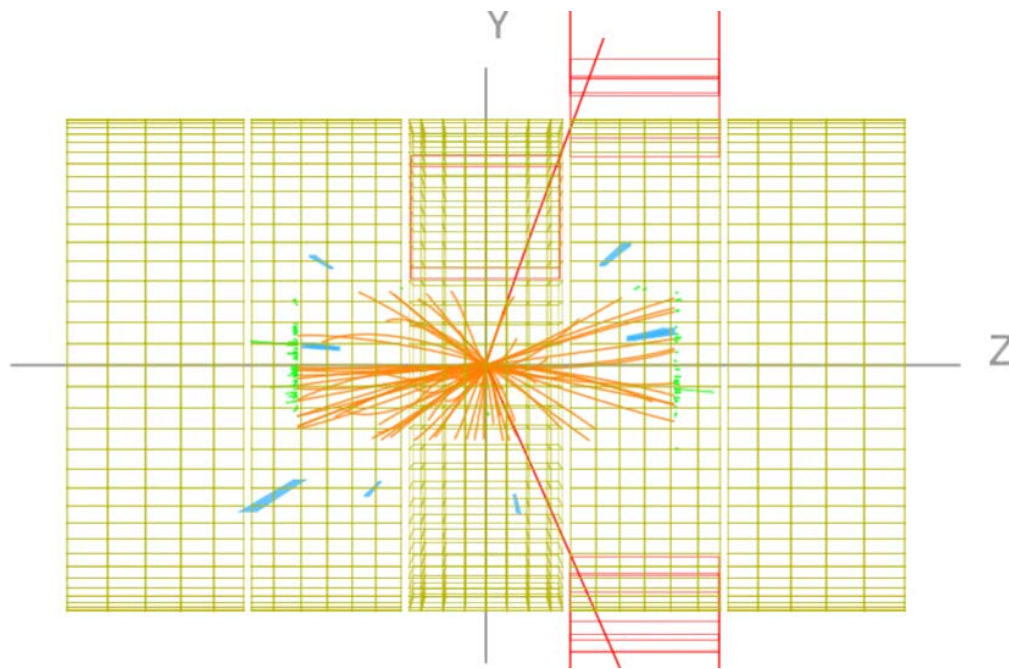
x-y view: measure  $\phi$



z-y view: measure  $\theta$

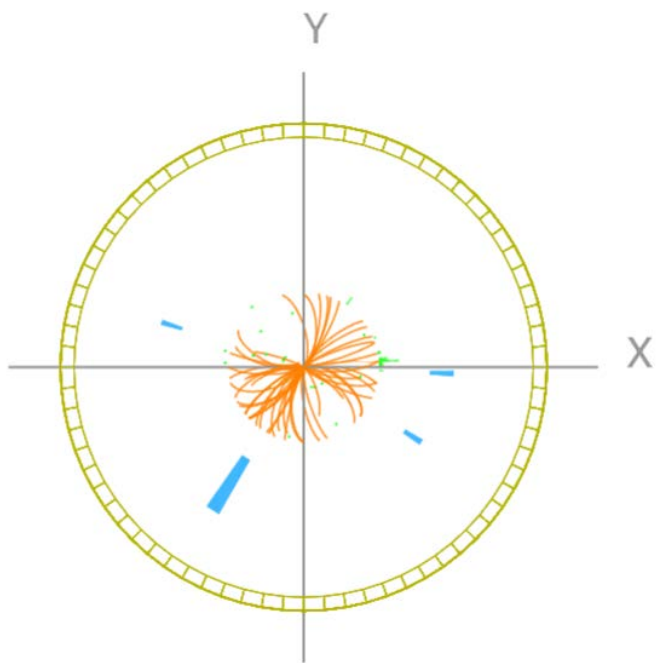


x-y view: measure  $\phi$

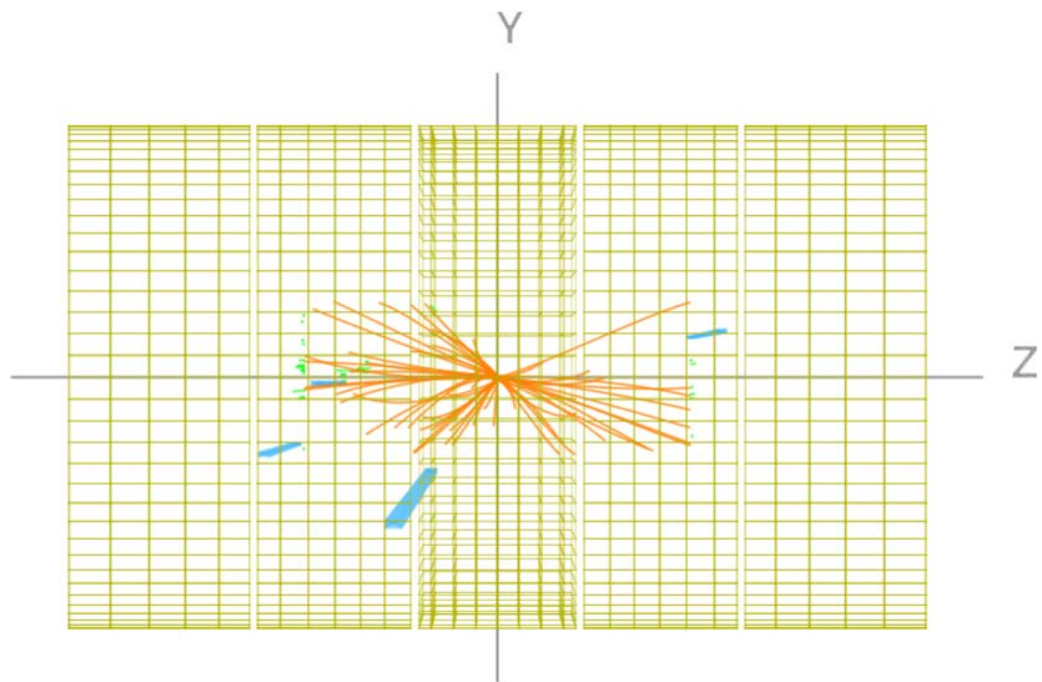


z-y view: measure  $\theta$

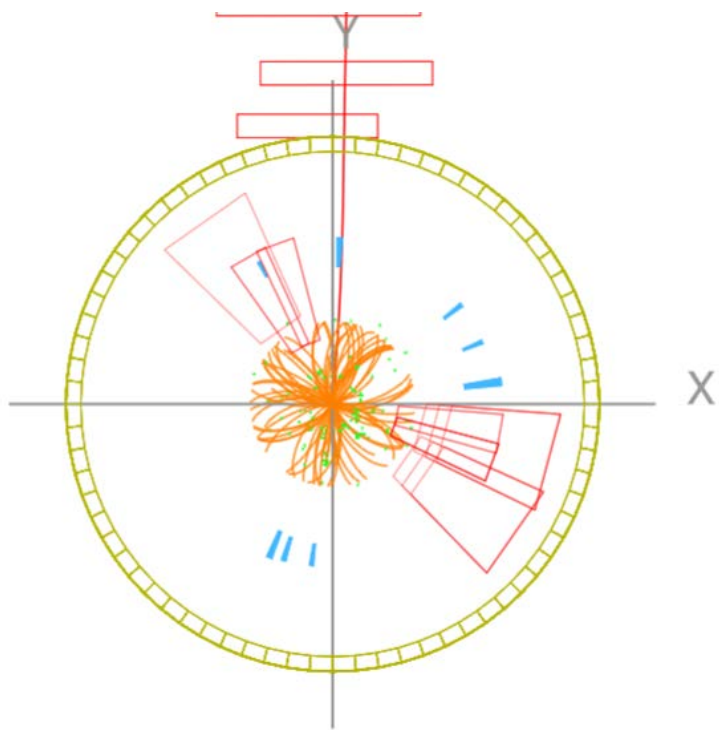




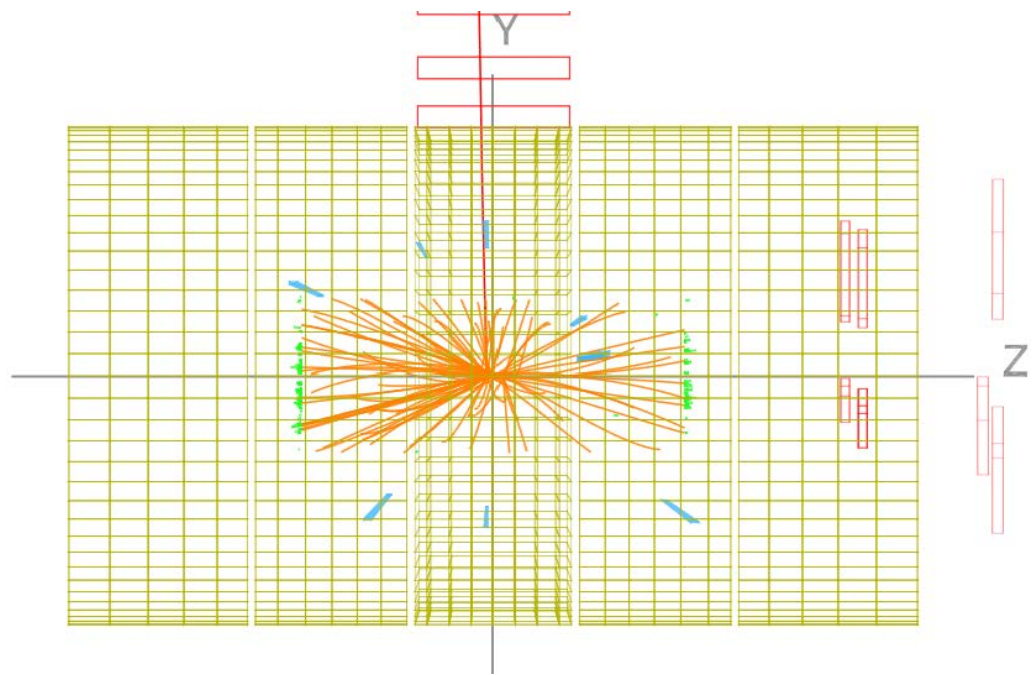
x-y view: measure  $\phi$



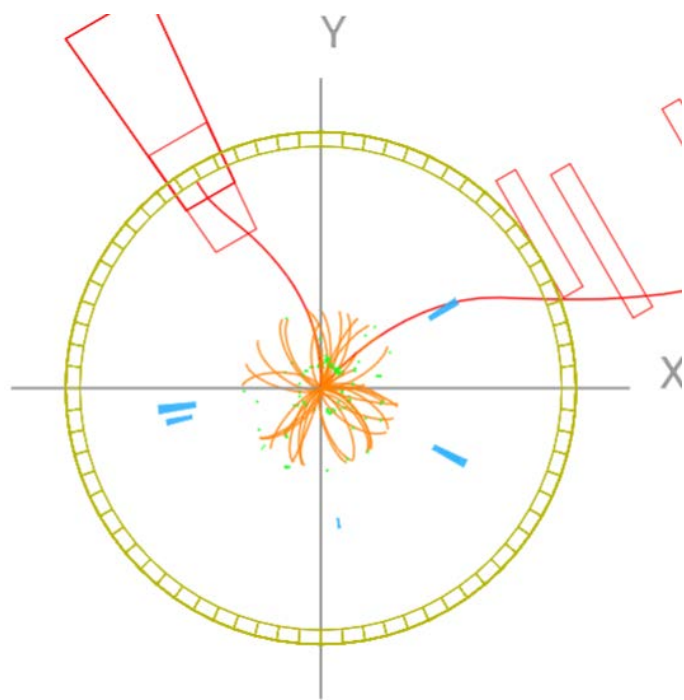
z-y view: measure  $\theta$



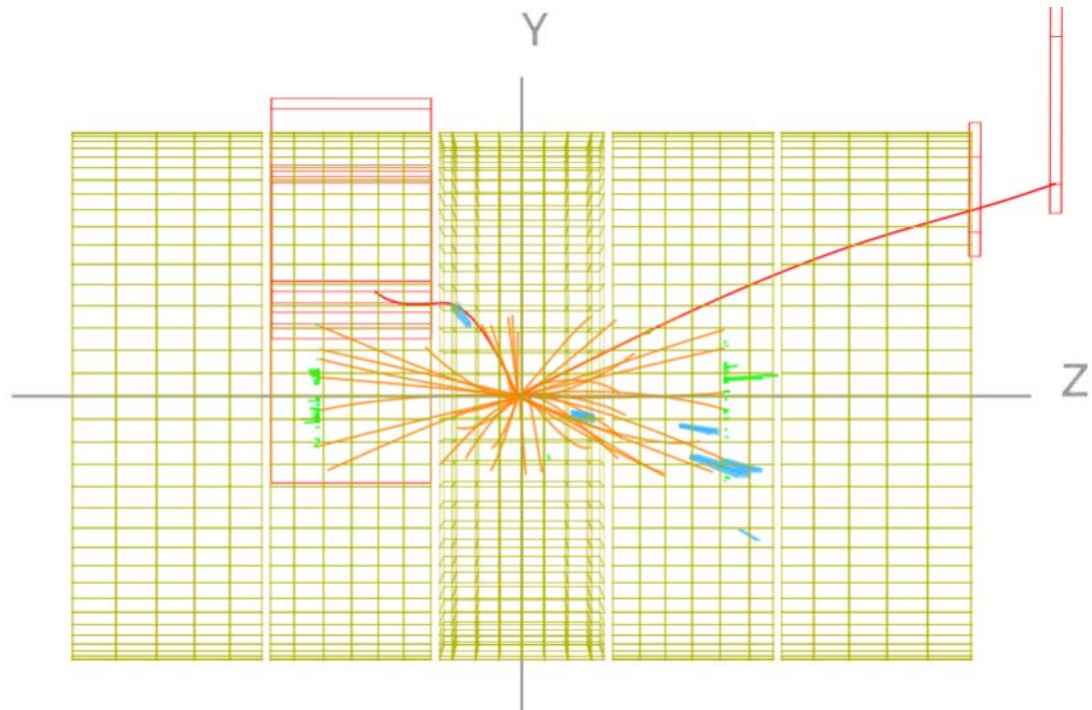
x-y view: measure  $\phi$



