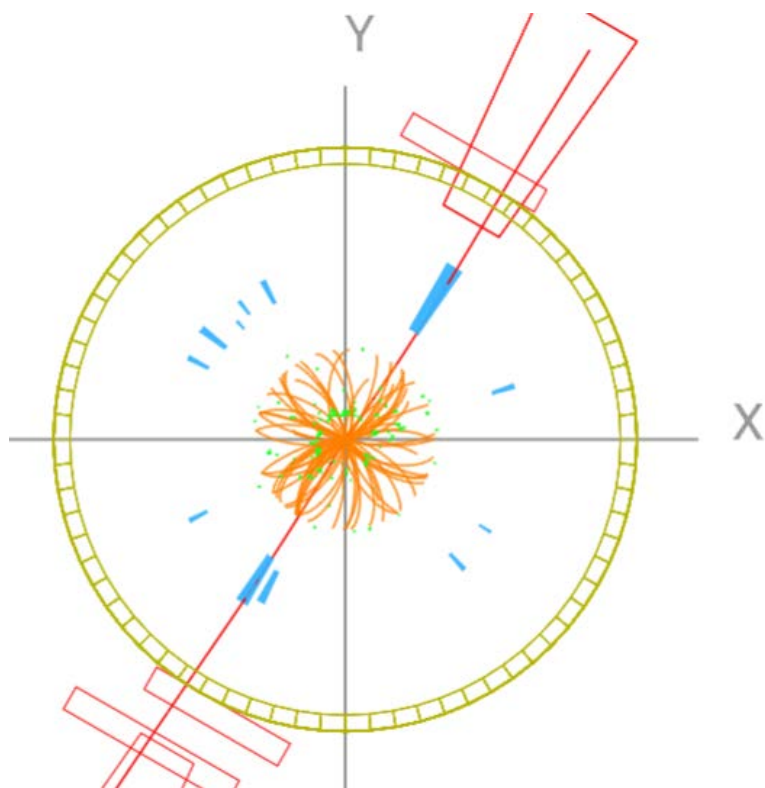
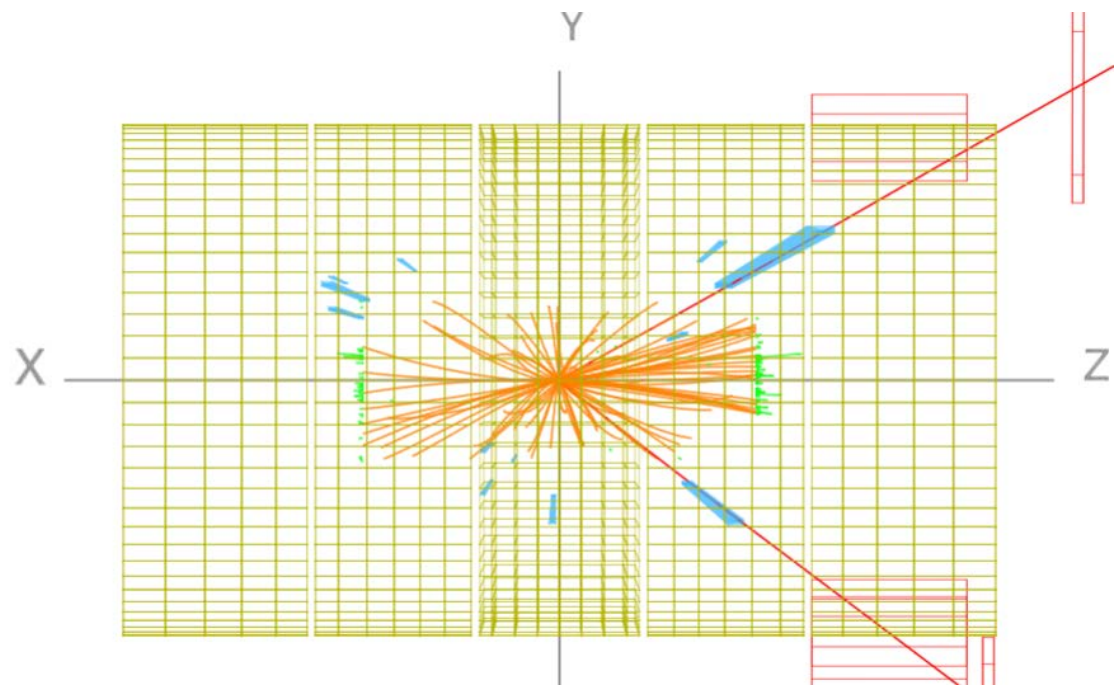


CMS-W2D2

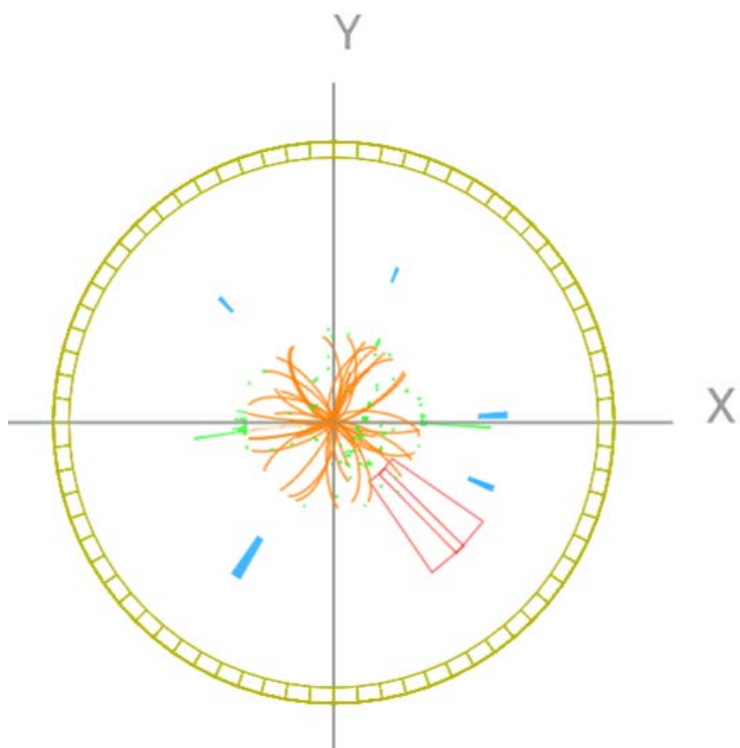
Measurement for
Masterclass-in-a-box
Data Set 4



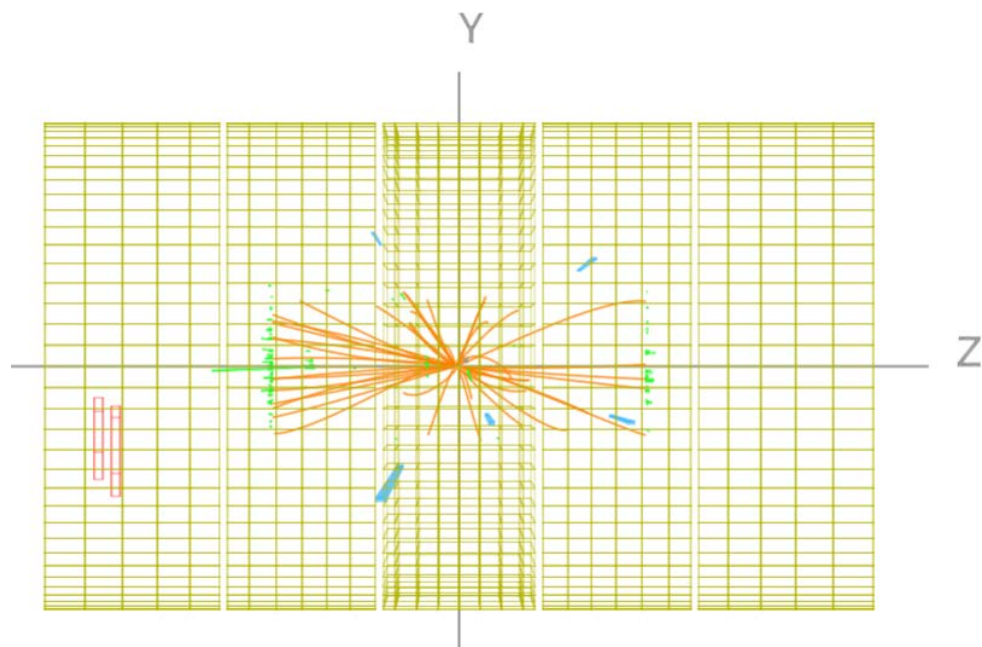
x-y view: measure ϕ



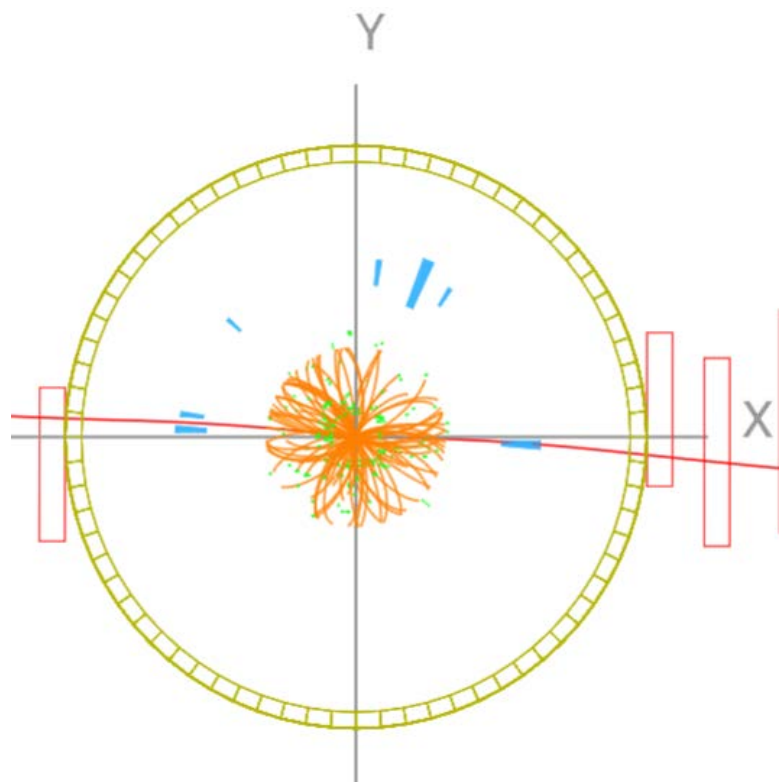
z-y view: measure θ



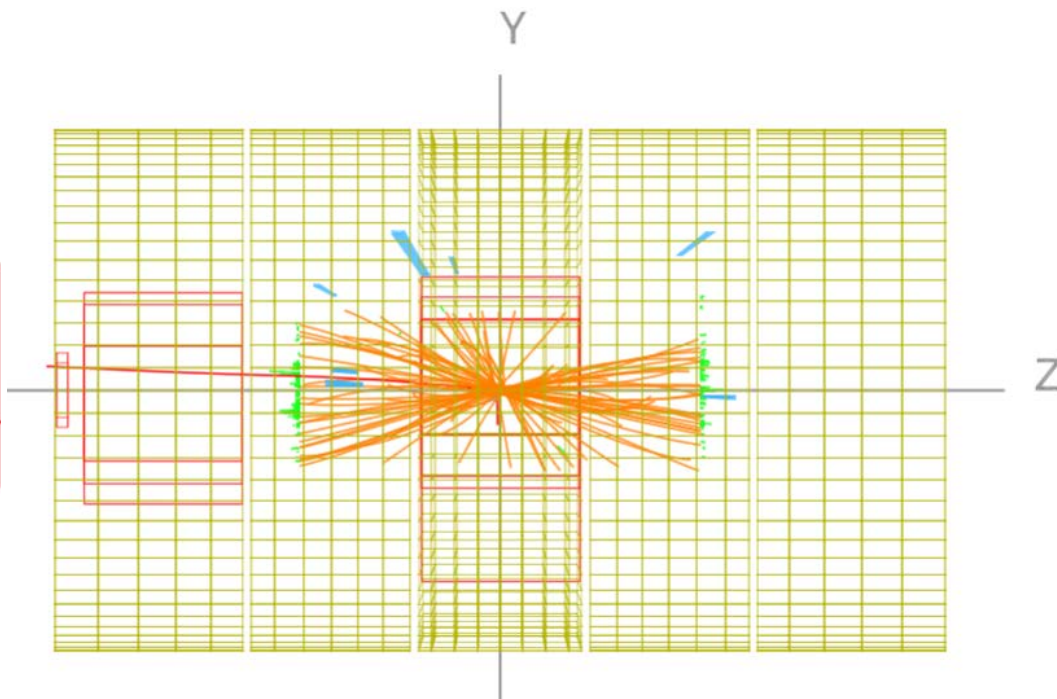
x-y view: measure ϕ



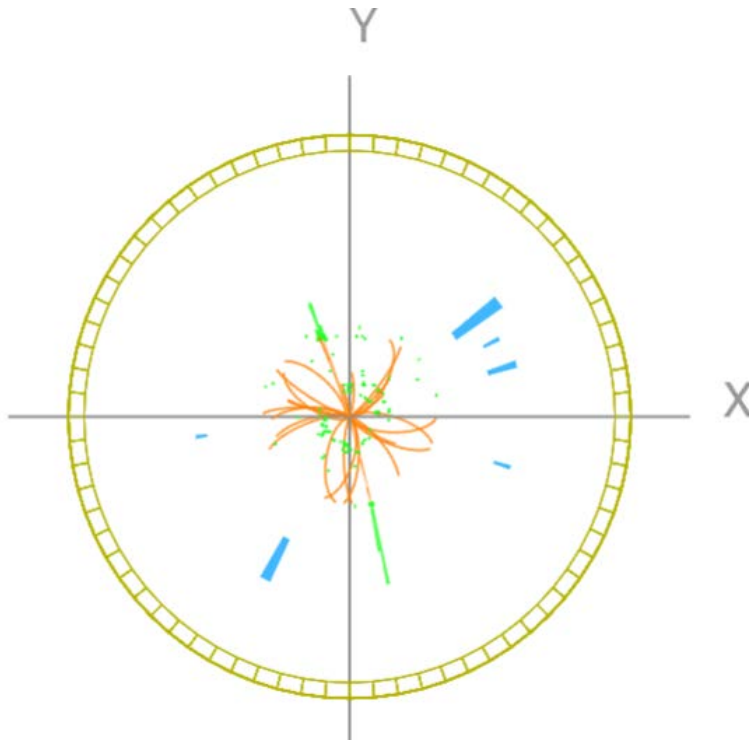
z-y view: measure θ



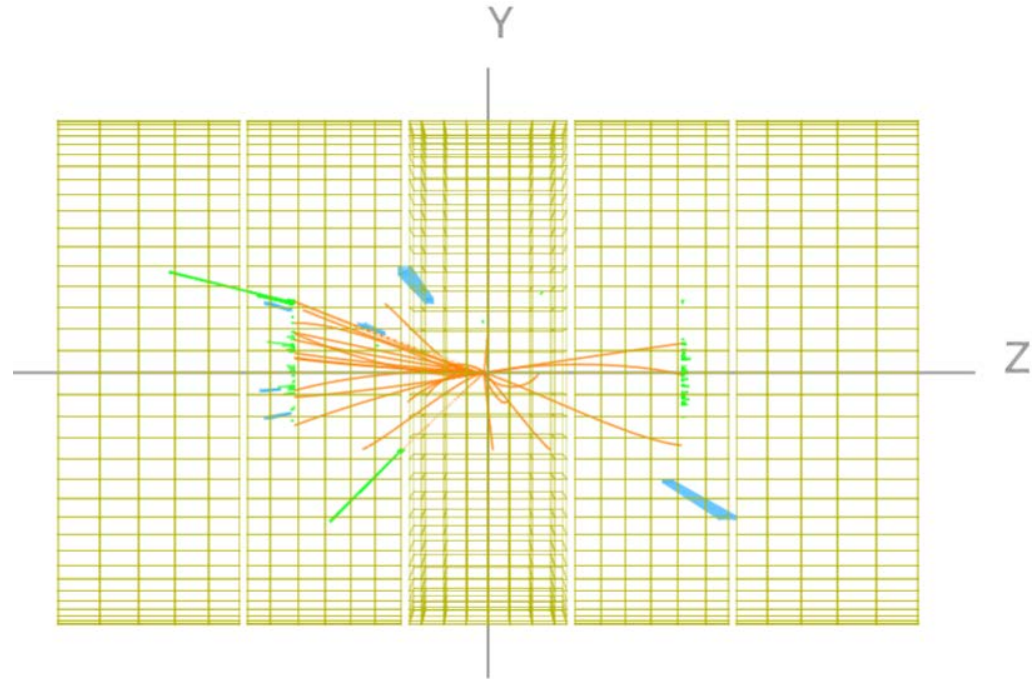
x-y view: measure ϕ



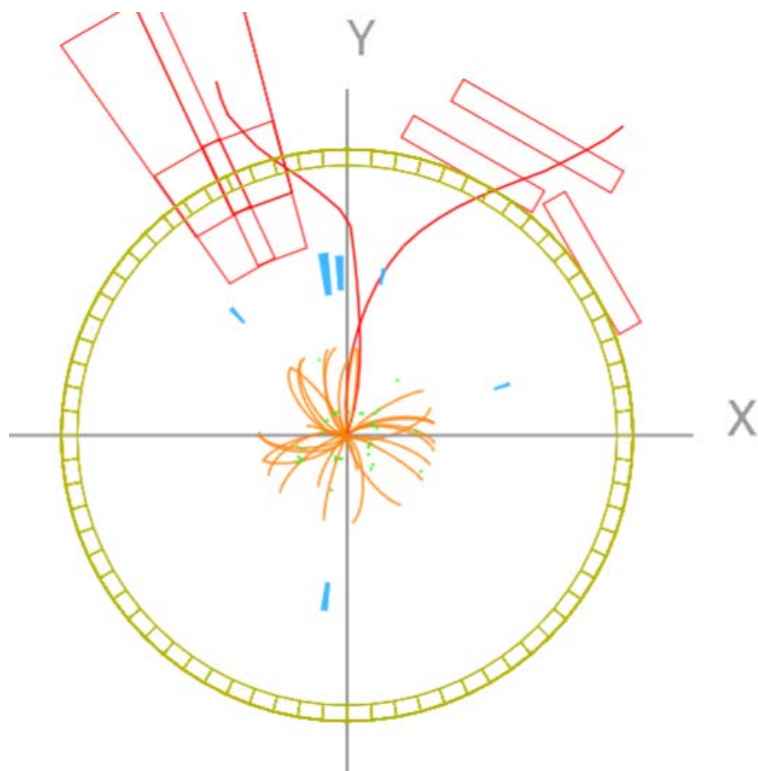
z-y view: measure θ



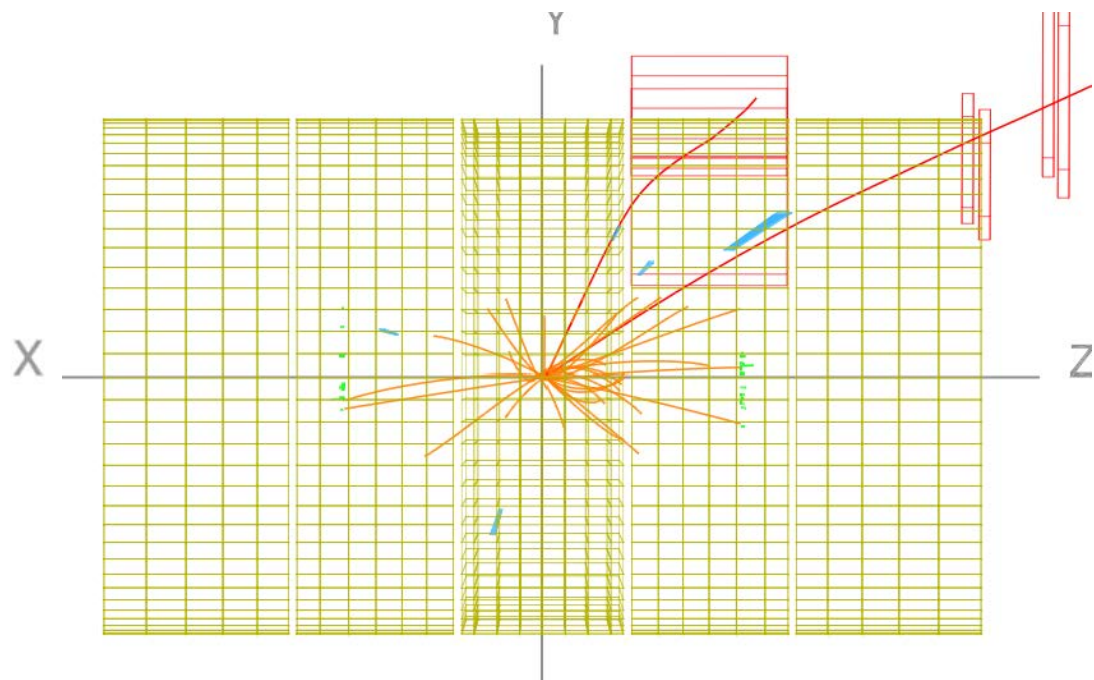
x-y view: measure ϕ