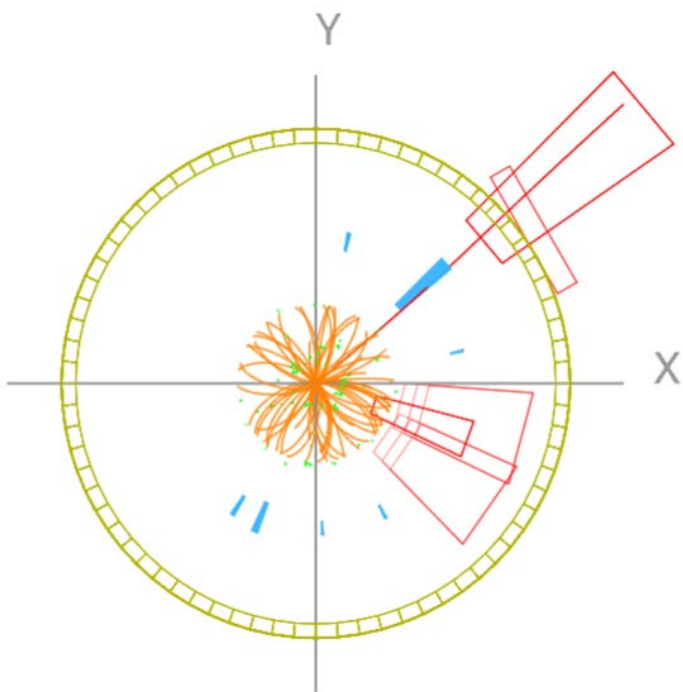
z-y view: measure  $\theta$



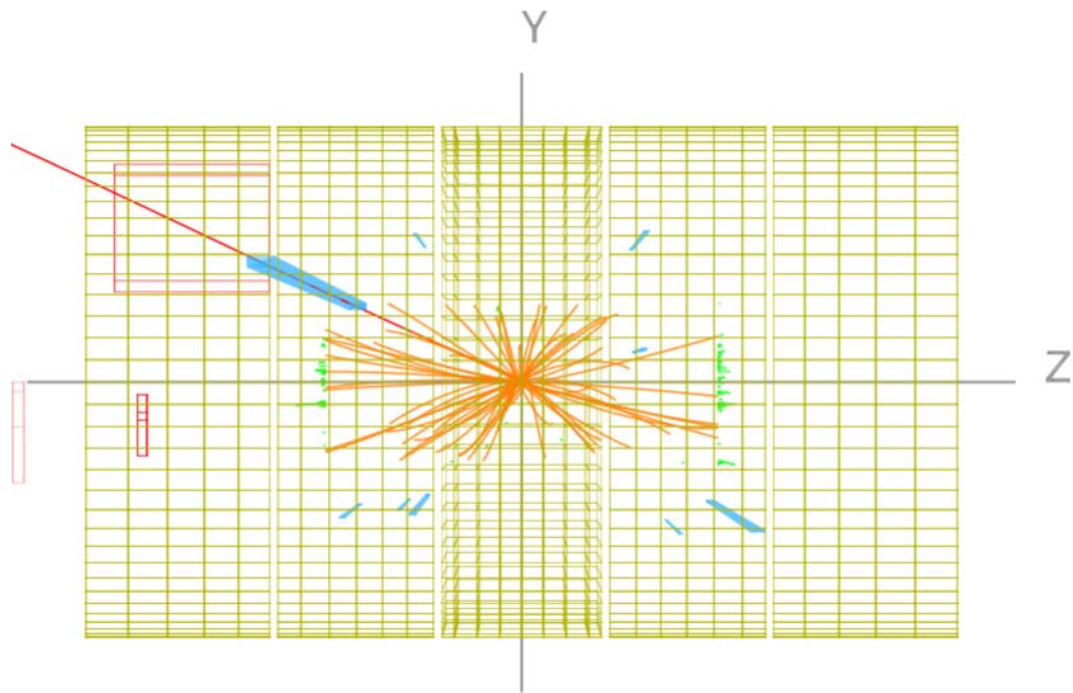
x-y view: measure  $\phi$



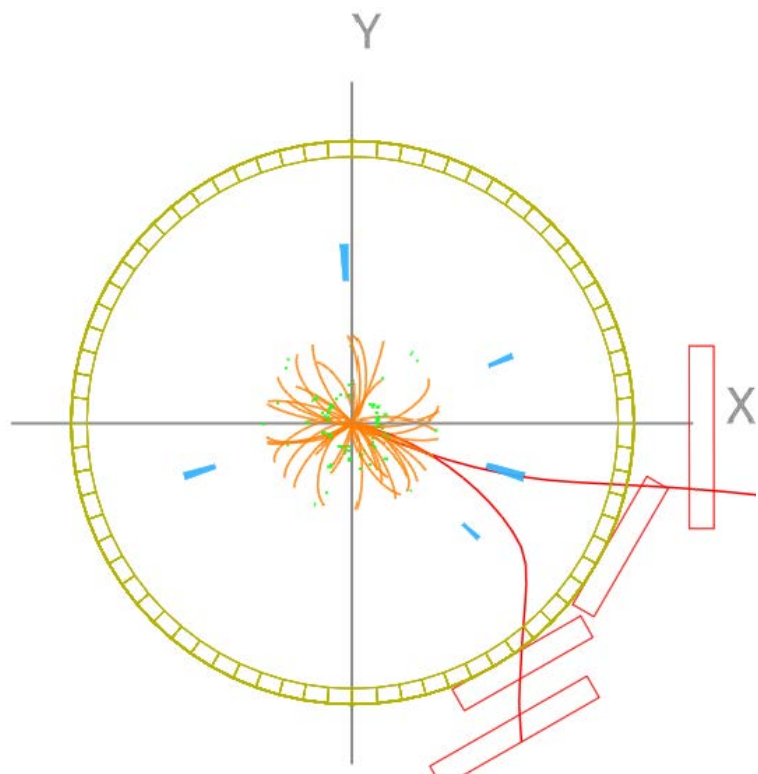
z-y view: measure  $\theta$



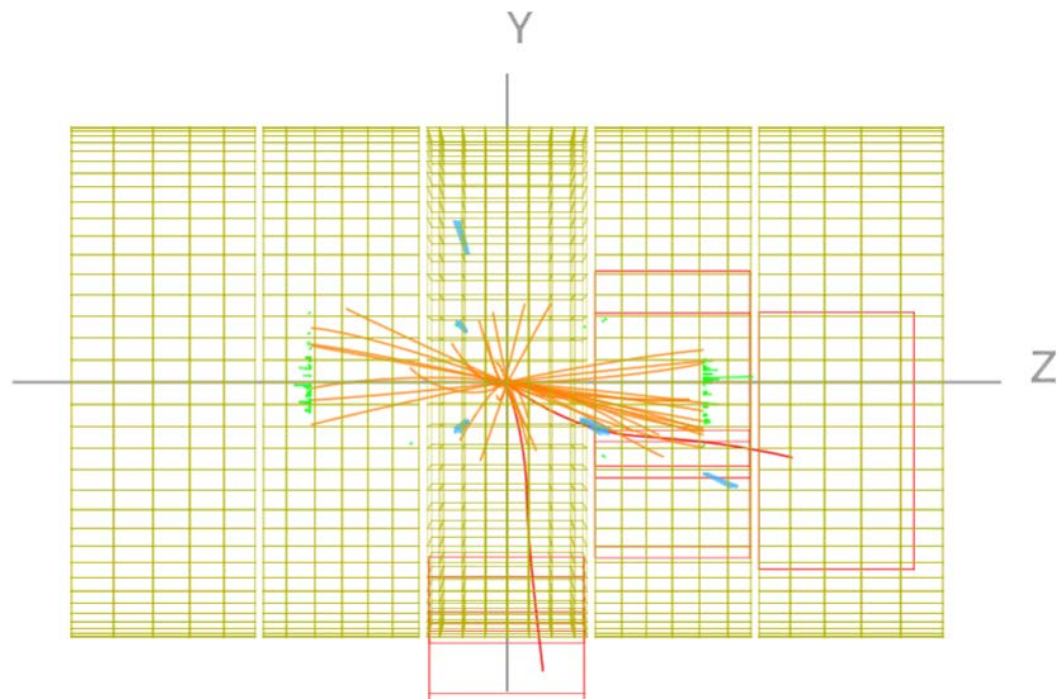
x-y view: measure  $\phi$



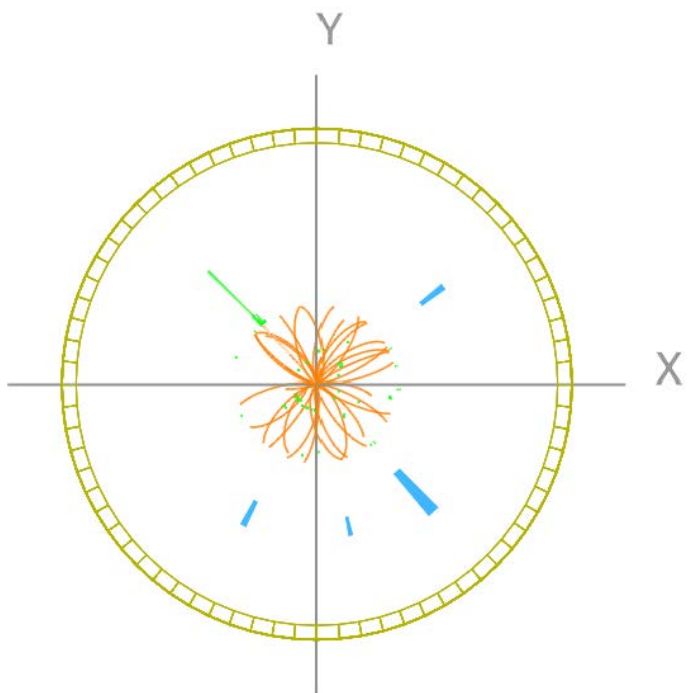
z-y view: measure  $\theta$



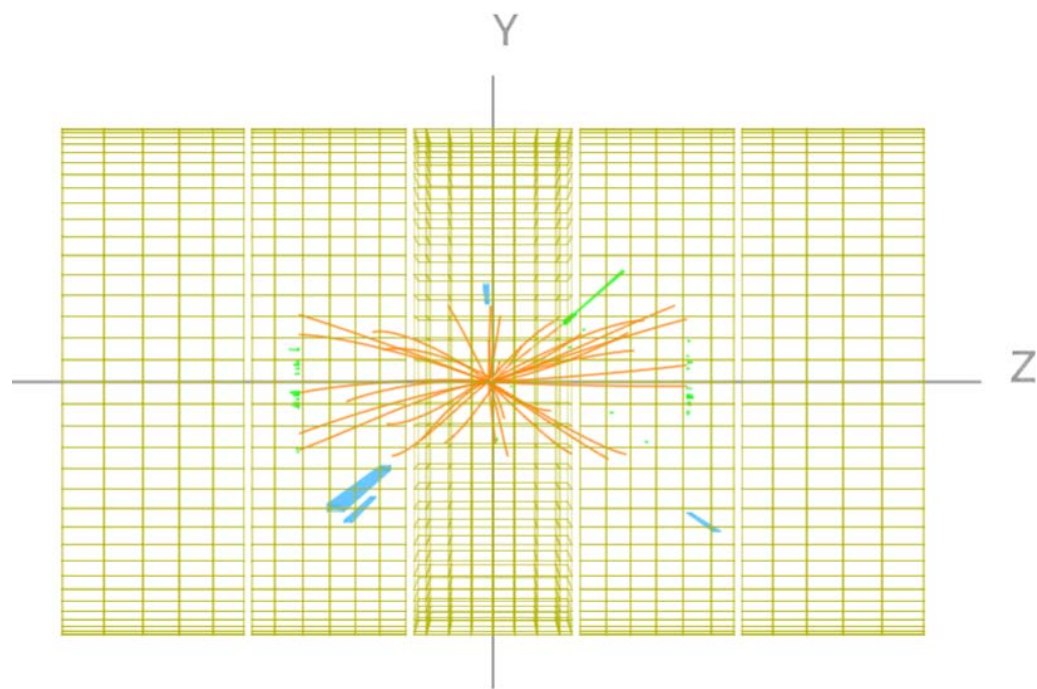
x-y view: measure  $\phi$



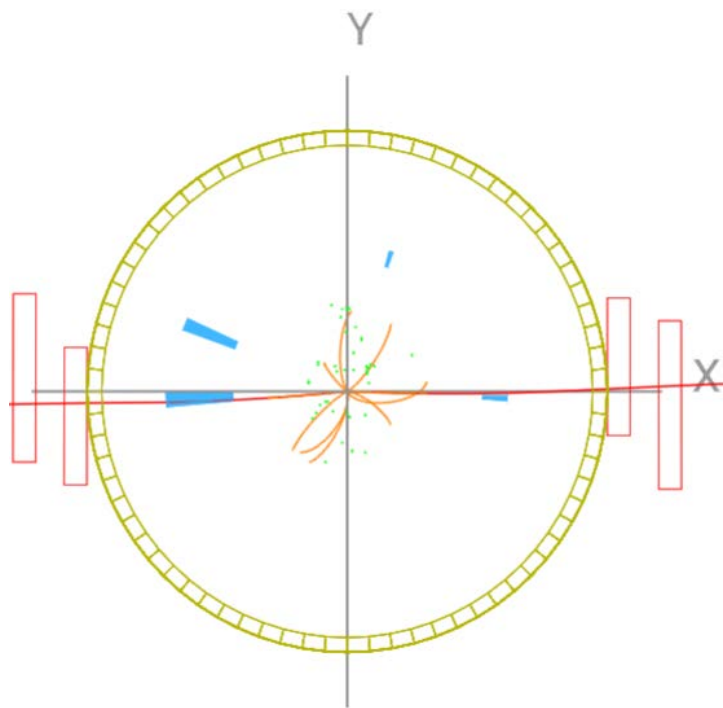
z-y view: measure  $\theta$