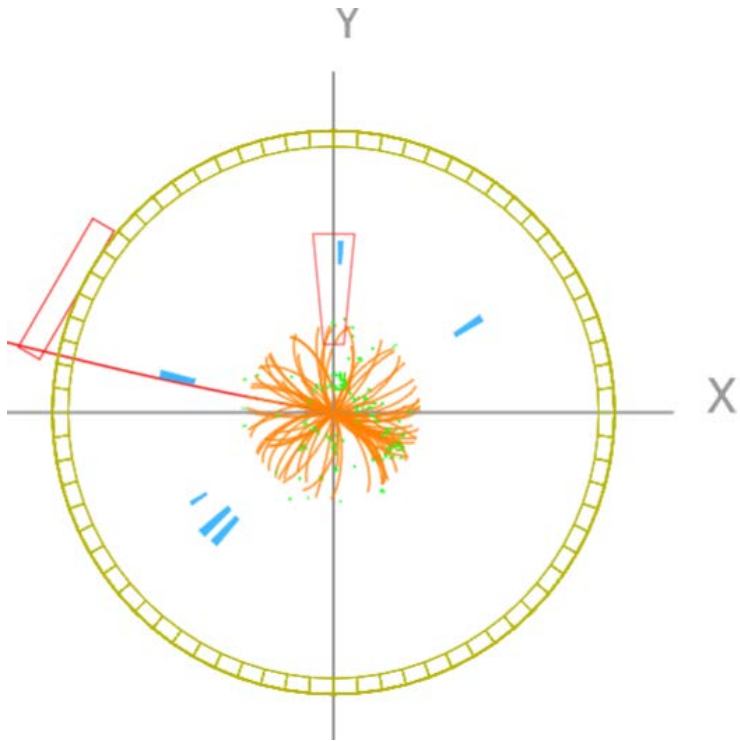
z-y view: measure θ



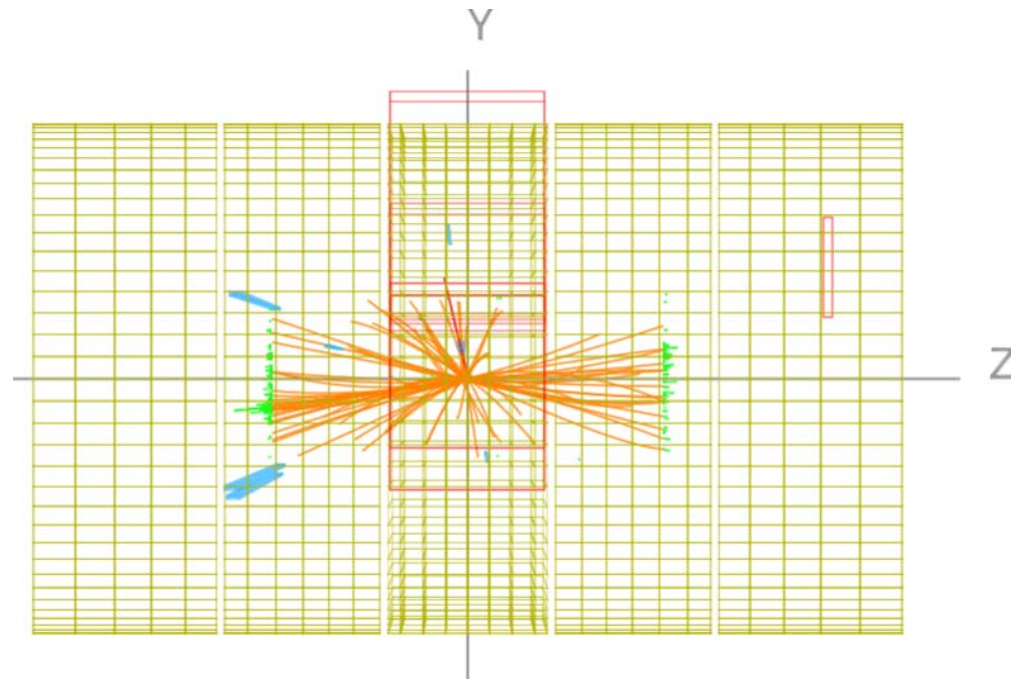
x-y view: measure ϕ



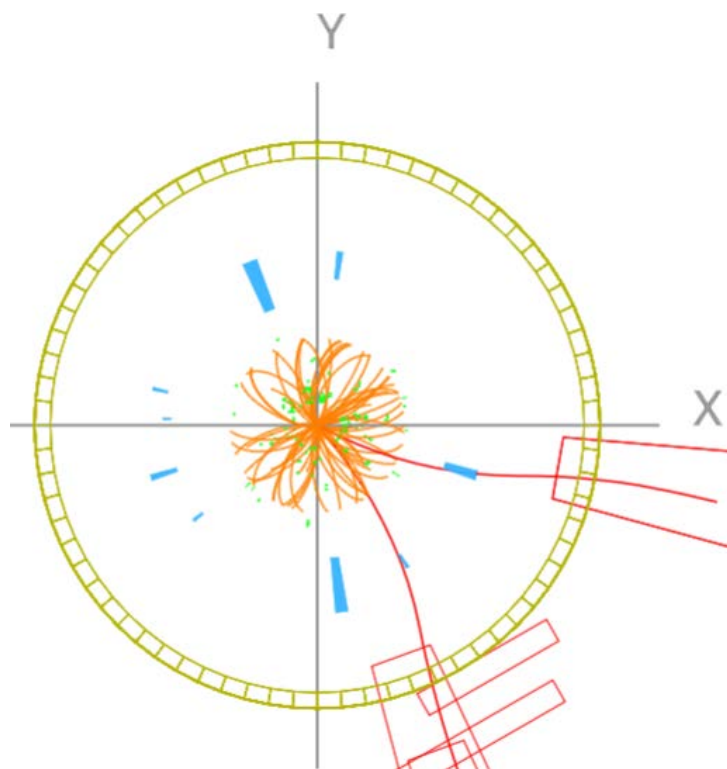
z-y view: measure θ



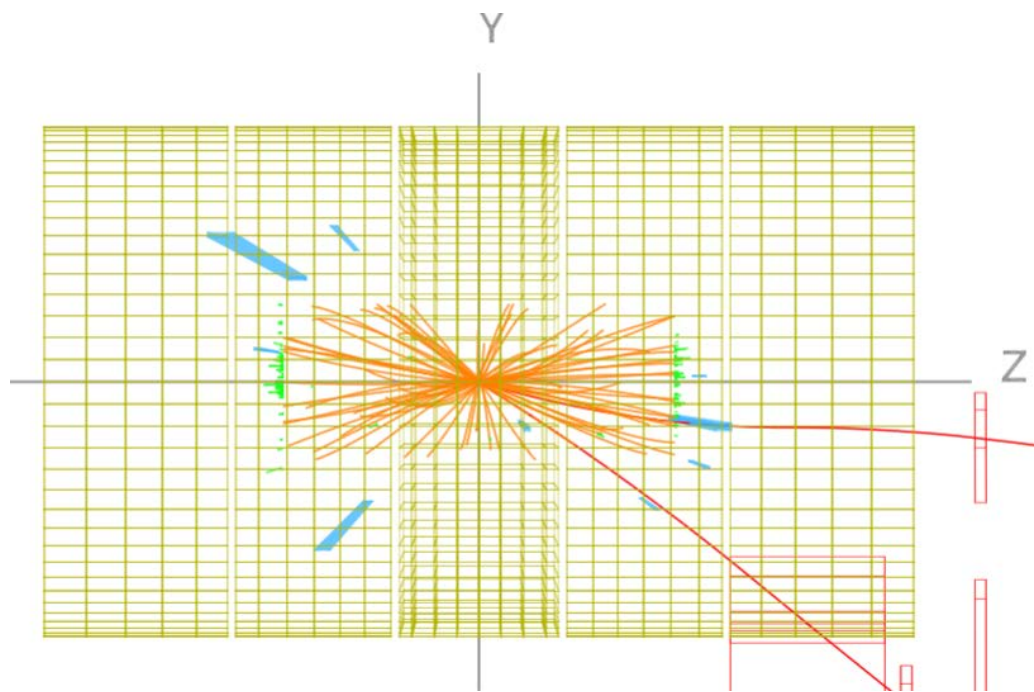
x-y view: measure ϕ



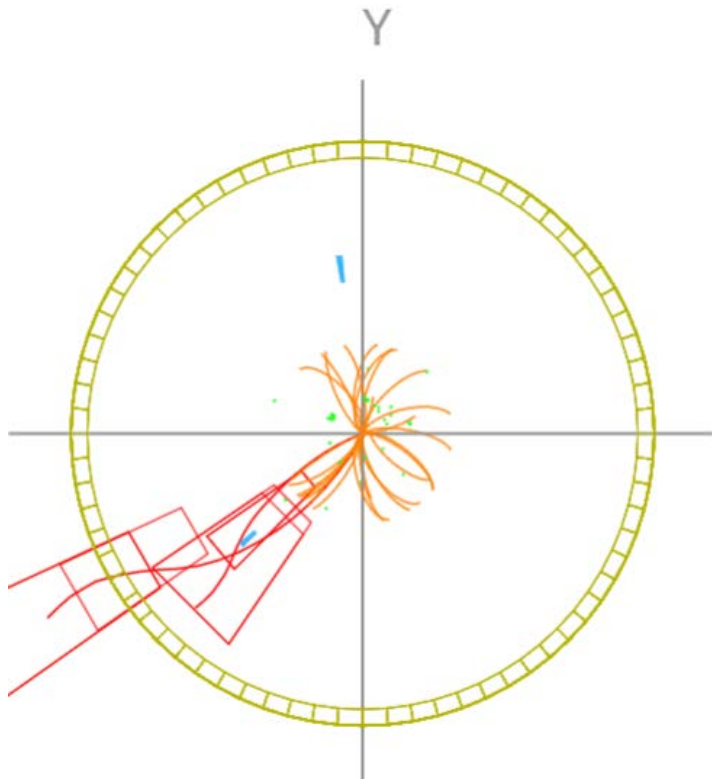
z-y view: measure θ



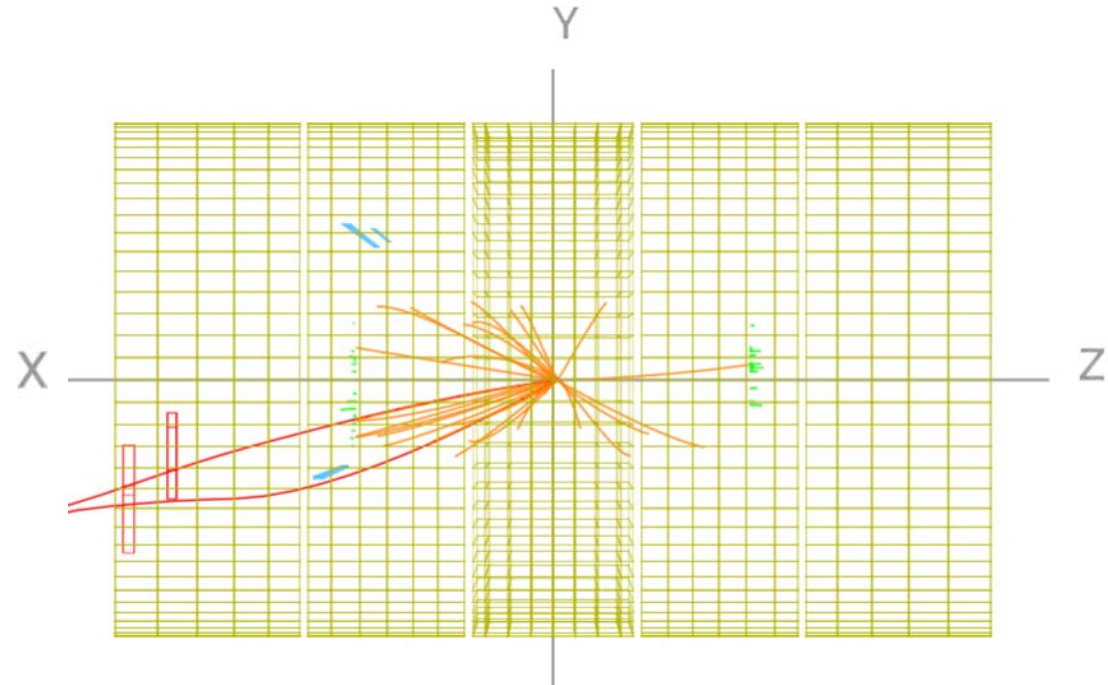
x-y view: measure ϕ



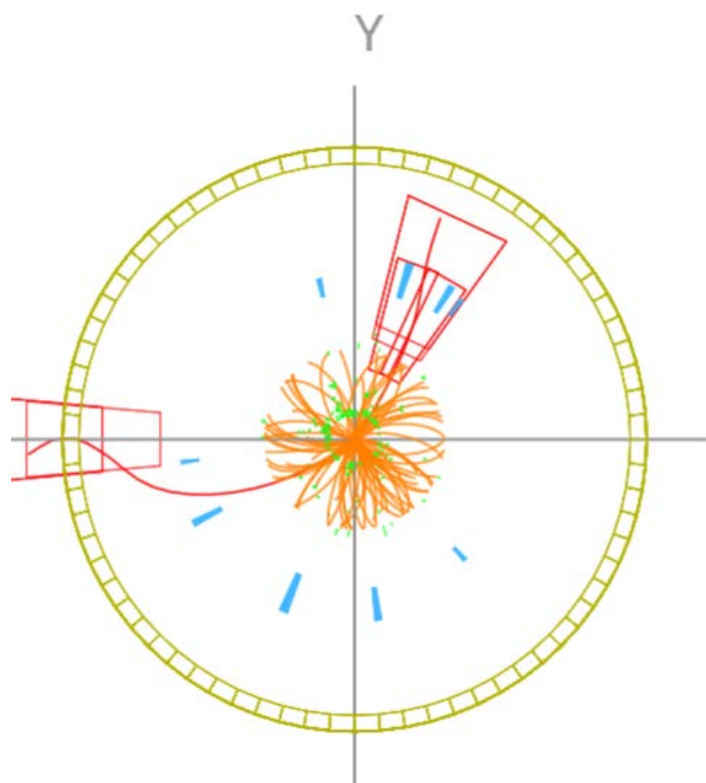
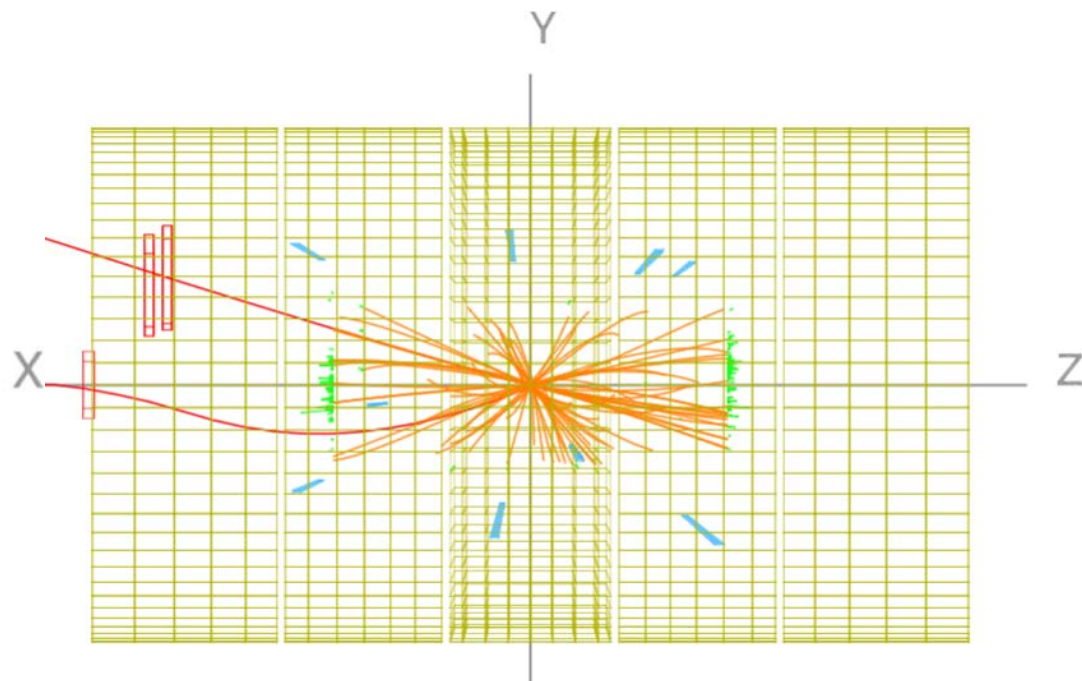
z-y view: measure θ