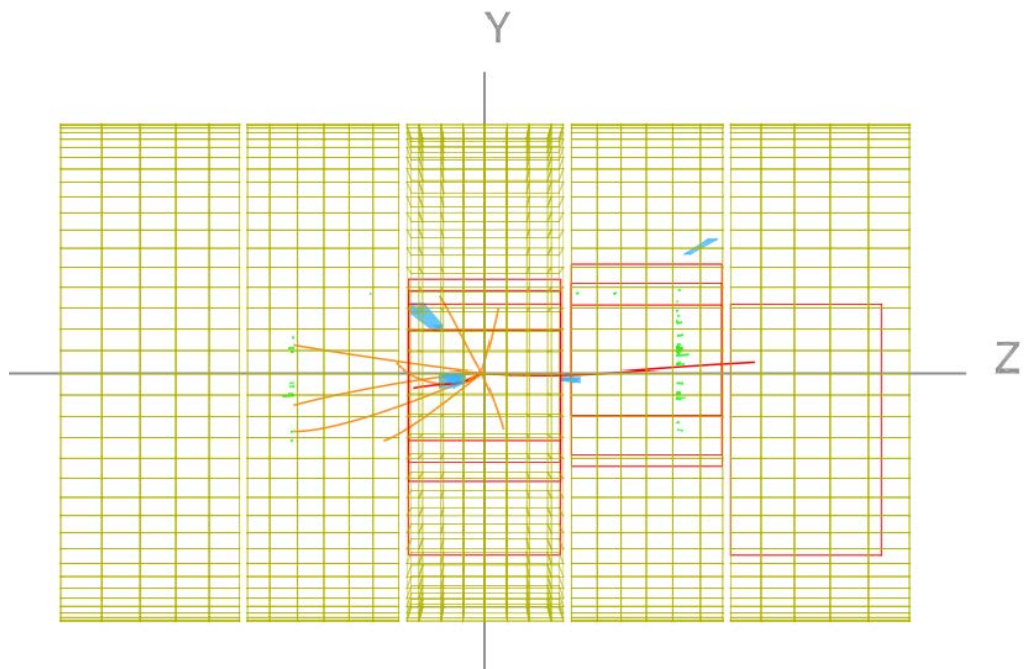
x-y view: measure  $\phi$



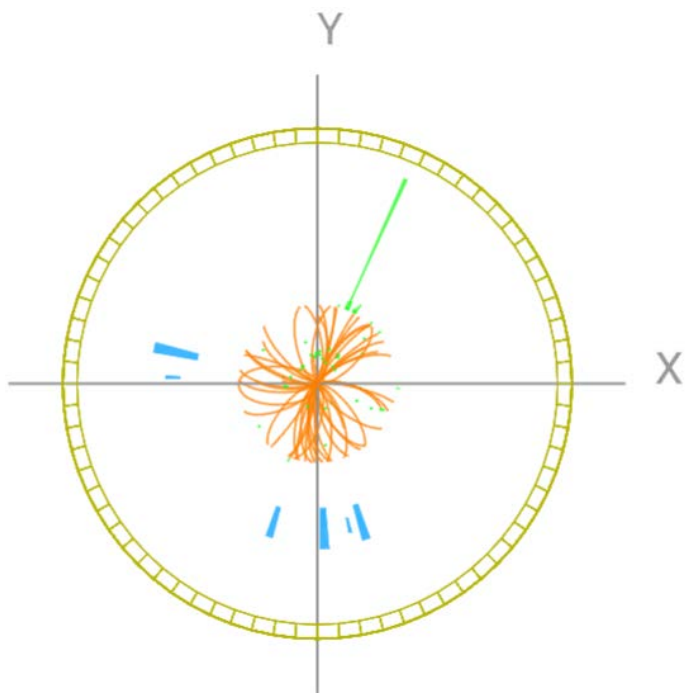
z-y view: measure  $\theta$



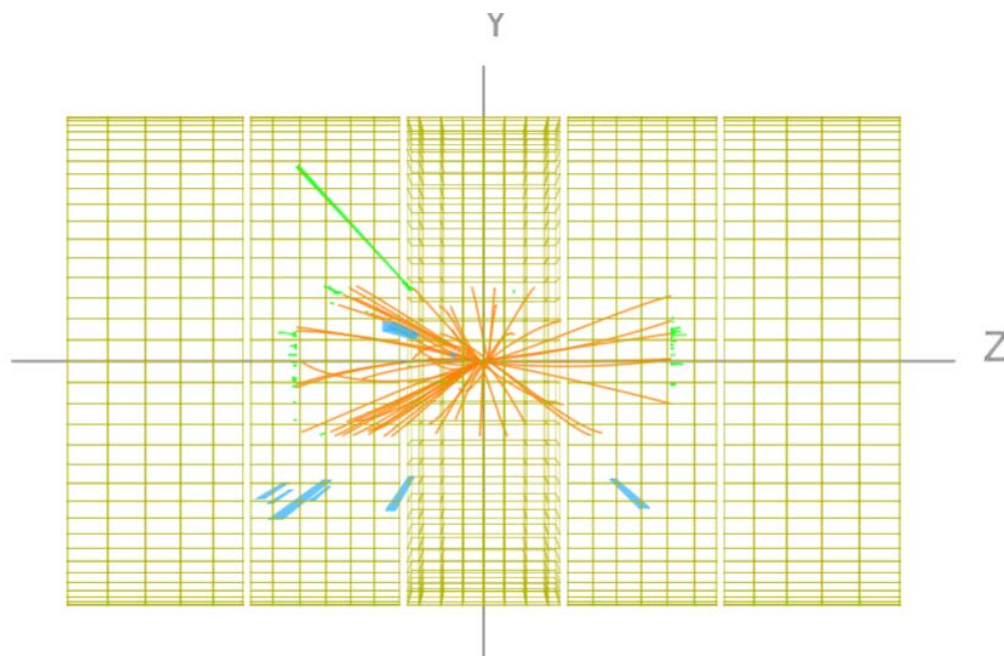
x-y view: measure  $\phi$



z-y view: measure  $\theta$

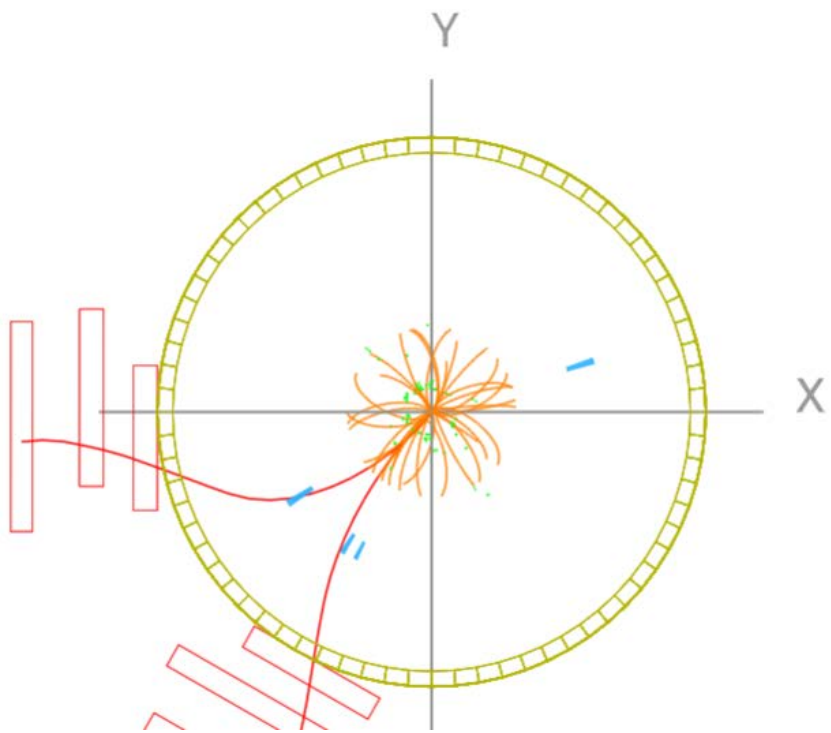


x-y view: measure  $\phi$

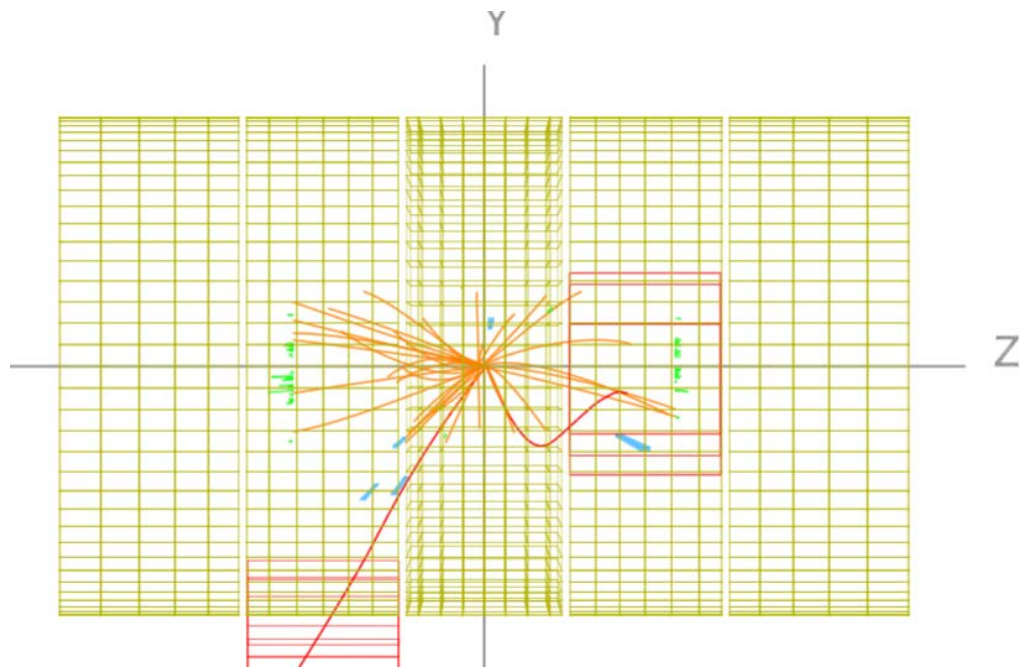


z-y view: measure  $\theta$

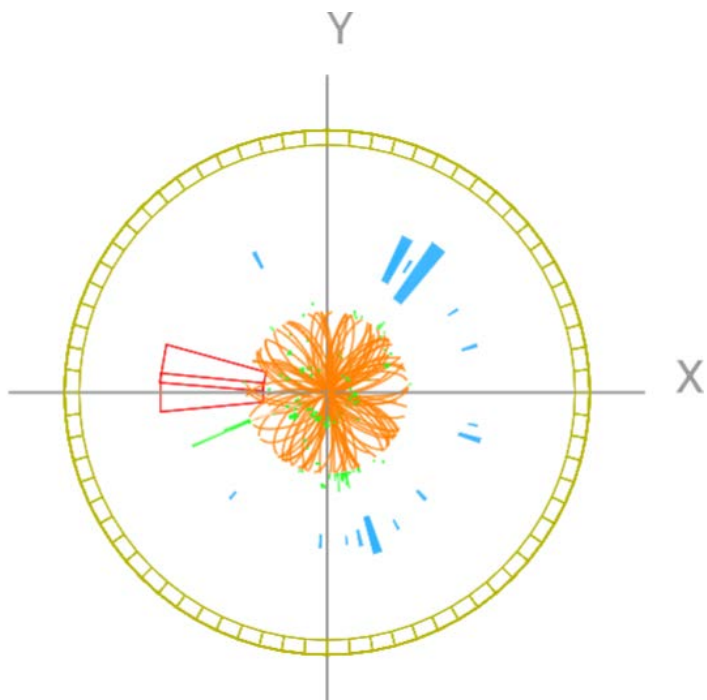




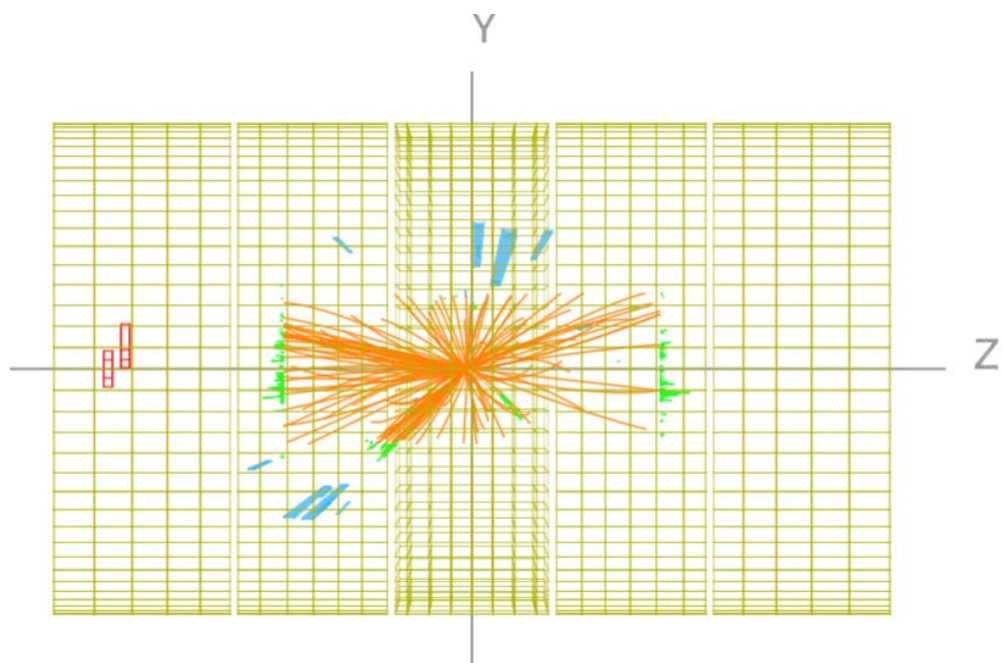
x-y view: measure  $\phi$