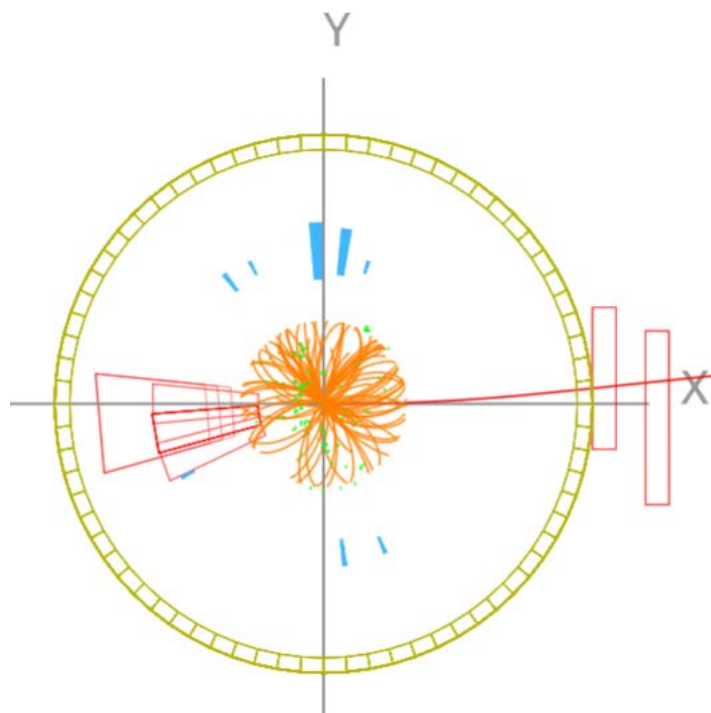


x-y view: measure ϕ

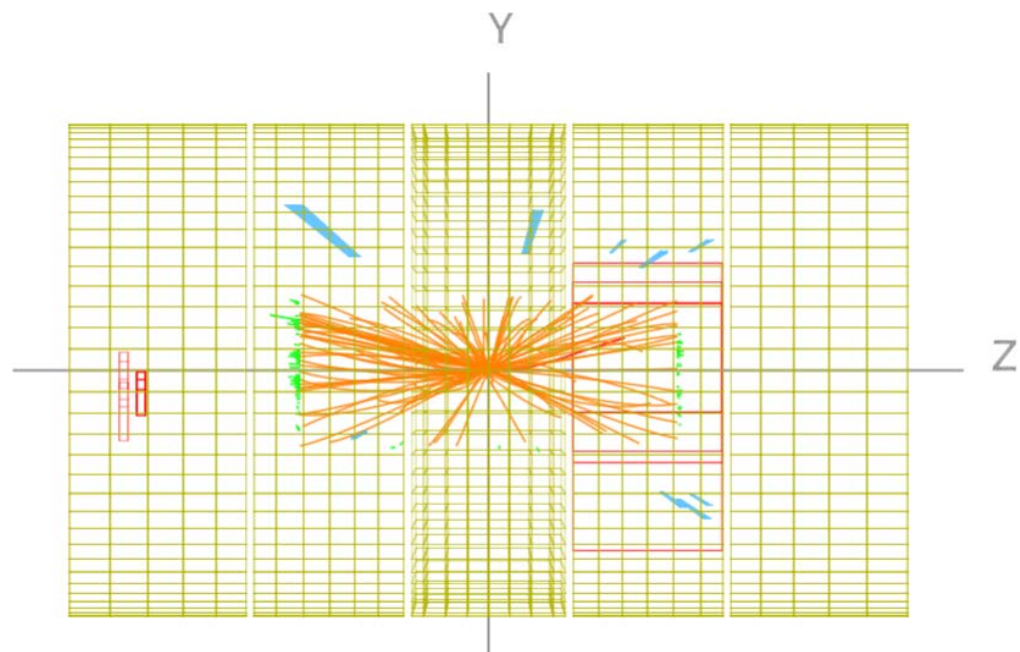


z-y view: measure θ

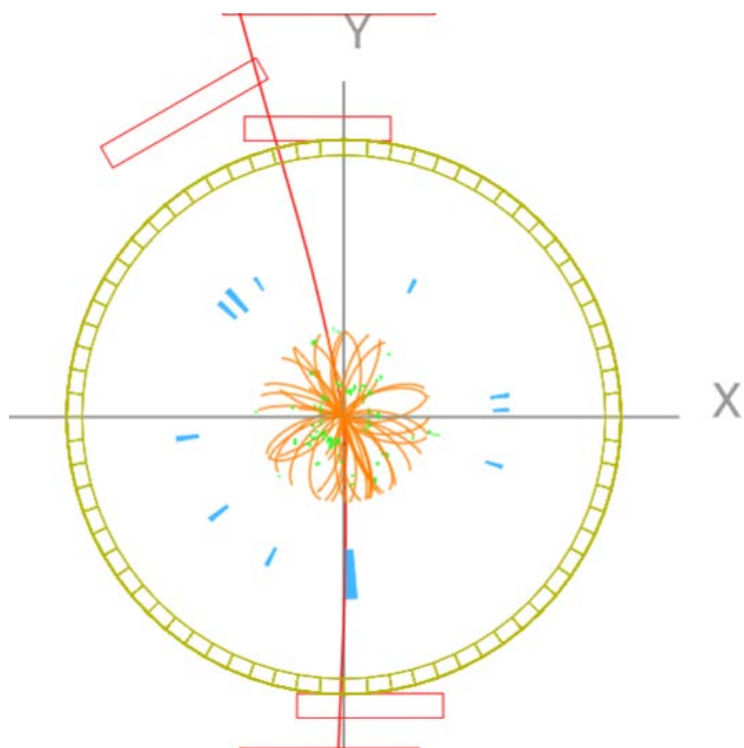
x-y view: measure ϕ z-y view: measure θ



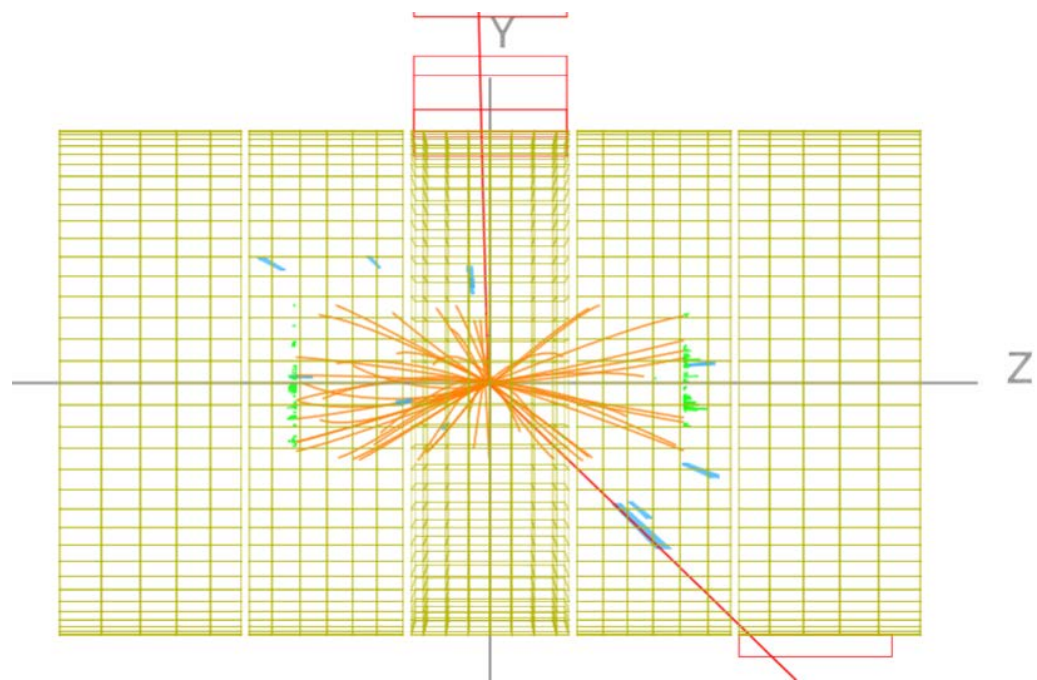
x-y view: measure ϕ



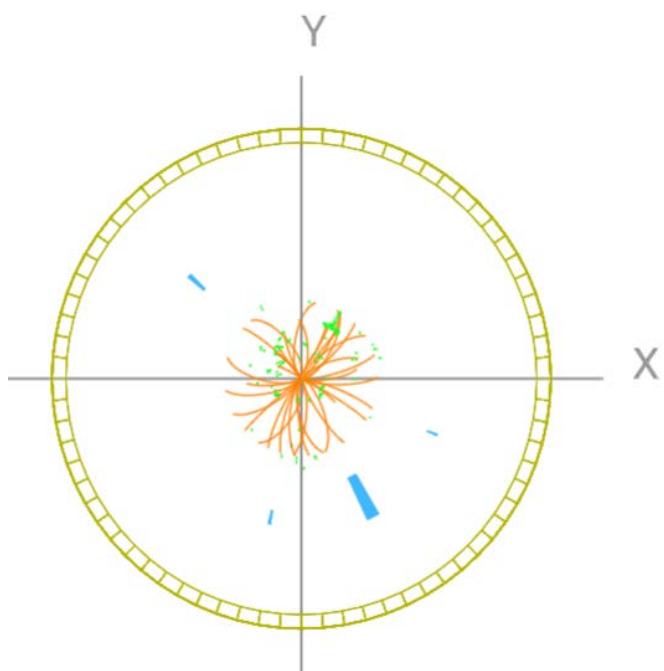
z-y view: measure θ



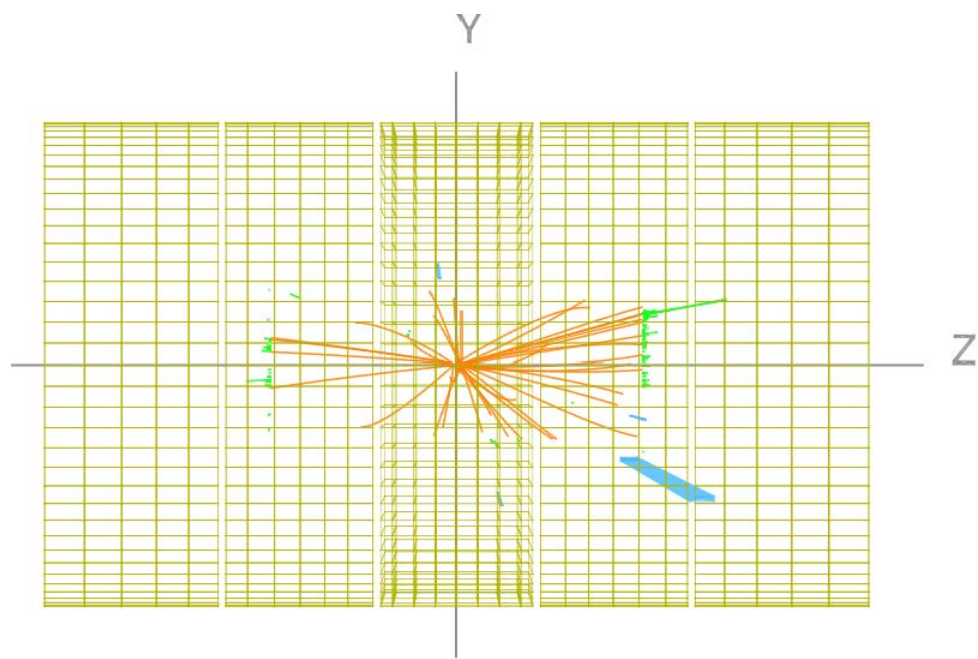
x-y view: measure ϕ



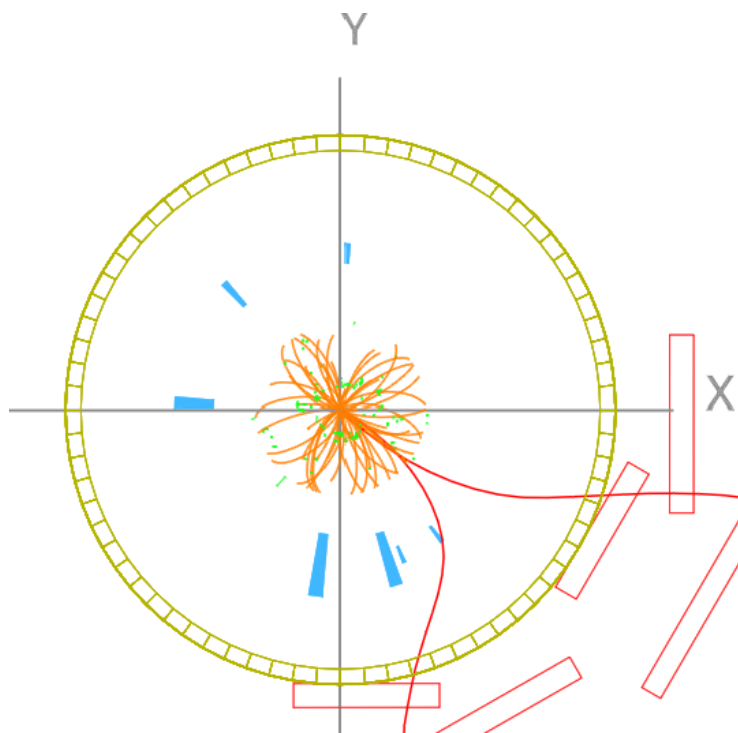
z-y view: measure θ



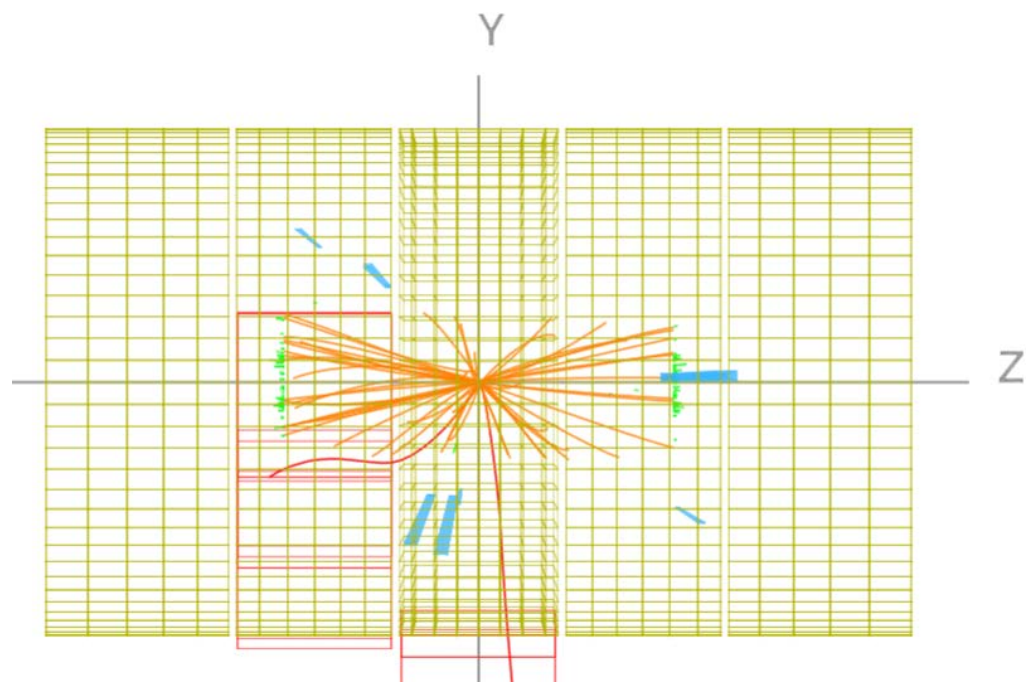
x-y view: measure ϕ



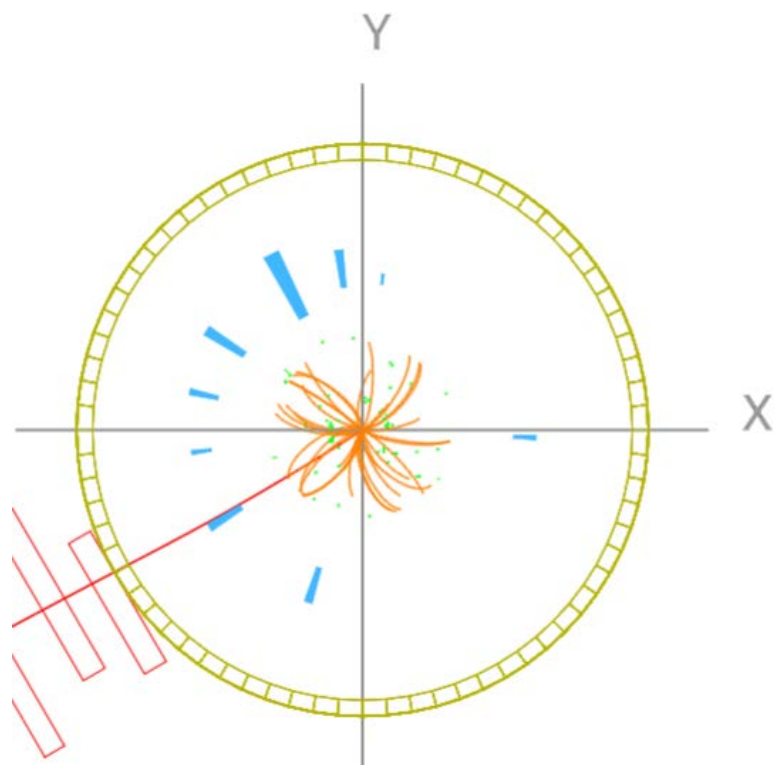
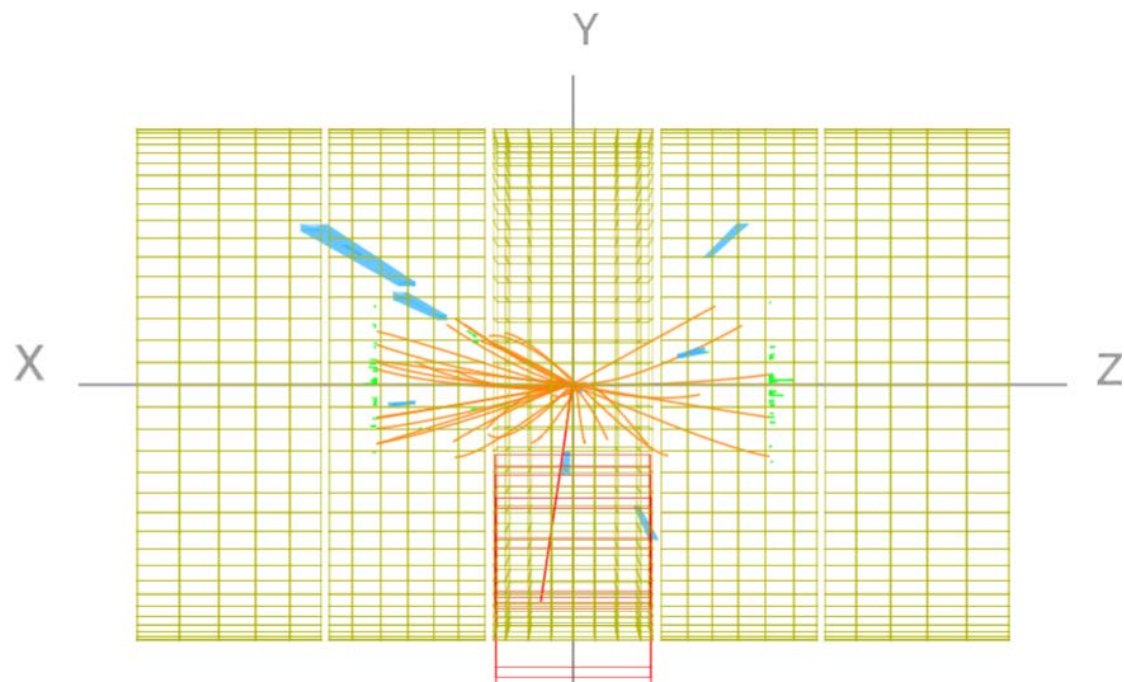
z-y view: measure θ