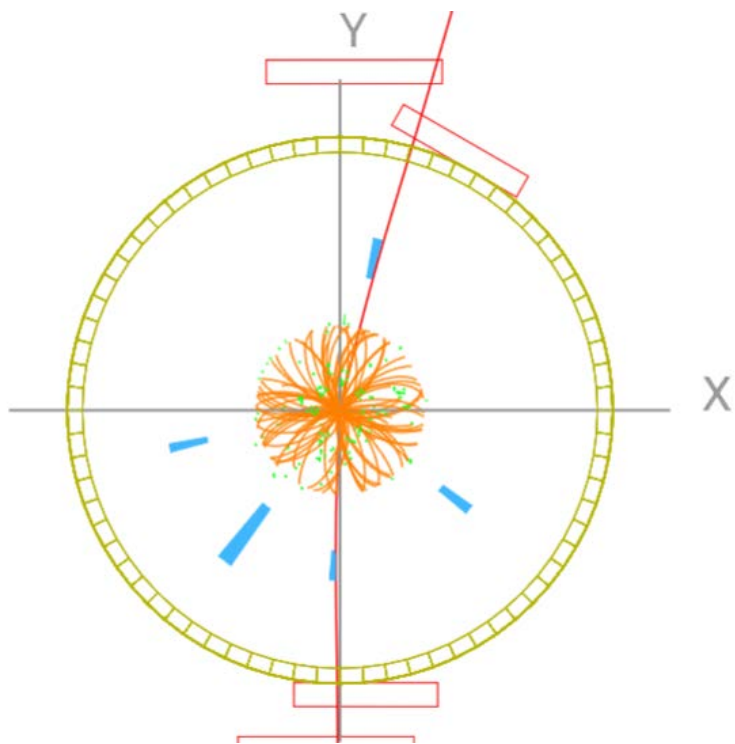
z-y view: measure  $\theta$



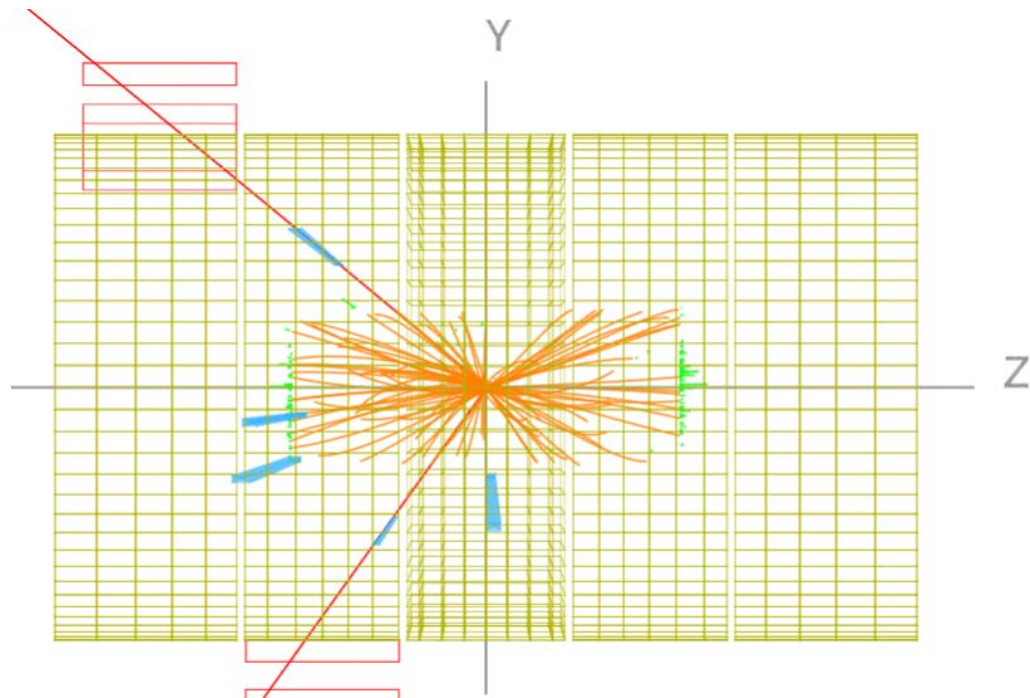
x-y view: measure  $\phi$



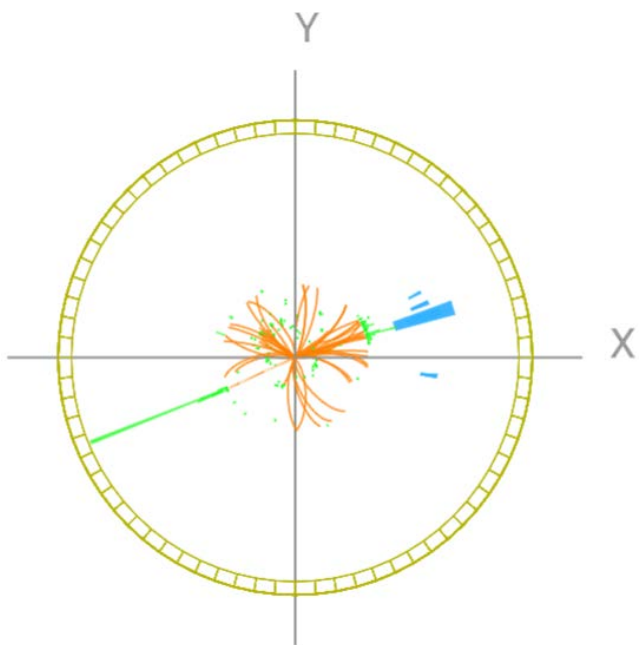
z-y view: measure  $\theta$



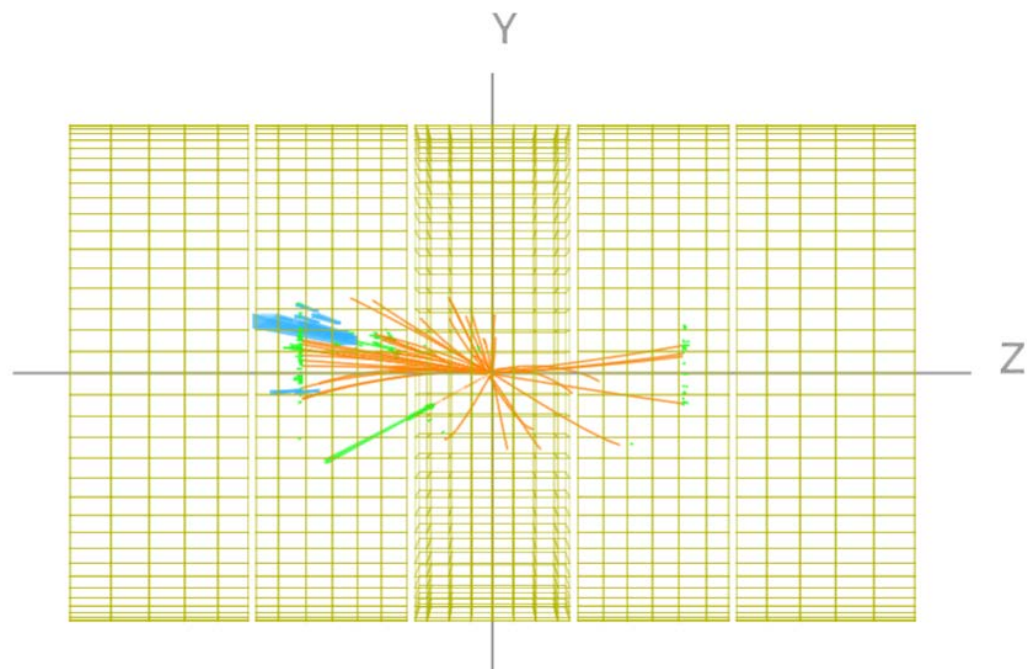
x-y view: measure  $\phi$



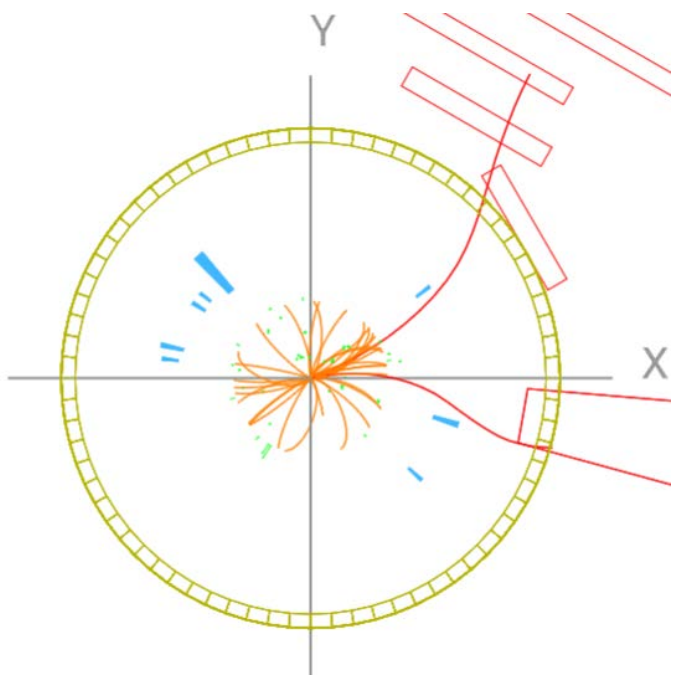
z-y view: measure  $\theta$



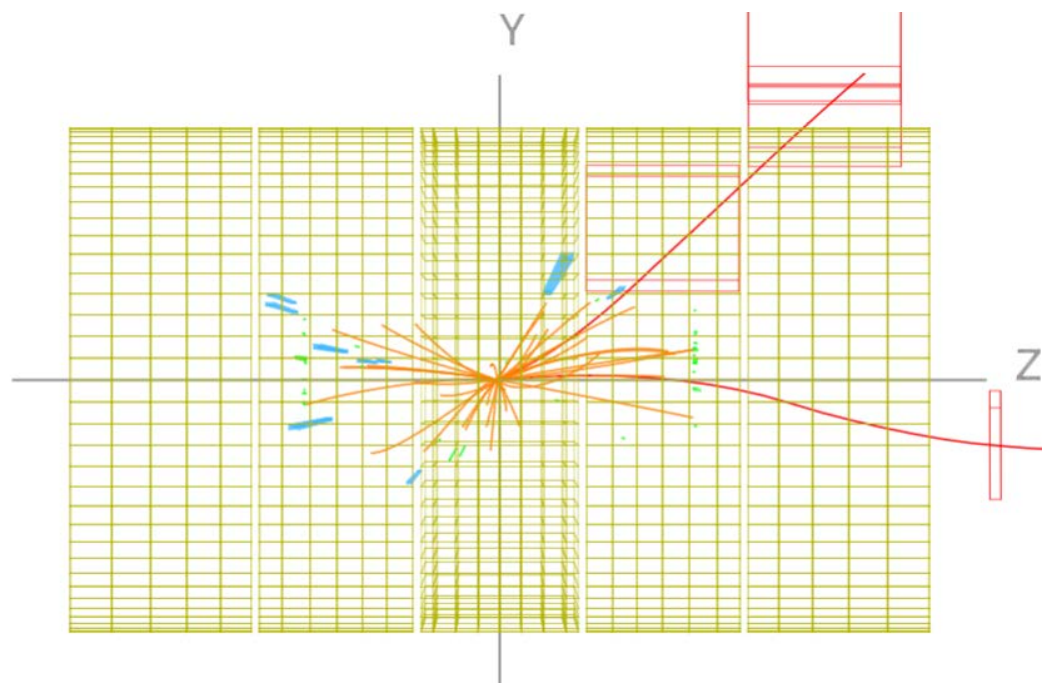
x-y view: measure  $\phi$



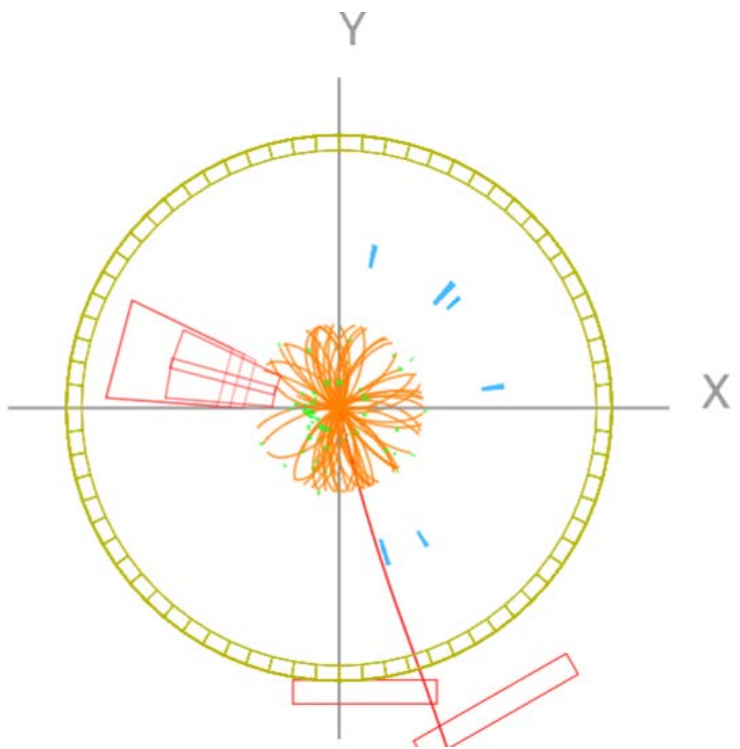
z-y view: measure  $\theta$



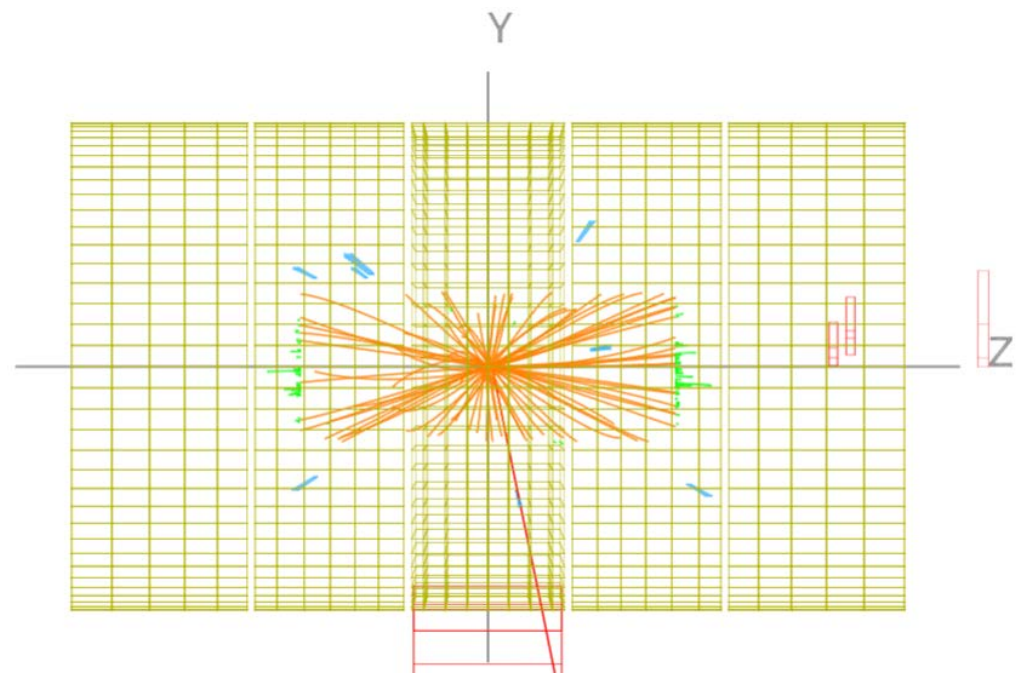
x-y view: measure  $\phi$



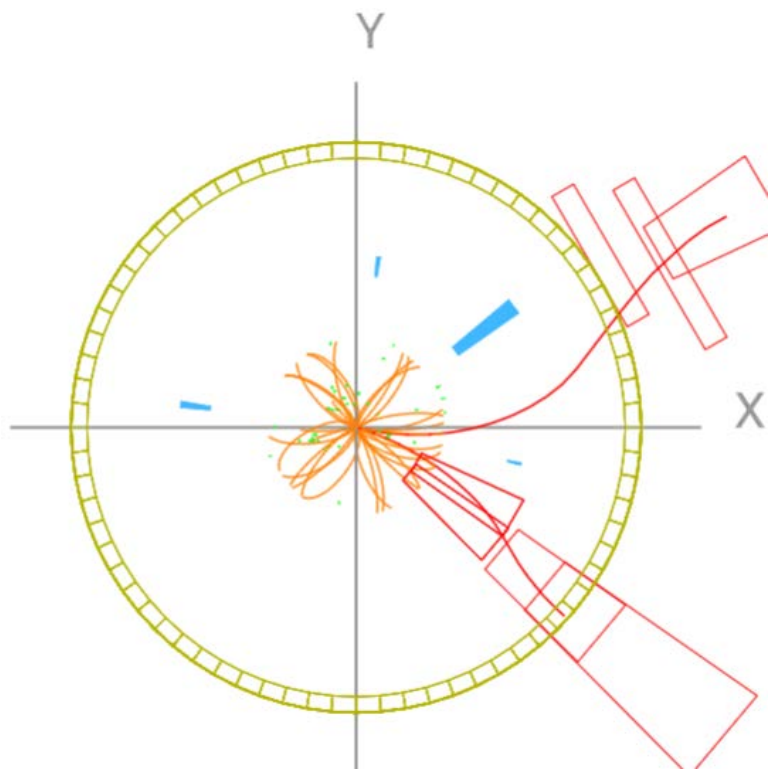
z-y view: measure  $\theta$



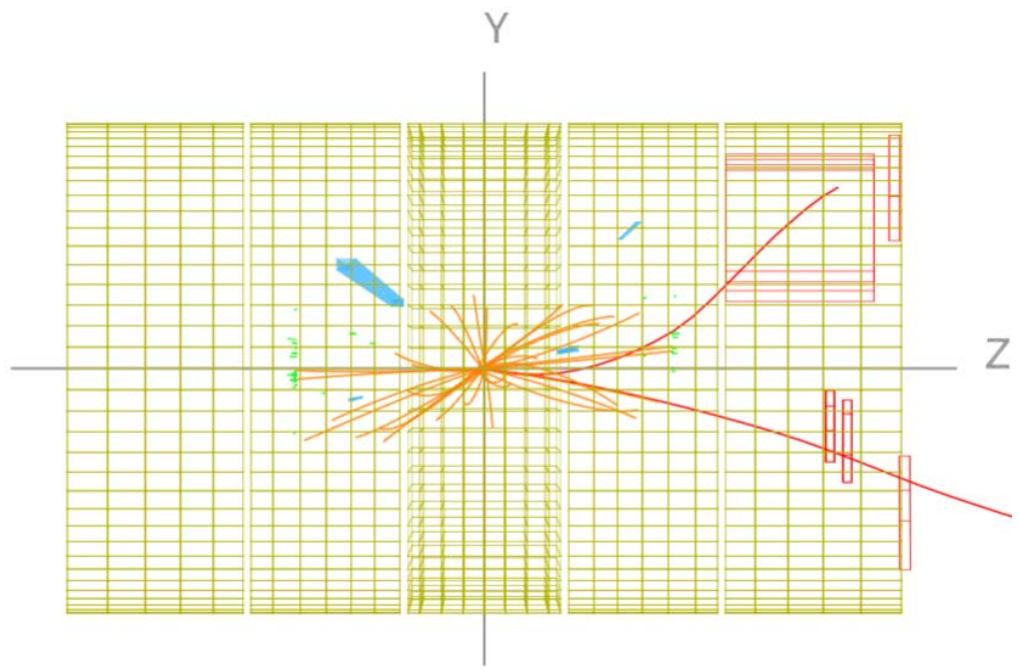
x-y view: measure  $\phi$



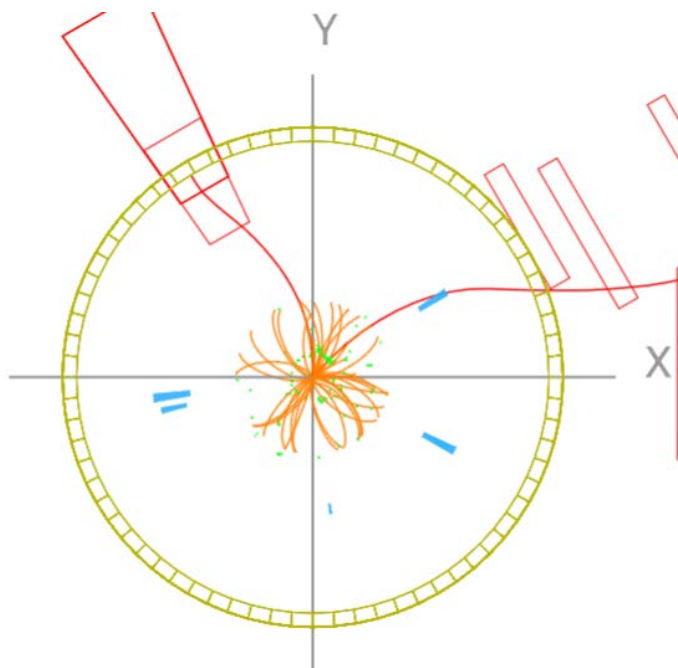
z-y view: measure  $\theta$



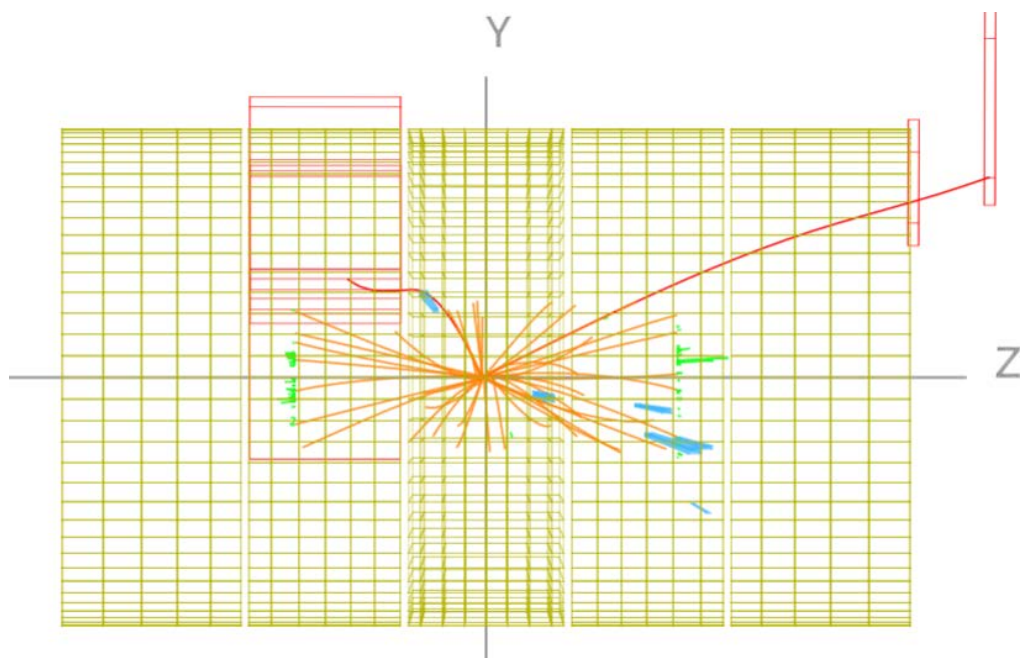
x-y view: measure  $\phi$



z-y view: measure  $\theta$

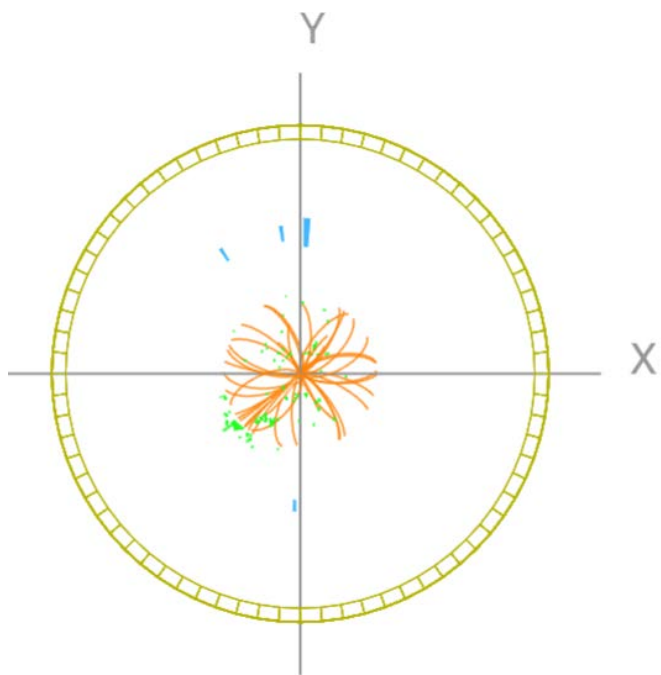


x-y view: measure  $\phi$

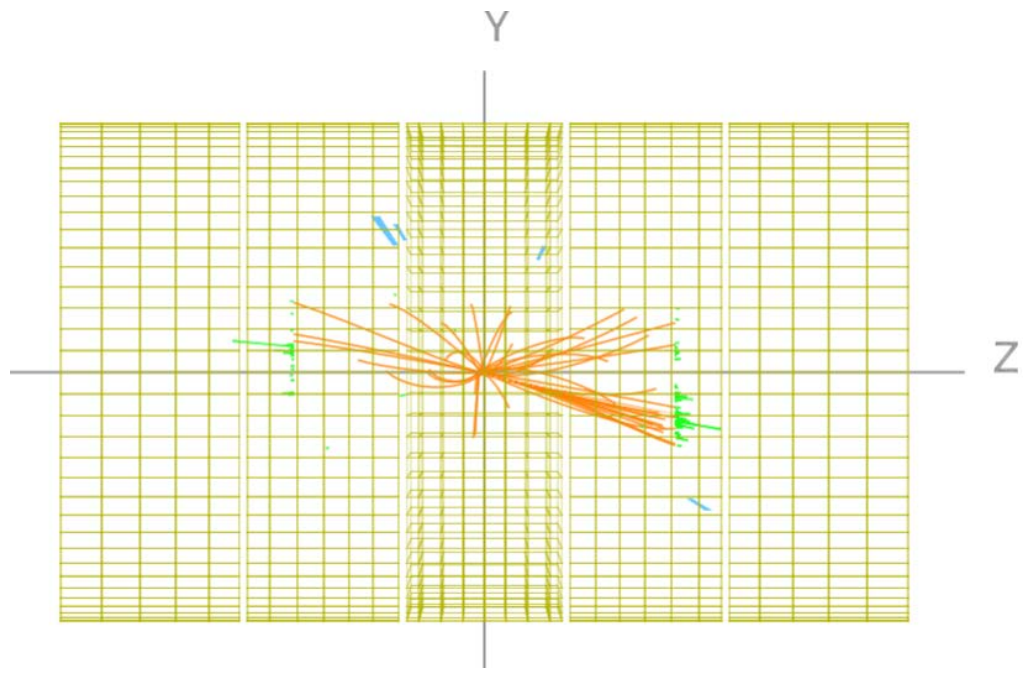