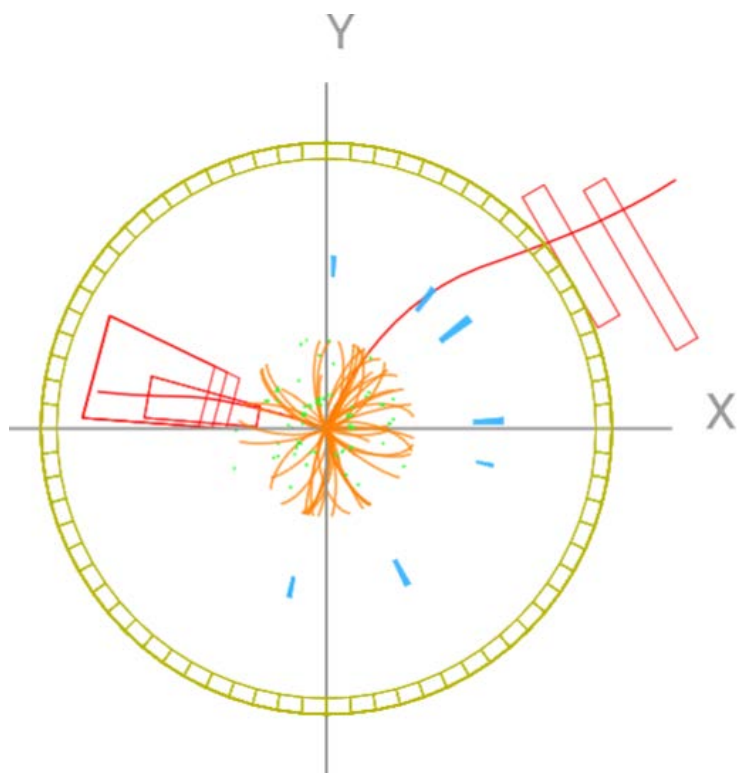


x-y view: measure ϕ

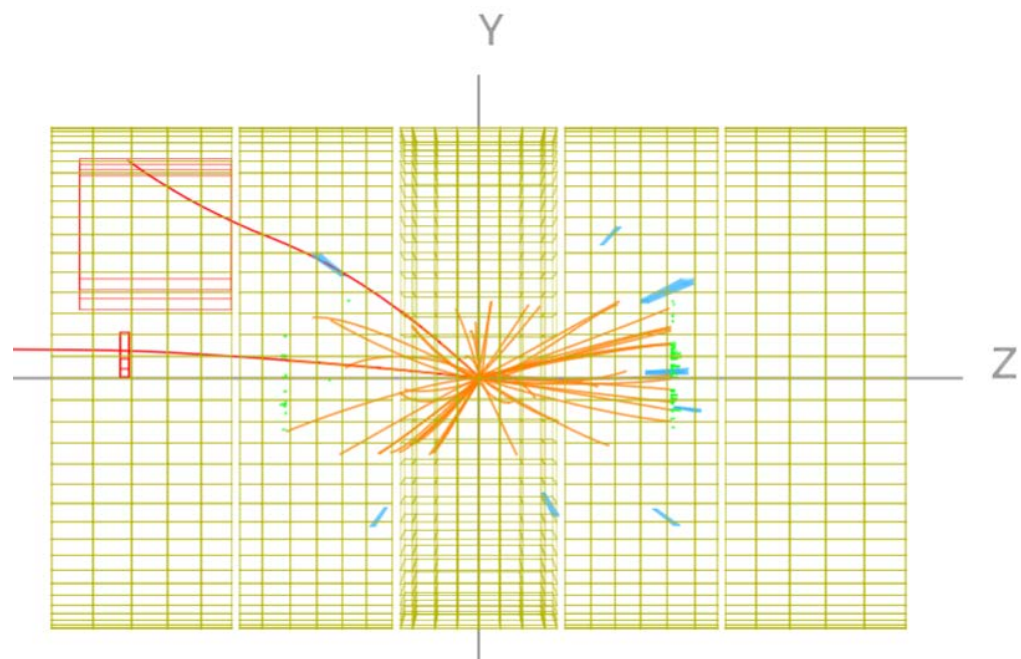


z-y view: measure θ

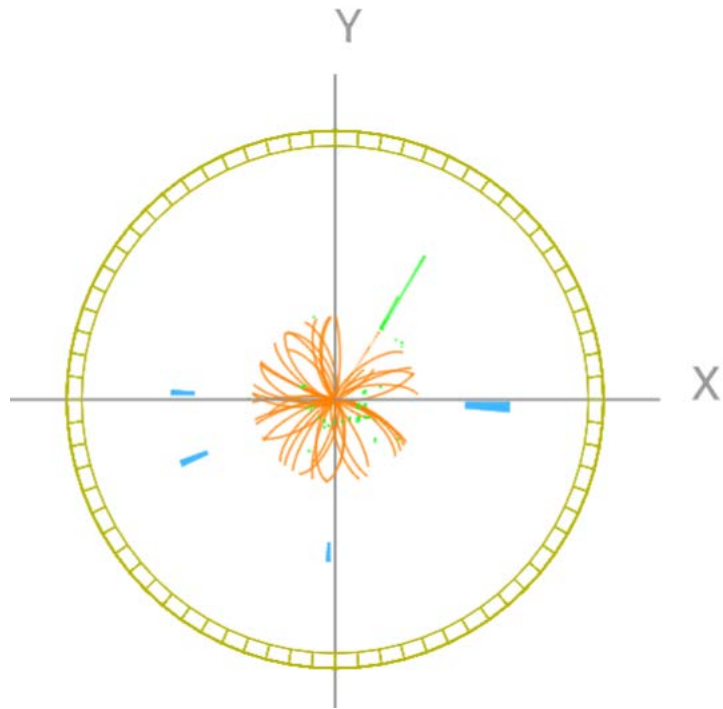
x-y view: measure ϕ z-y view: measure θ



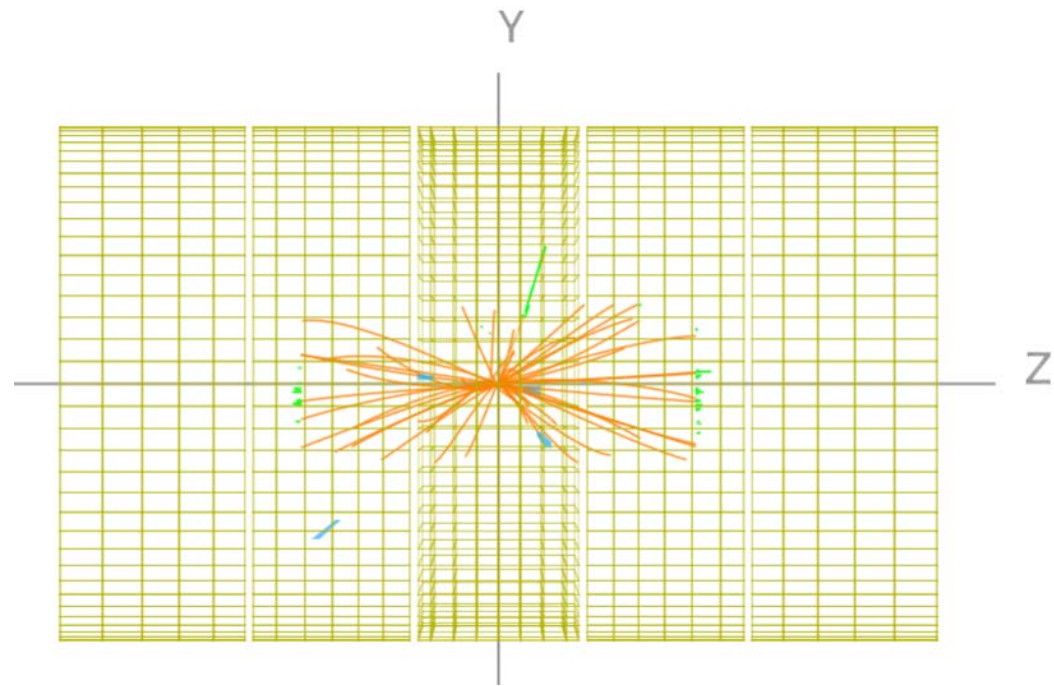
x-y view: measure ϕ



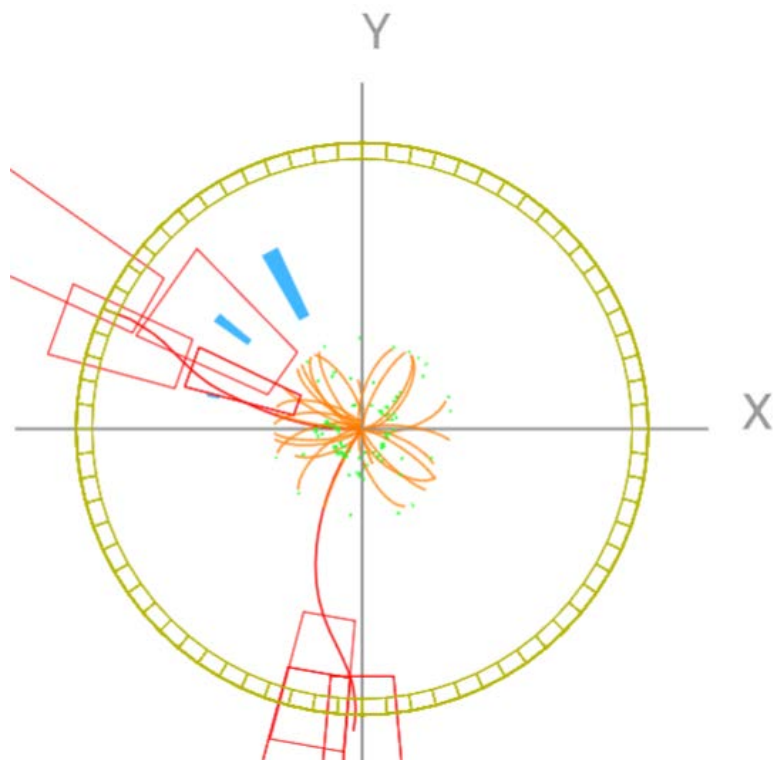
z-y view: measure θ



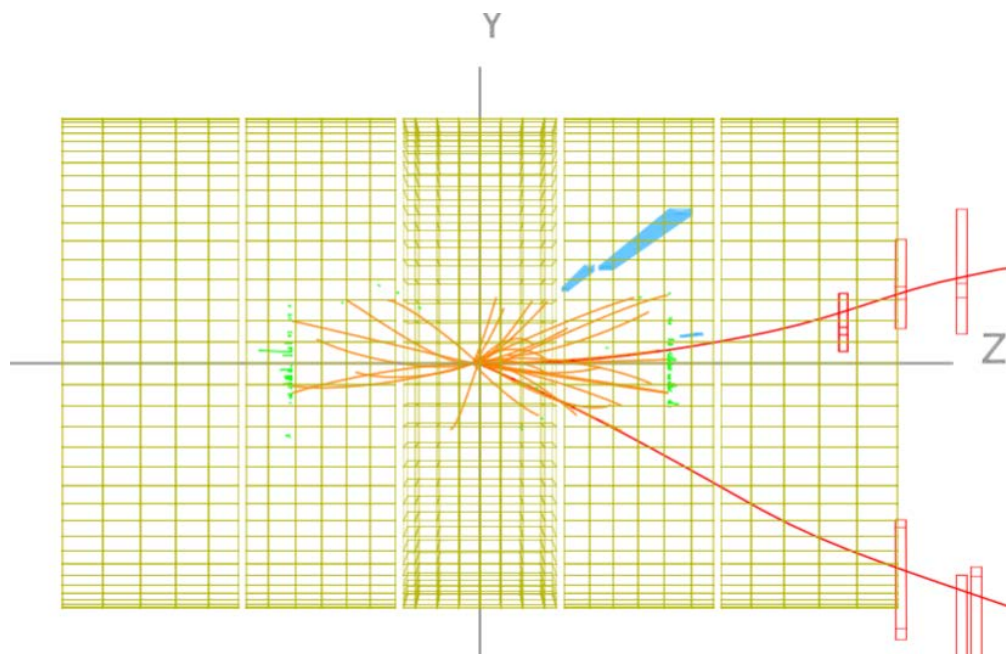
x-y view: measure ϕ



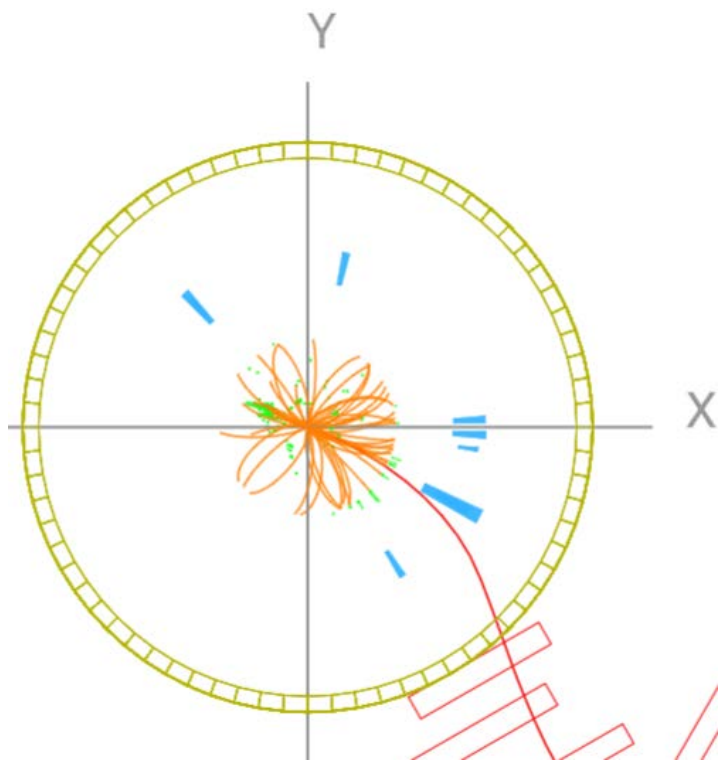