z-y view: measure  $\theta$

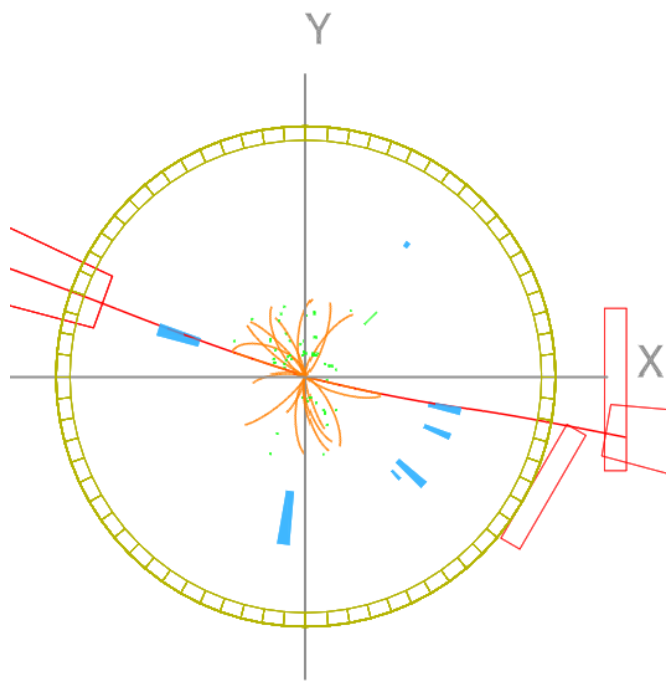




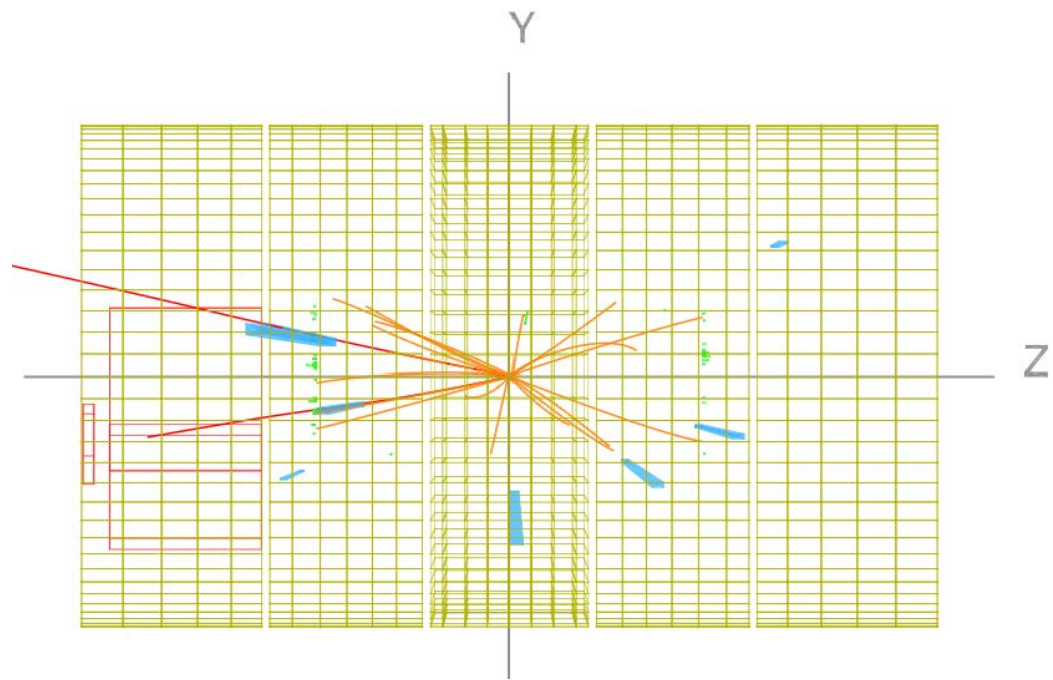
x-y view: measure  $\phi$



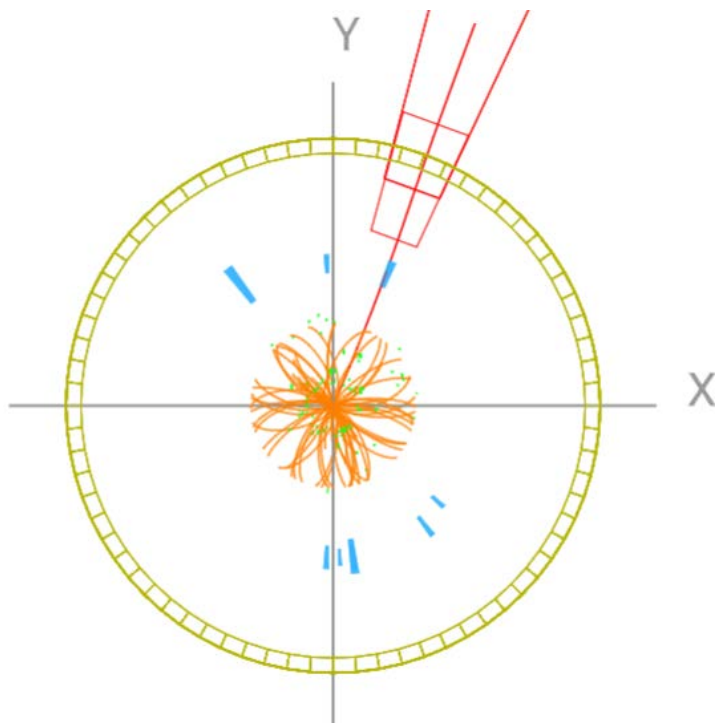
z-y view: measure  $\theta$



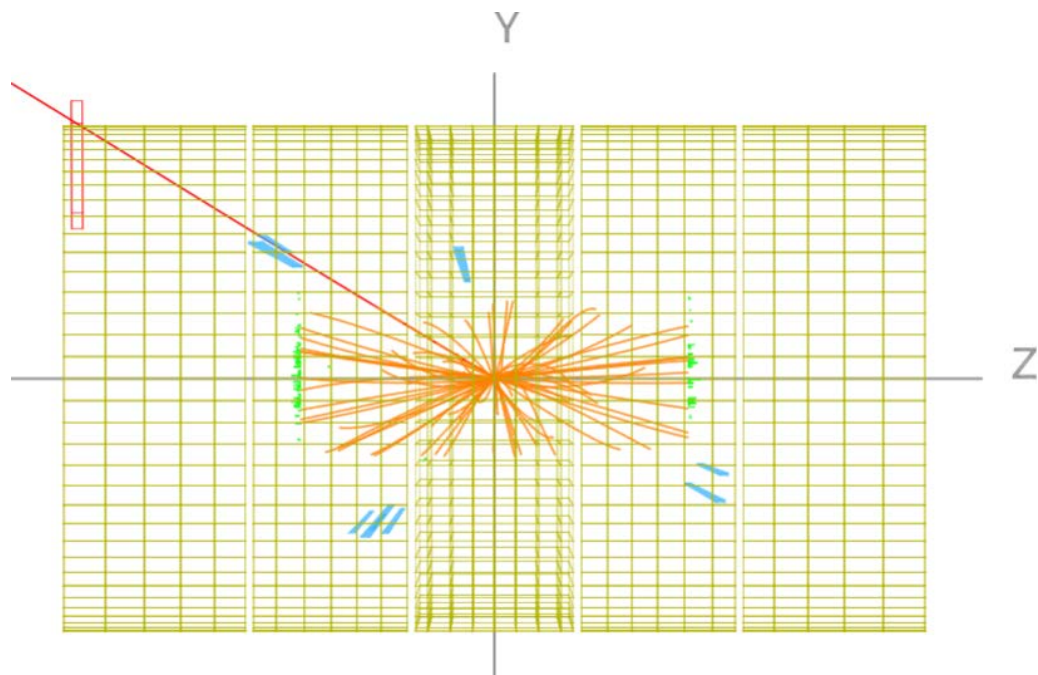
x-y view: measure  $\phi$



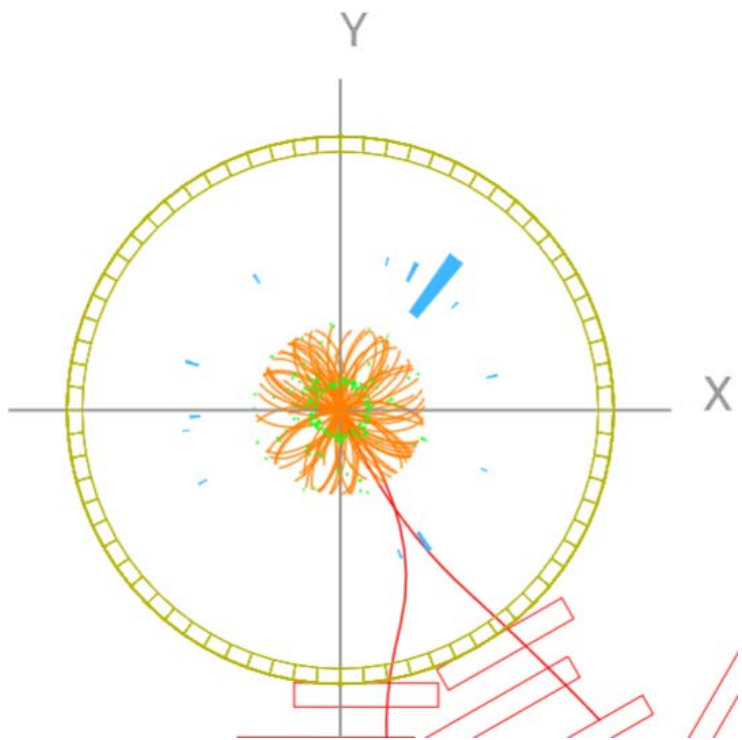
z-y view: measure  $\theta$



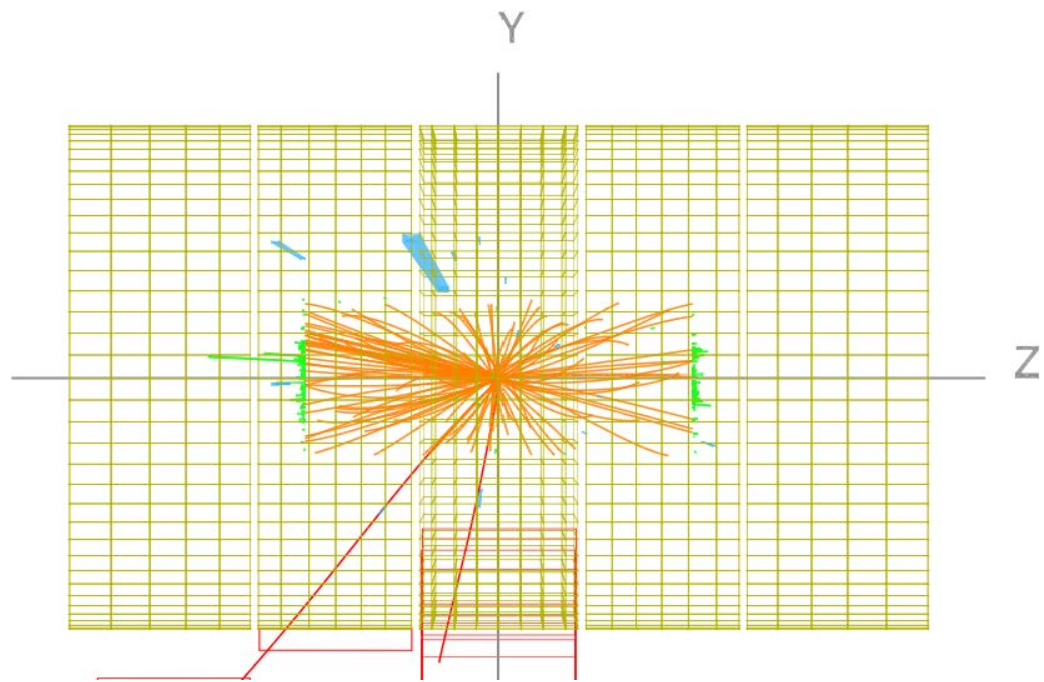
x-y view: measure  $\phi$



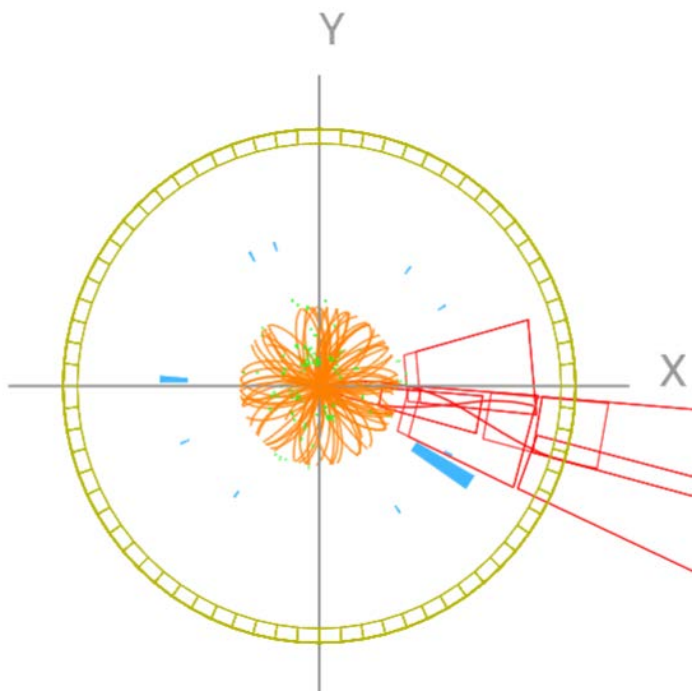
z-y view: measure  $\theta$