z-y view: measure θ



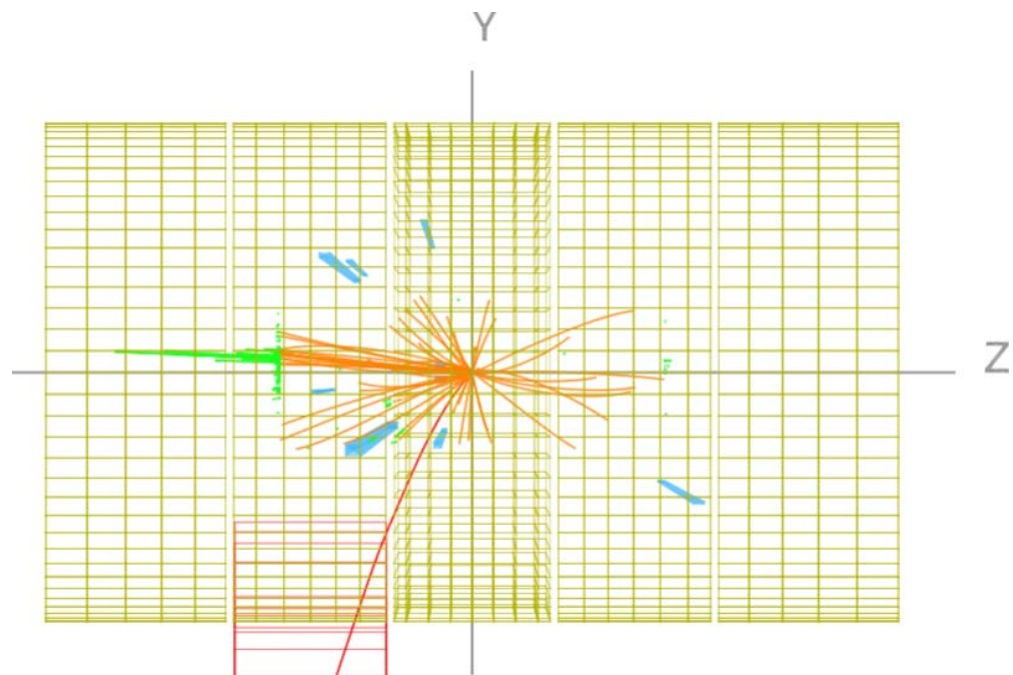
x-y view: measure ϕ



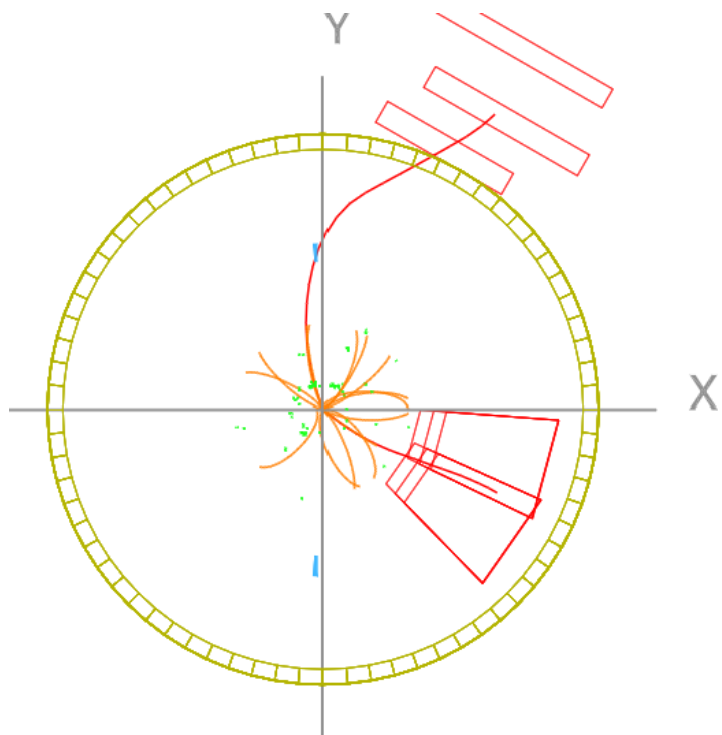
z-y view: measure θ



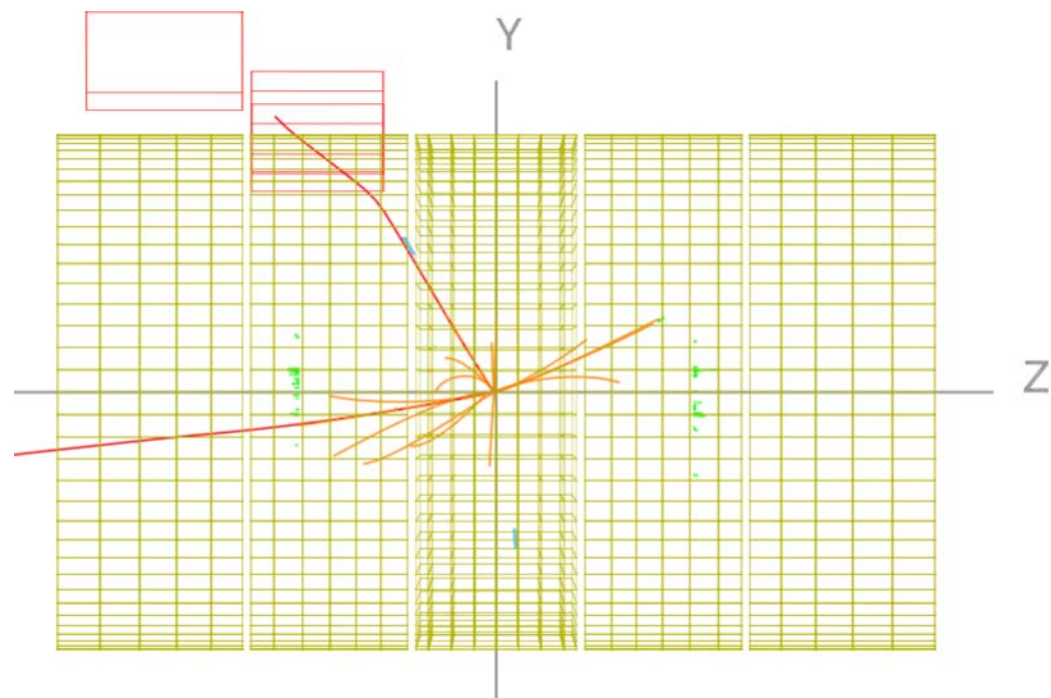
x-y view: measure ϕ



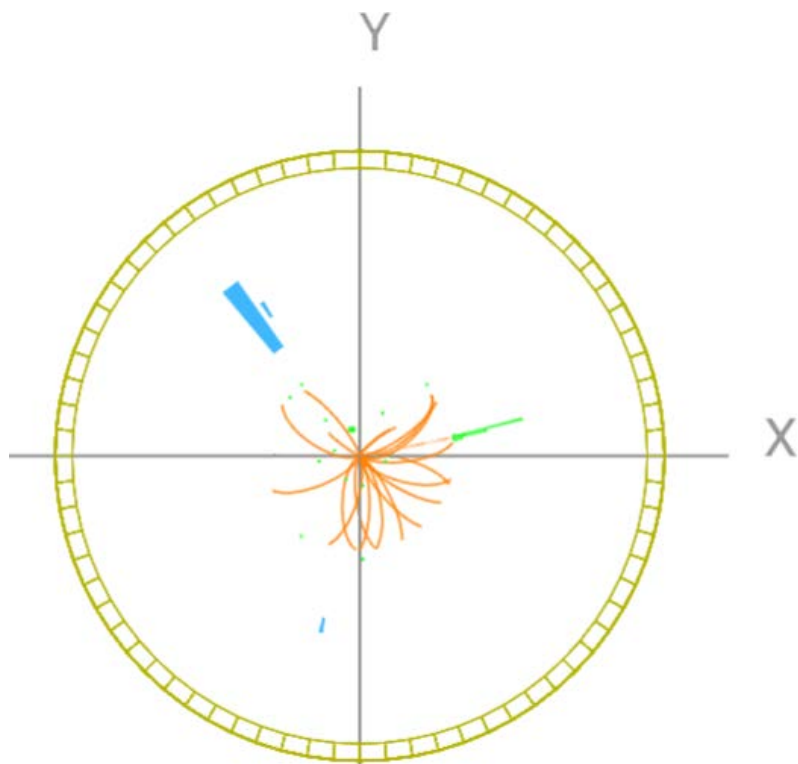
z-y view: measure θ



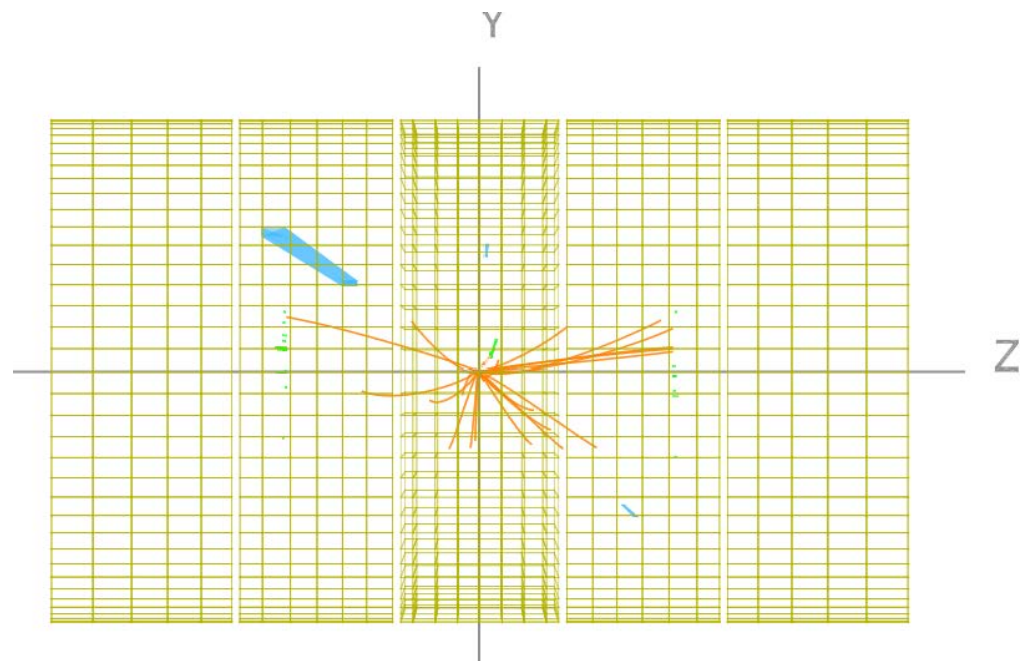
x-y view: measure ϕ



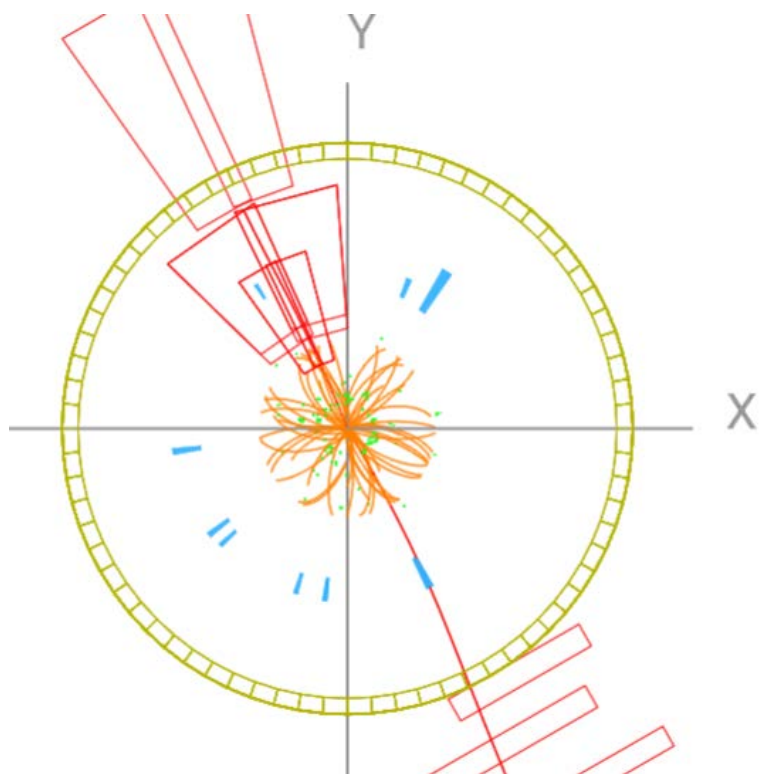
z-y view: measure θ



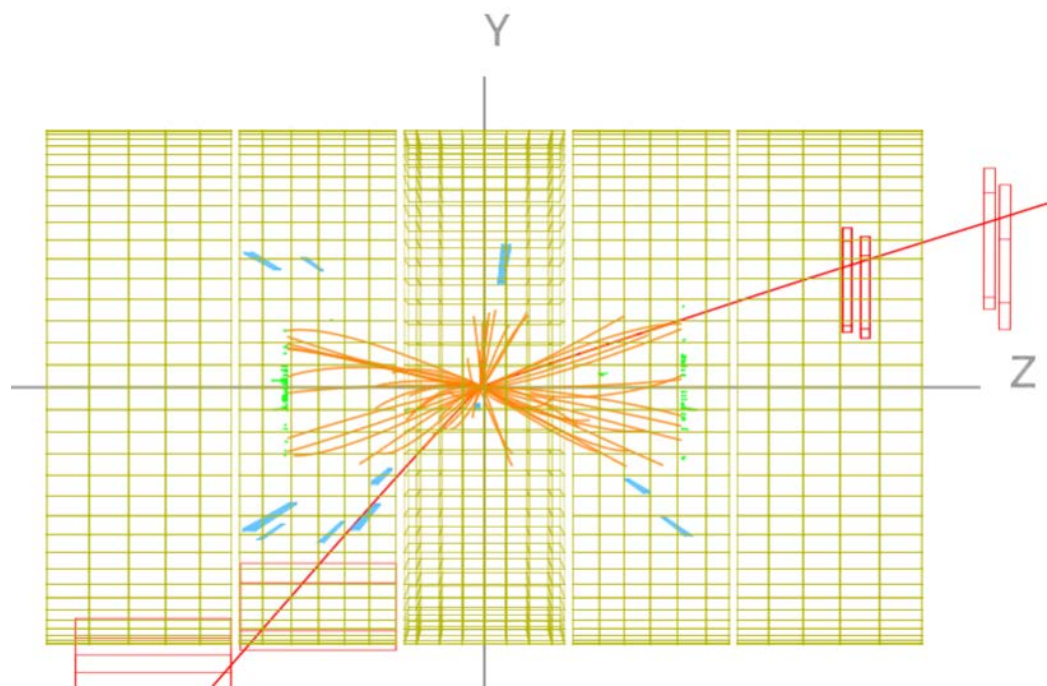
x-y view: measure ϕ



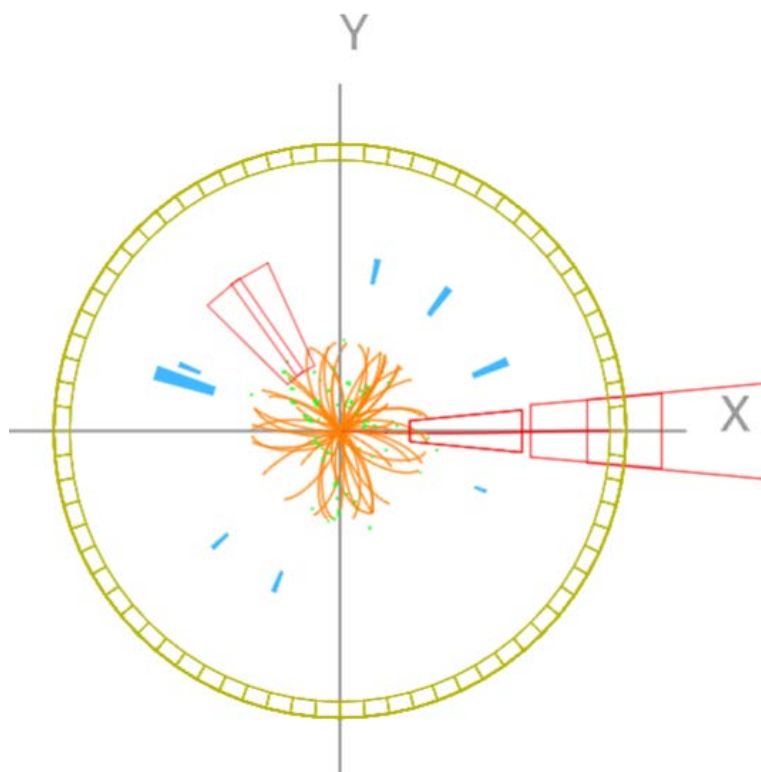
z-y view: measure θ



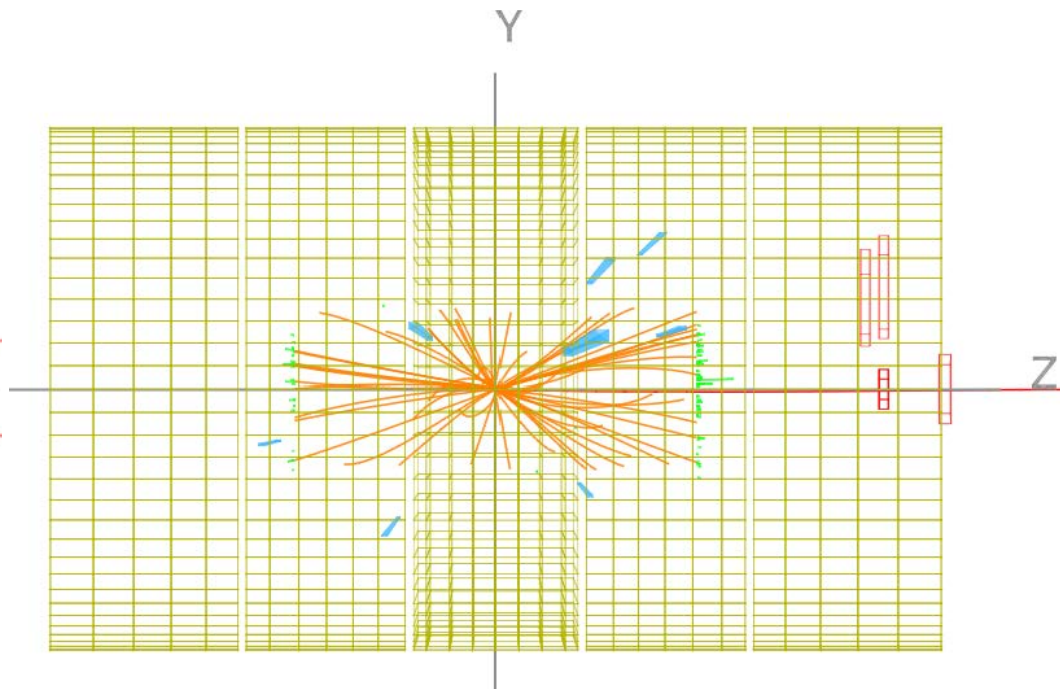
x-y view: measure ϕ



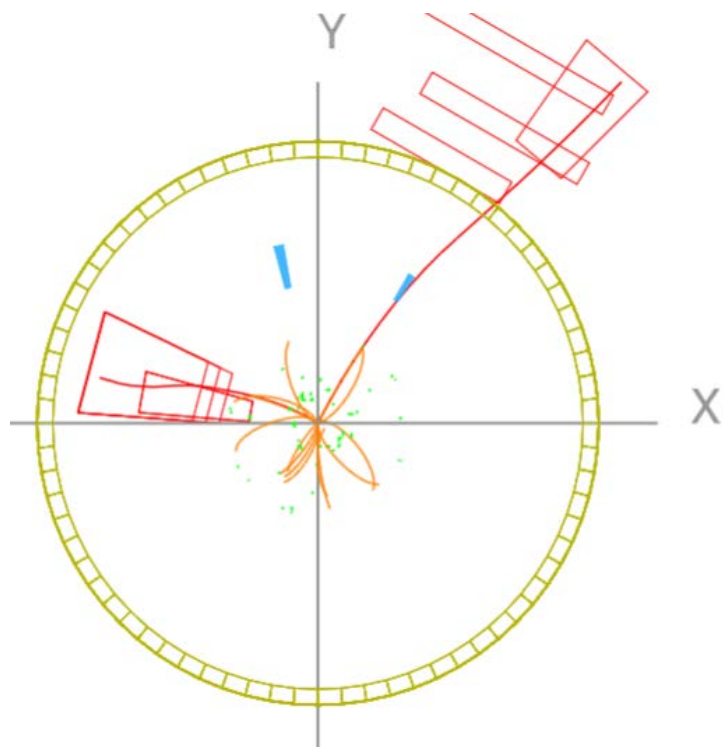
z-y view: measure θ



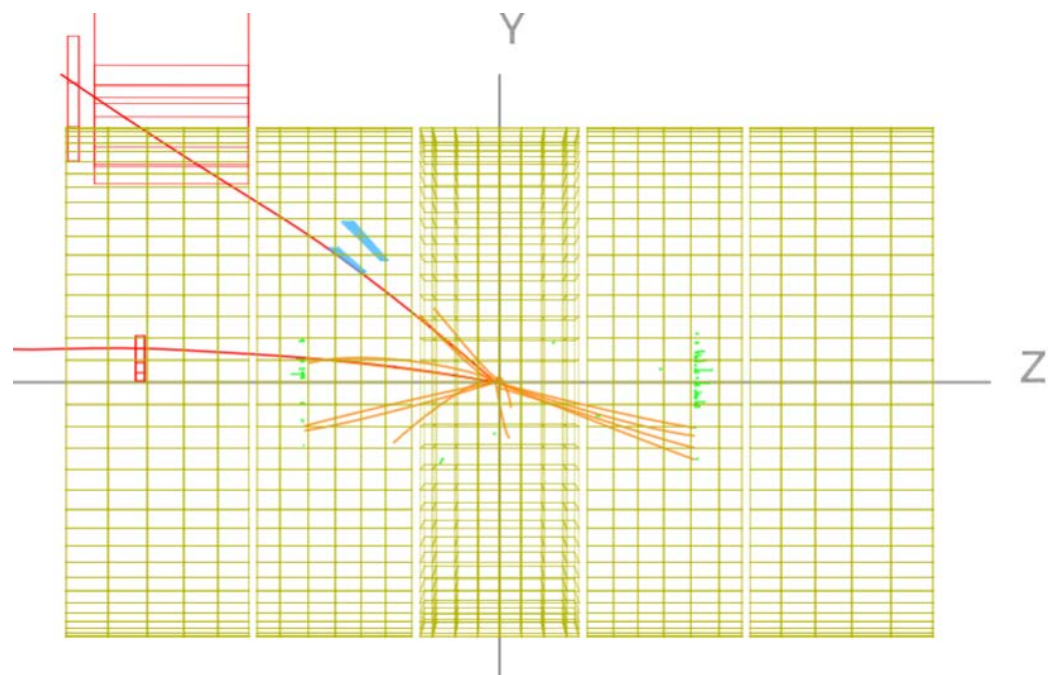
x-y view: measure ϕ



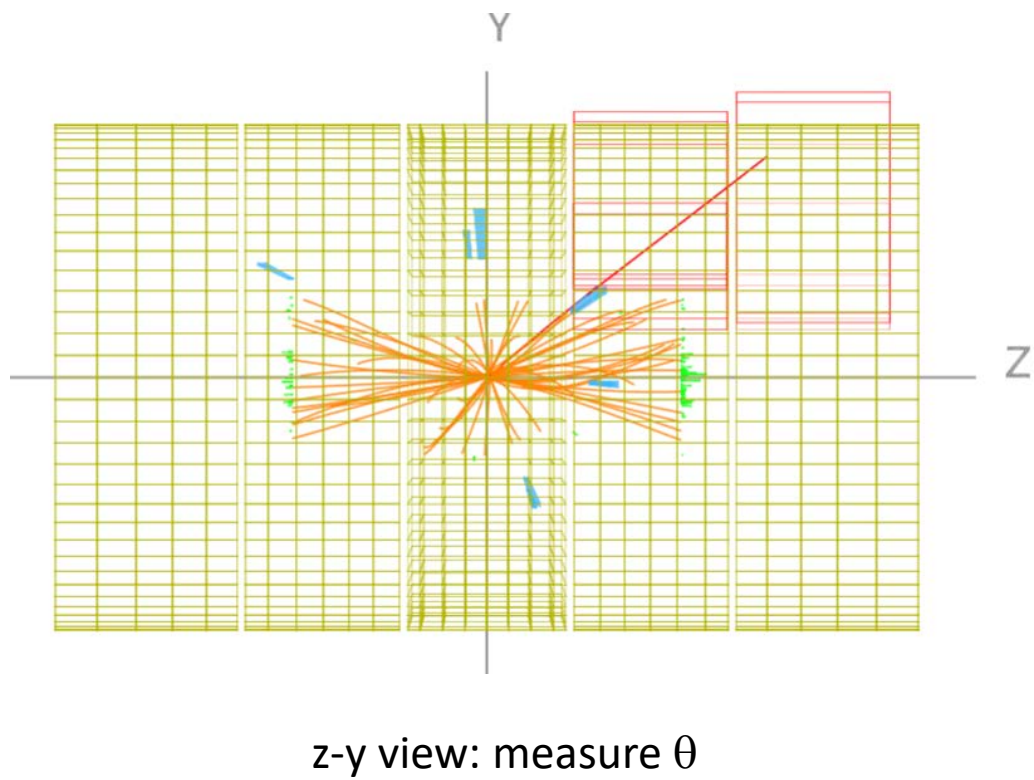
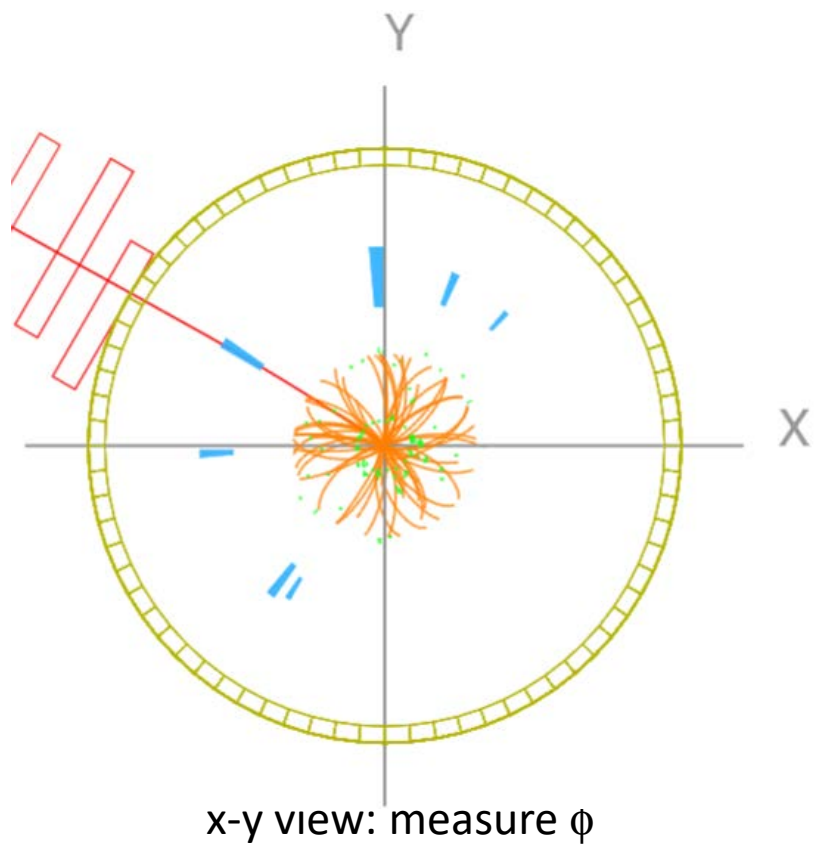
z-y view: measure θ