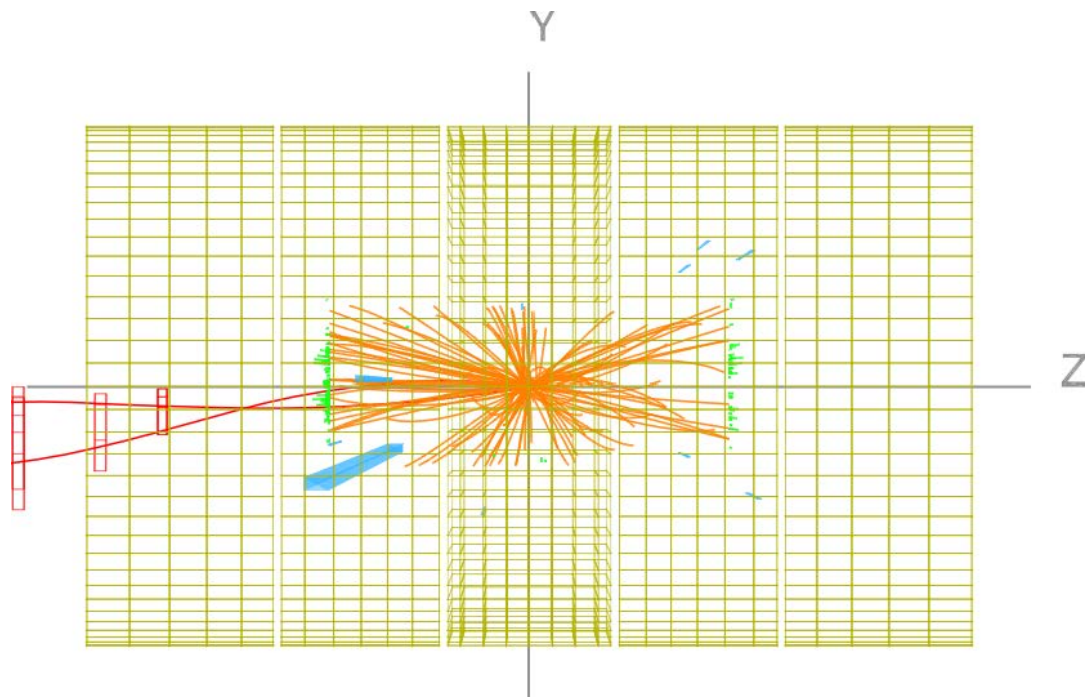
x-y view: measure  $\phi$



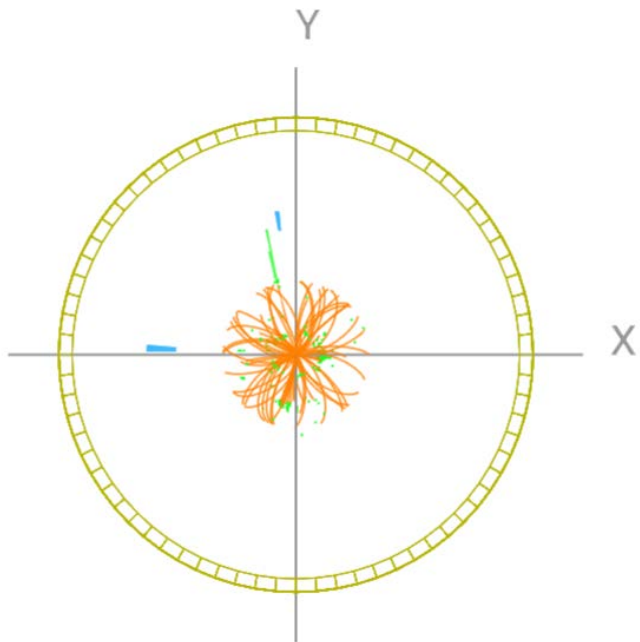
z-y view: measure  $\theta$



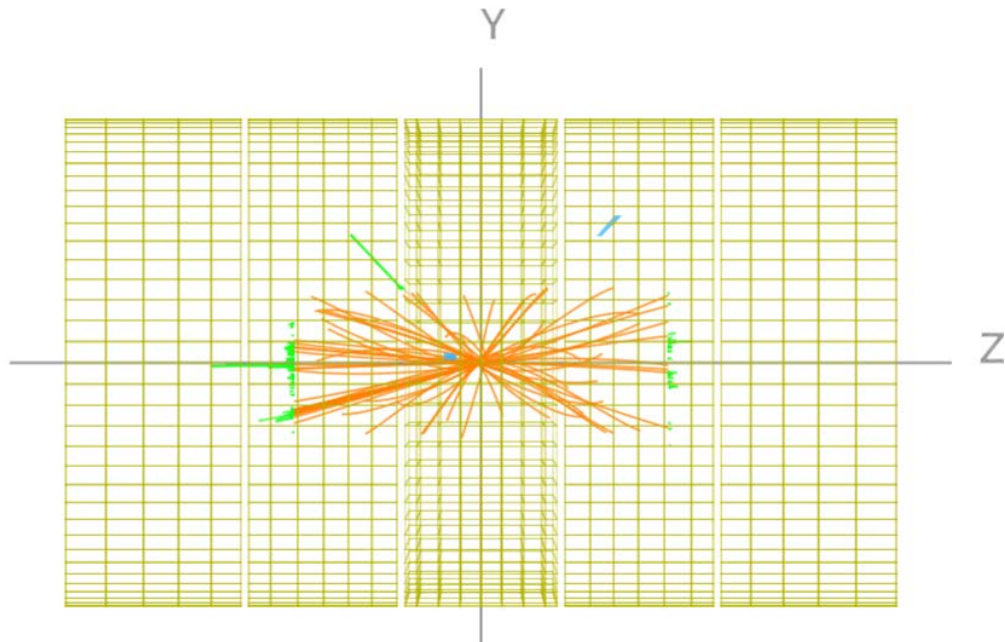
x-y view: measure  $\phi$



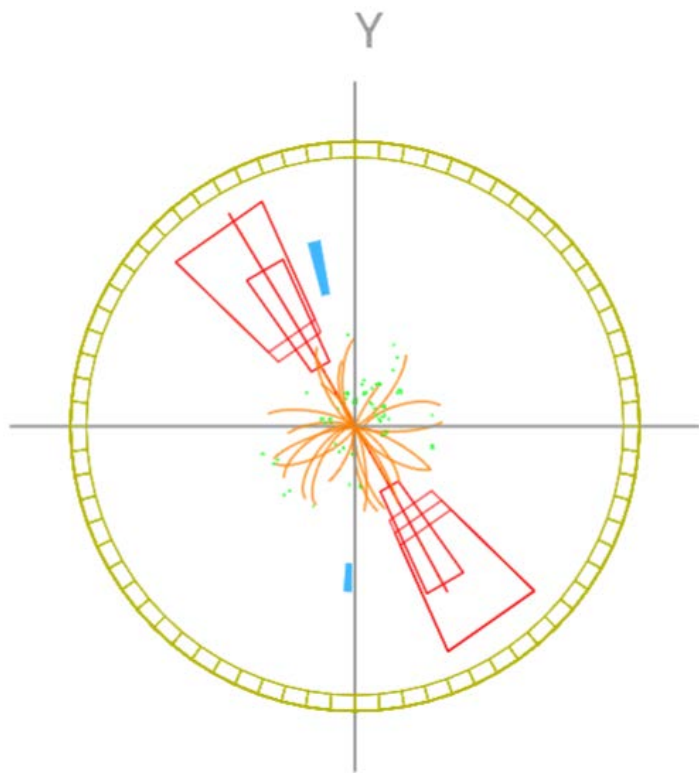
z-y view: measure  $\theta$



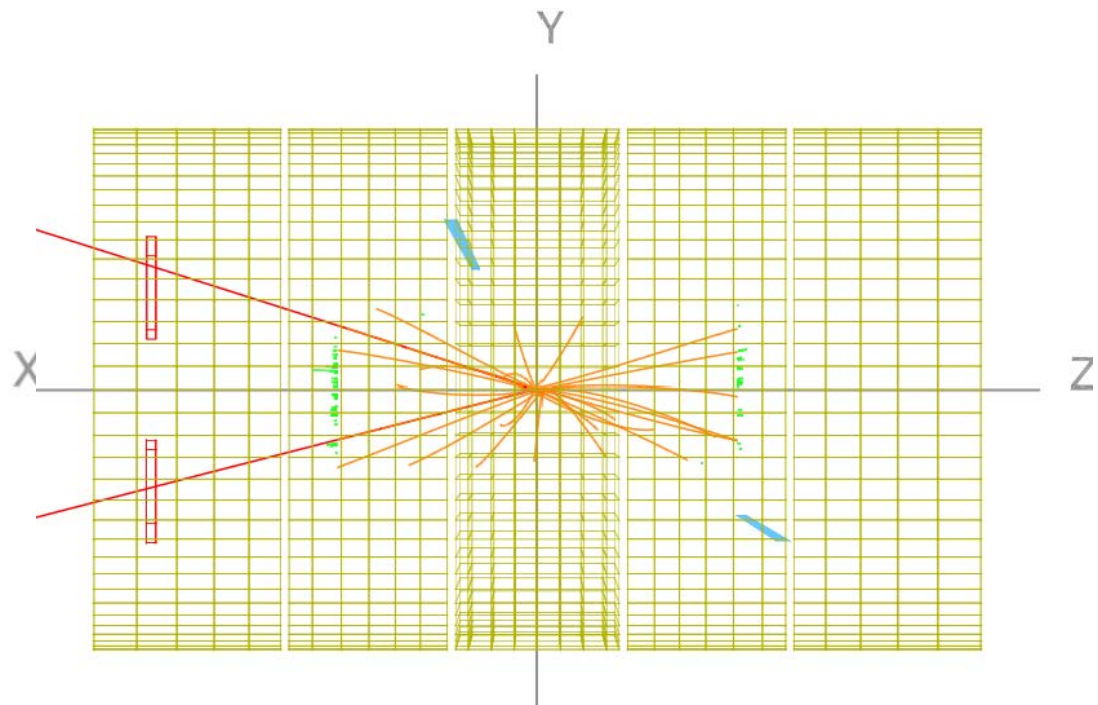
x-y view: measure  $\phi$



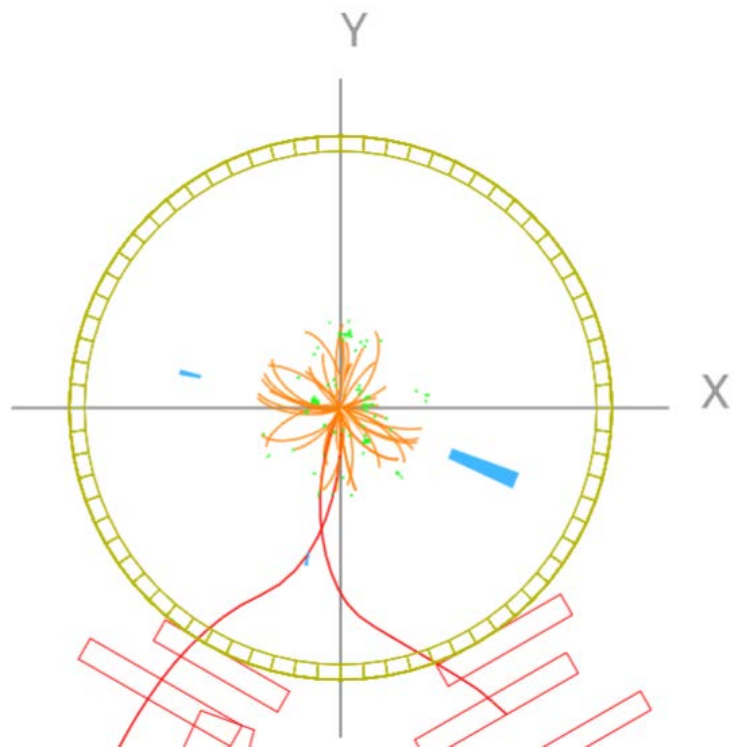
z-y view: measure  $\theta$



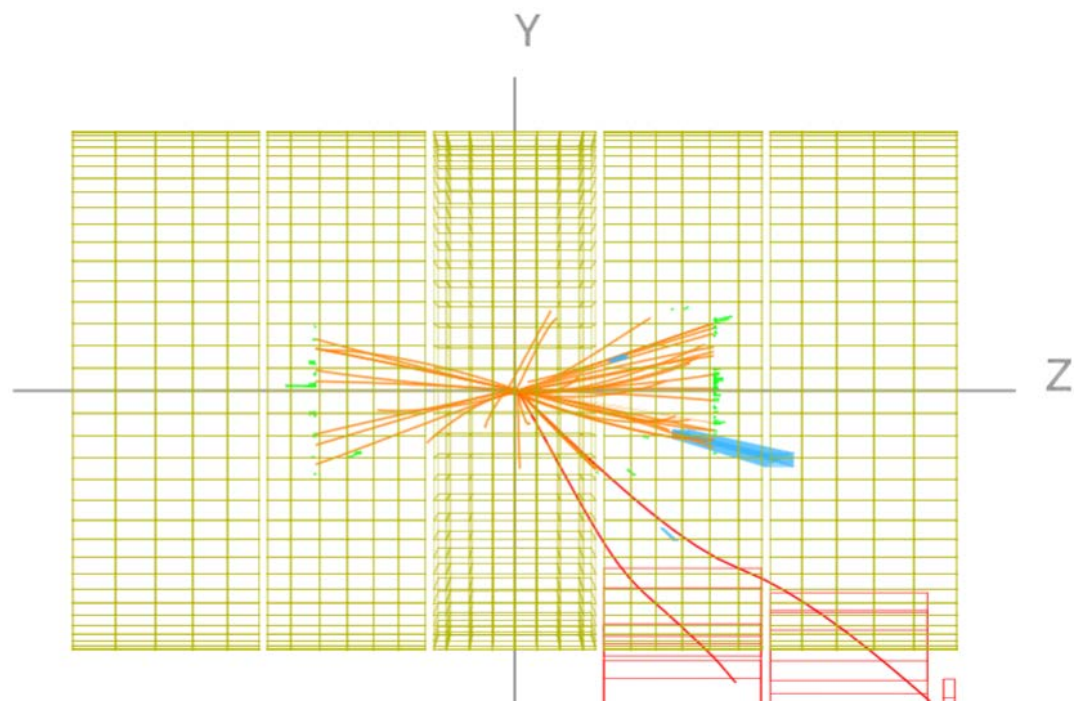
x-y view: measure  $\phi$



z-y view: measure  $\theta$

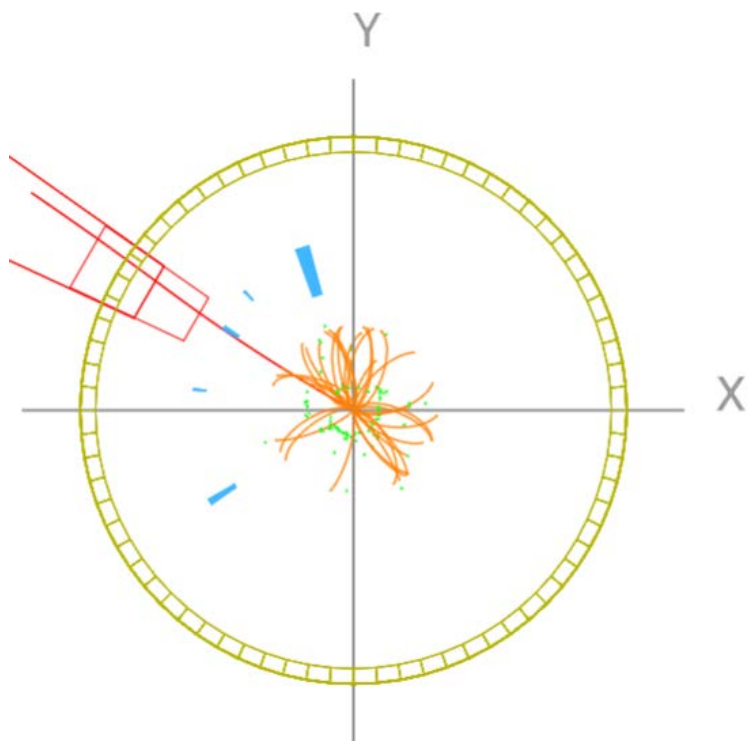


x-y view: measure  $\phi$

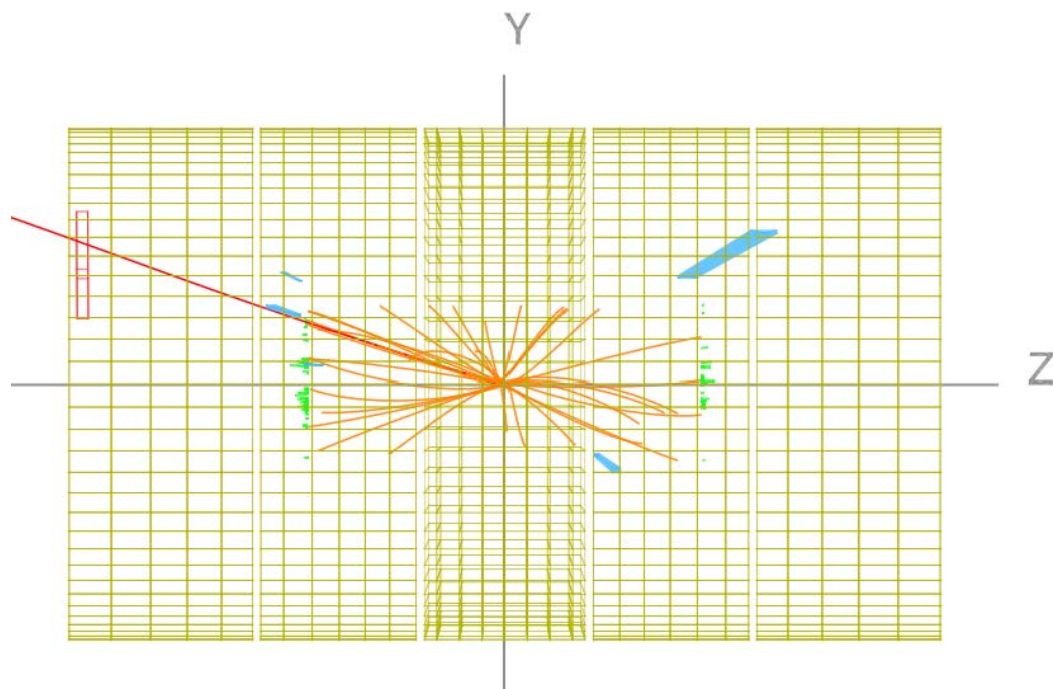


z-y view: measure  $\theta$

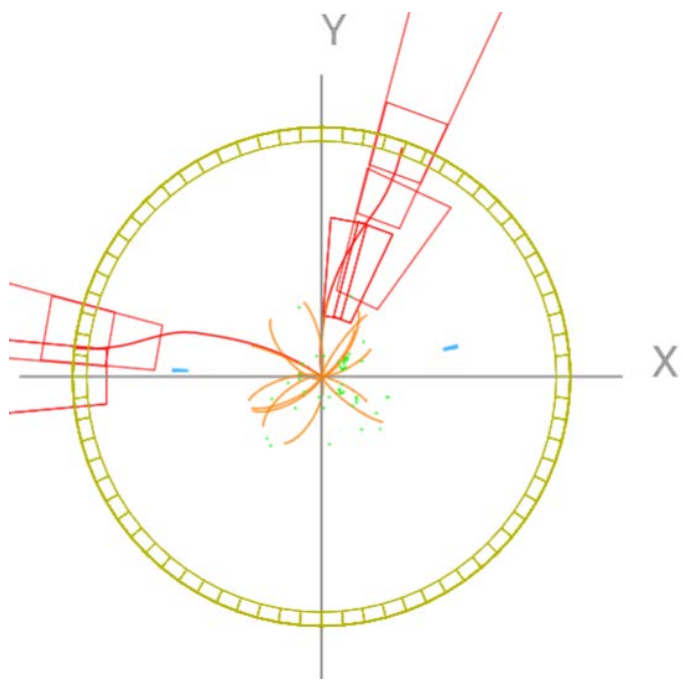




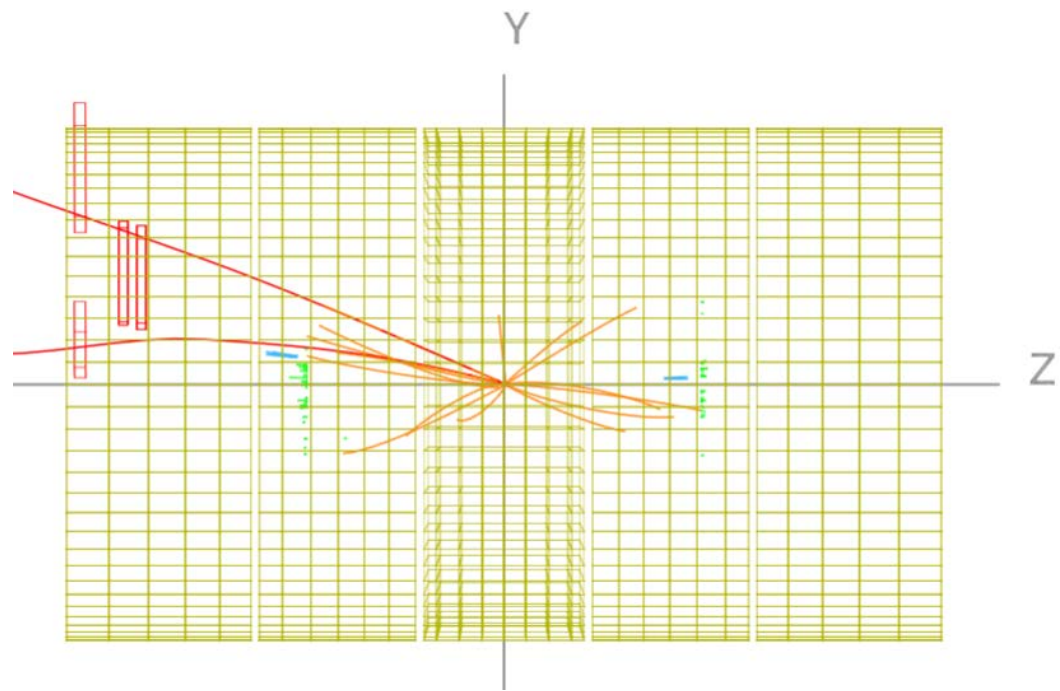
x-y view: measure  $\phi$



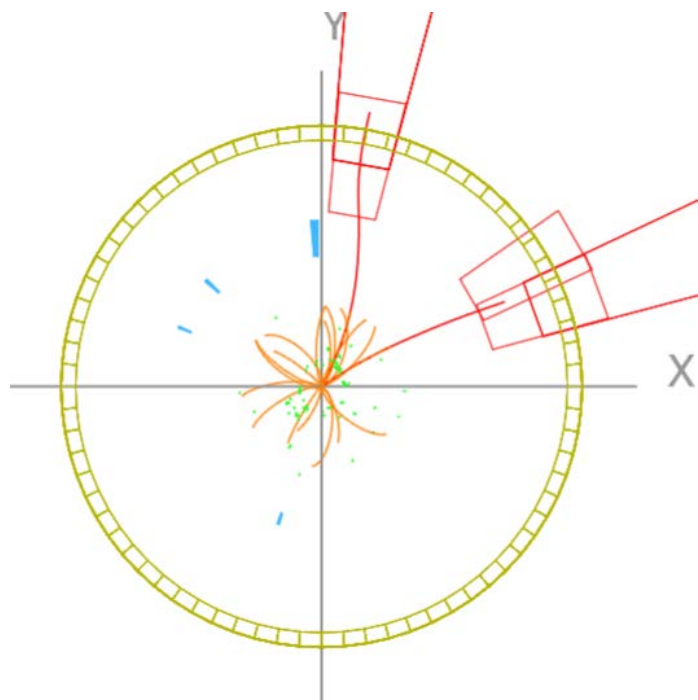
z-y view: measure  $\theta$



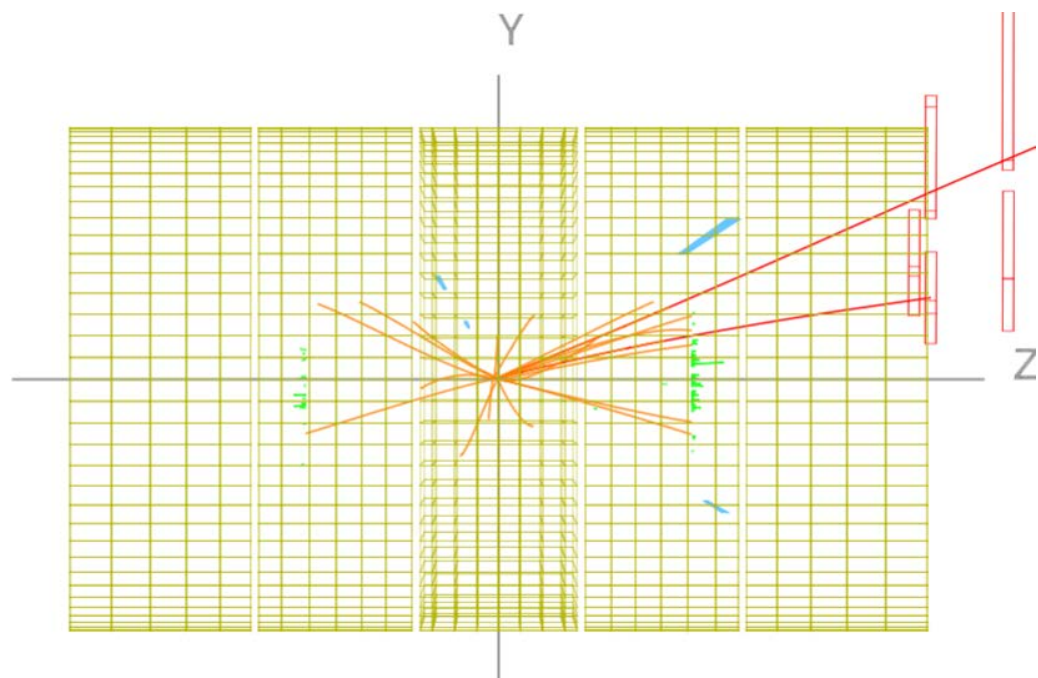
x-y view: measure  $\phi$



z-y view: measure  $\theta$



x-y view: measure  $\phi$



z-y view: measure  $\theta$