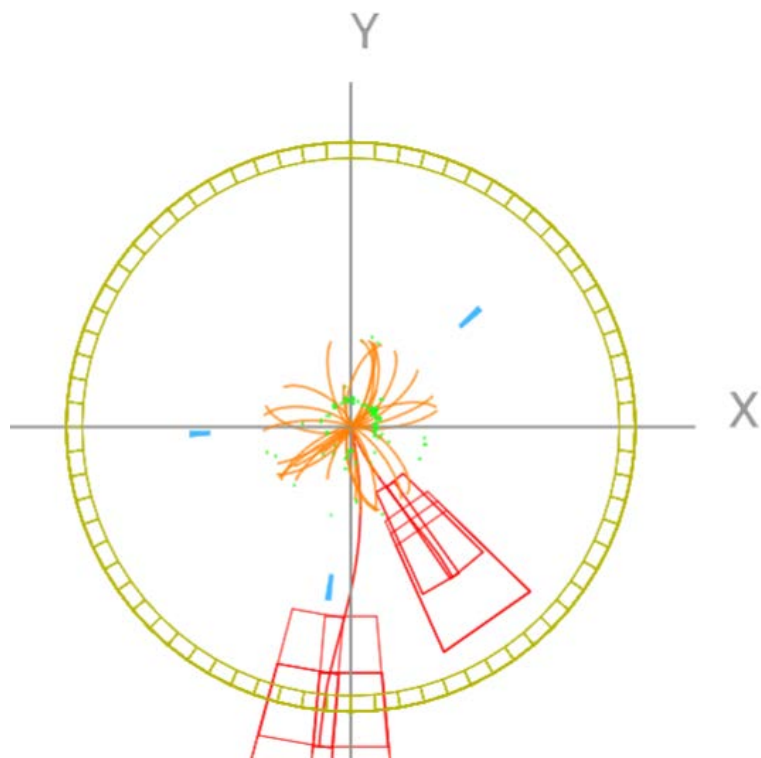


x-y view: measure ϕ

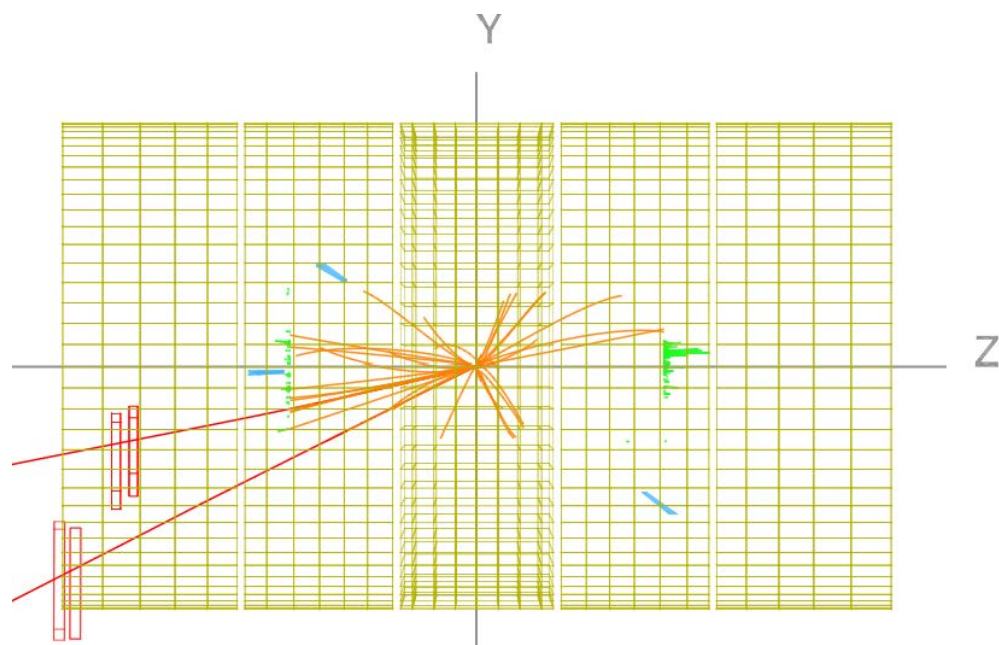


z-y view: measure θ

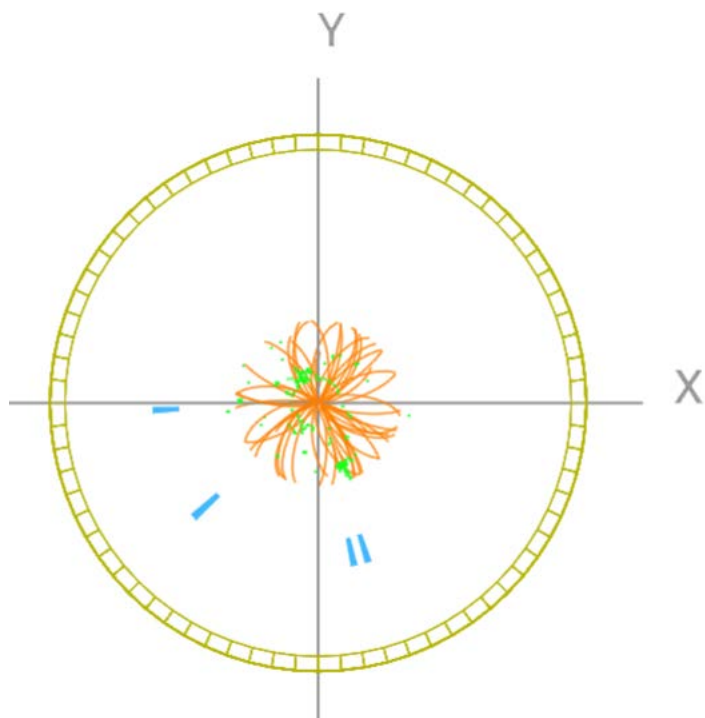




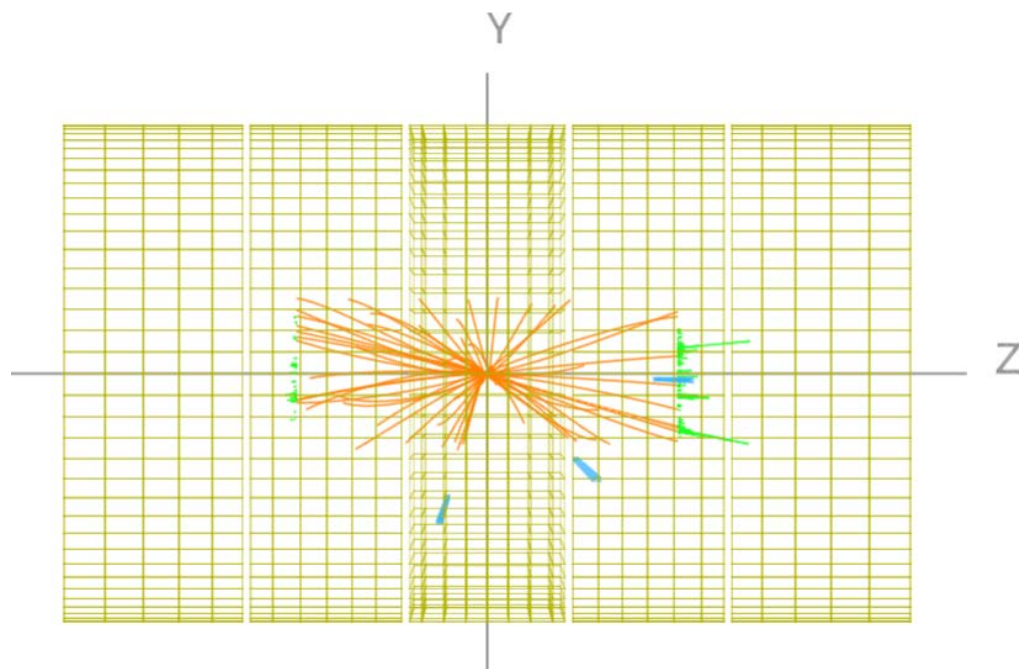
x-y view: measure ϕ



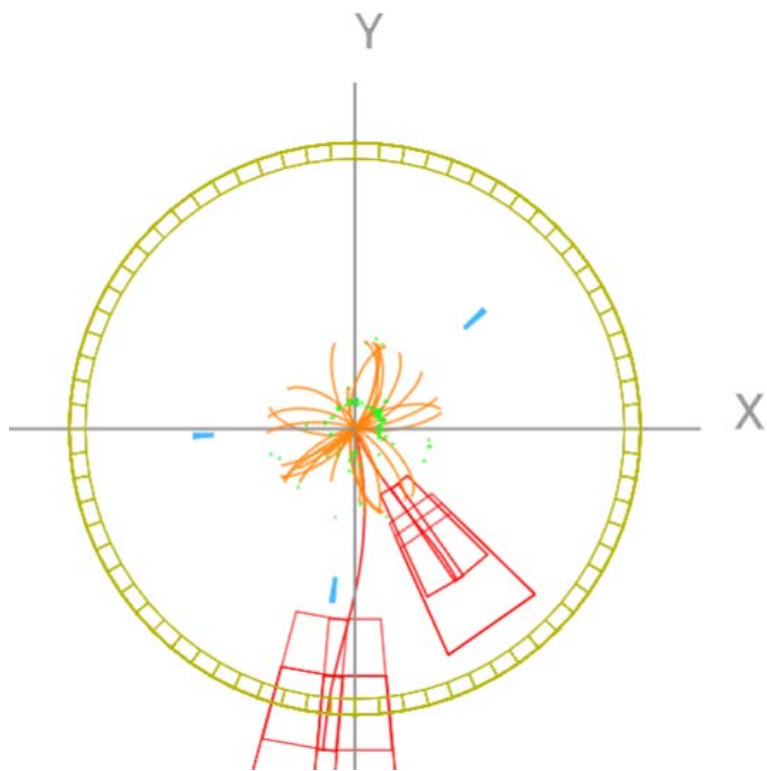
z-y view: measure θ



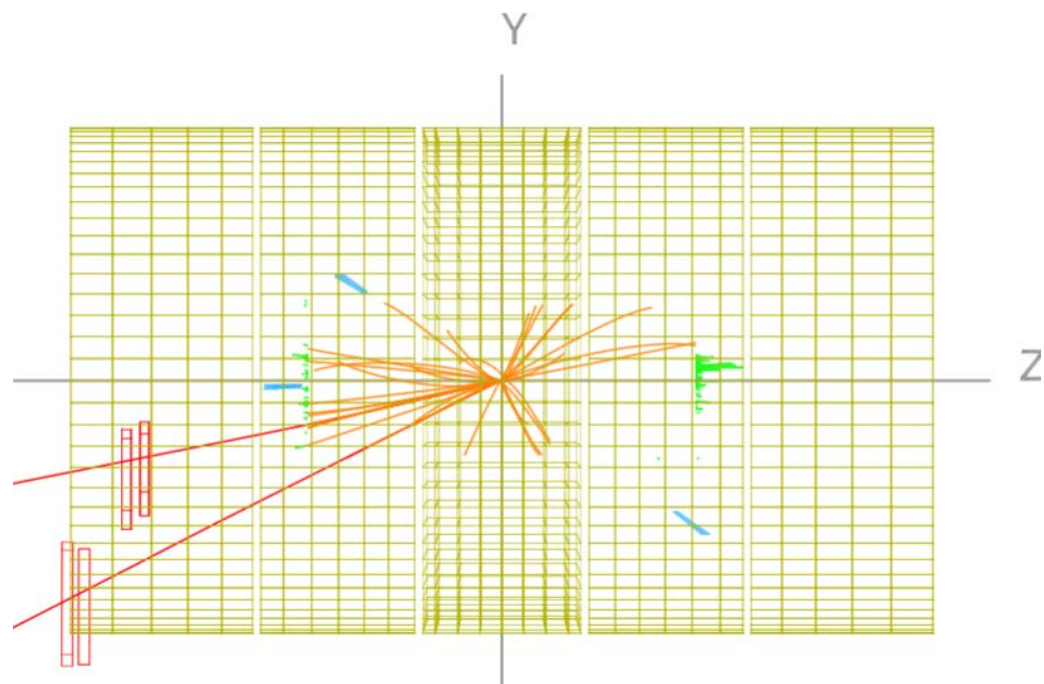
x-y view: measure ϕ



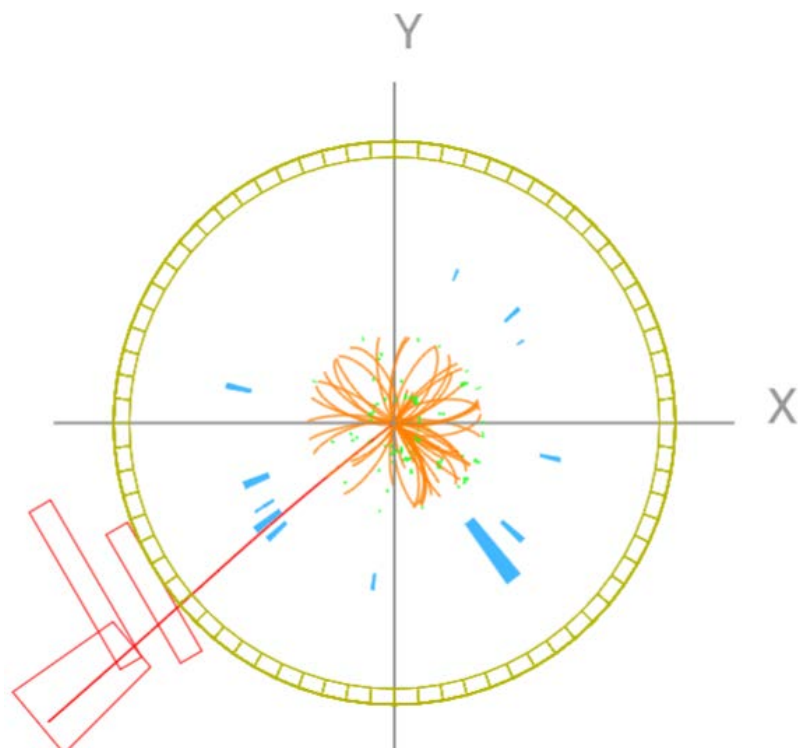
z-y view: measure θ



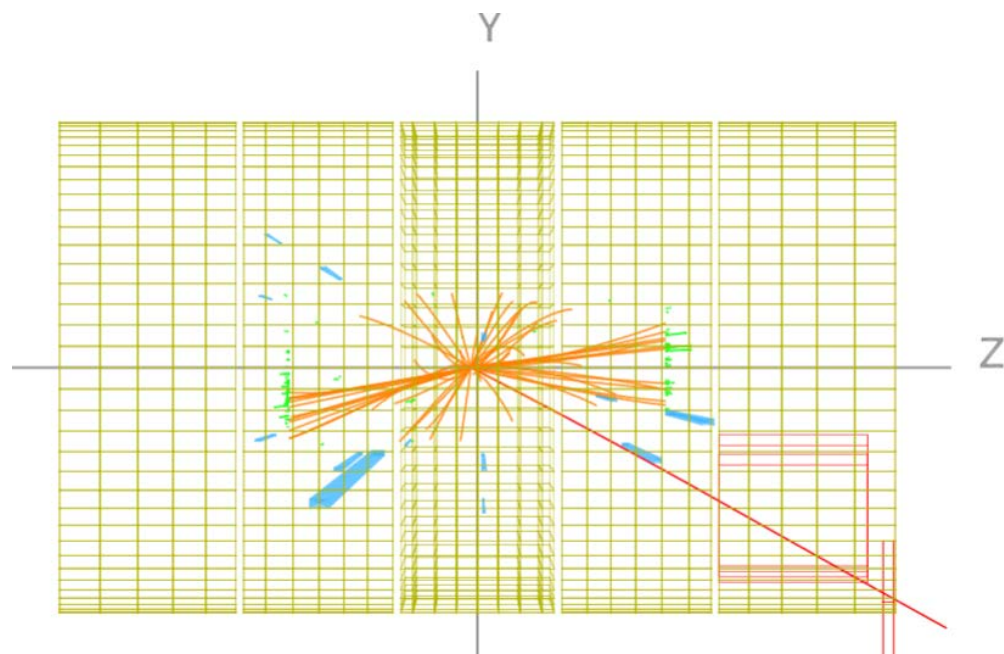
x-y view: measure ϕ



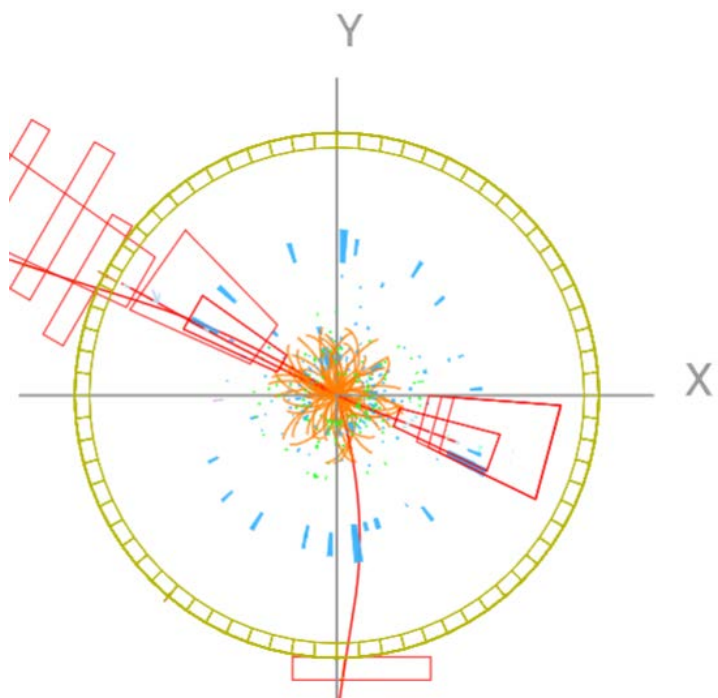
z-y view: measure θ



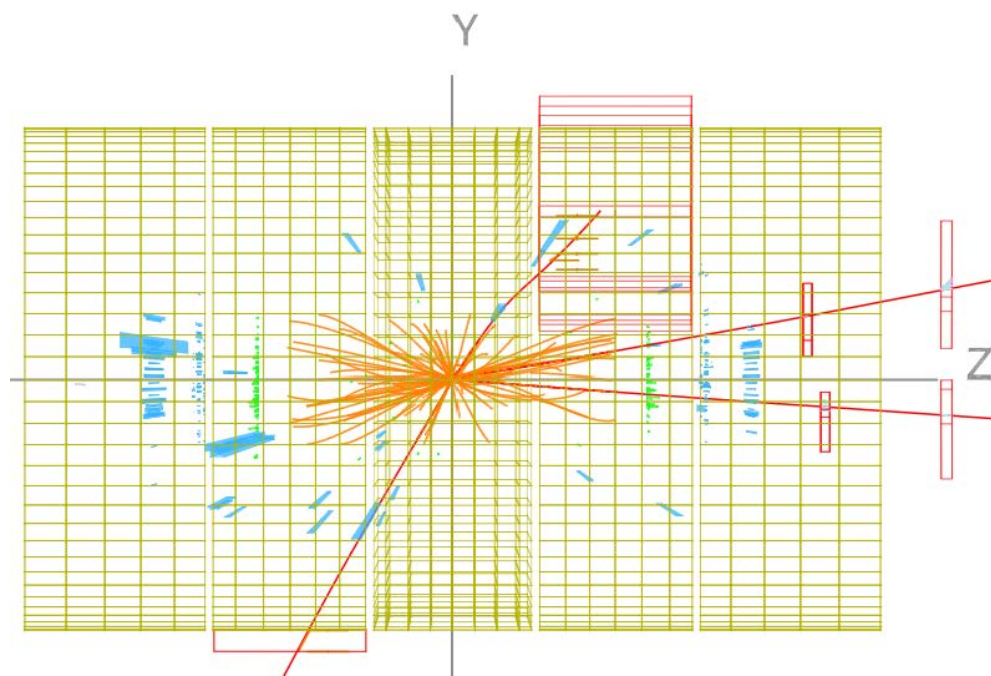
x-y view: measure ϕ



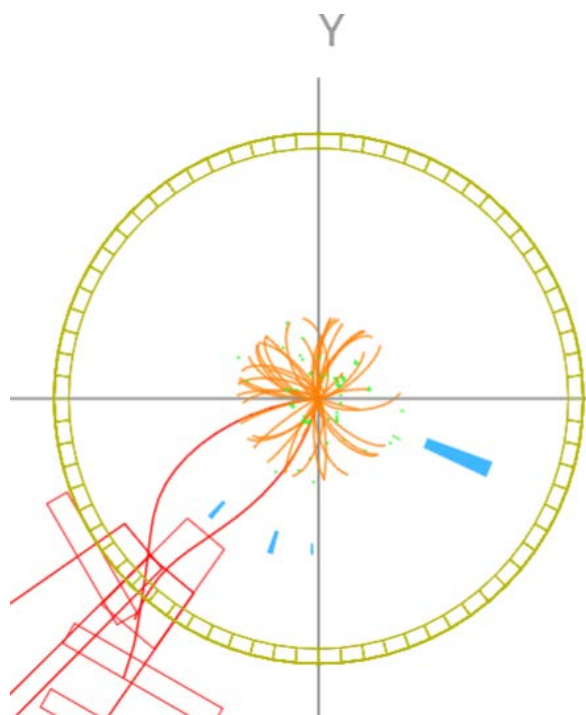
z-y view: measure θ



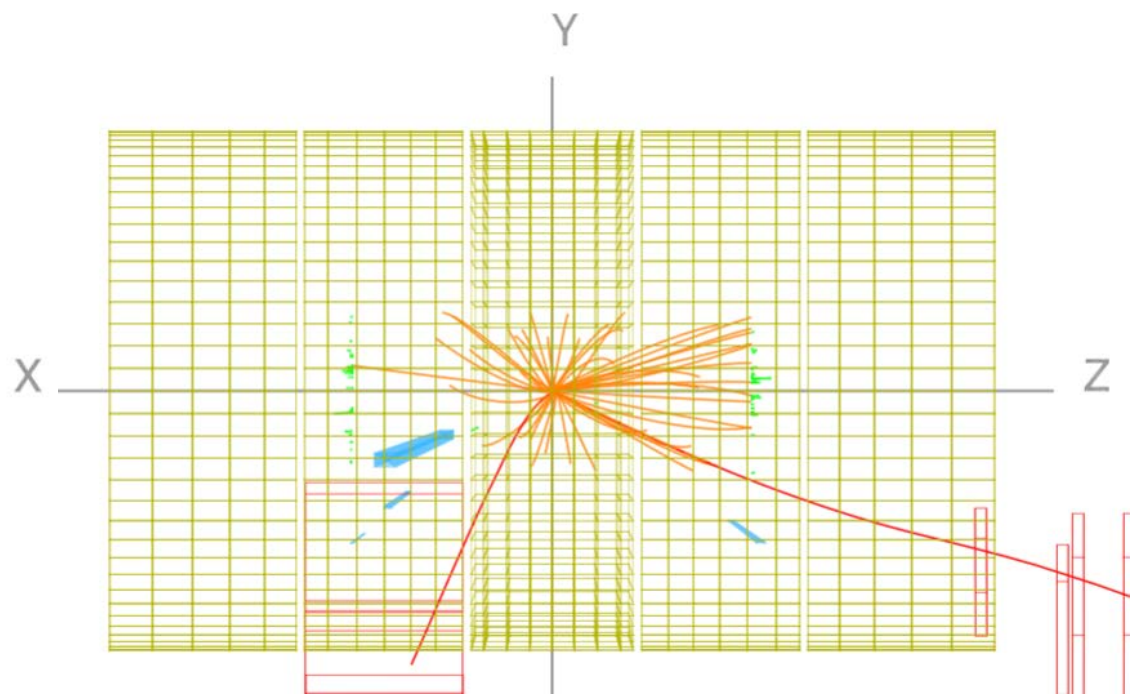
x-y view: measure ϕ



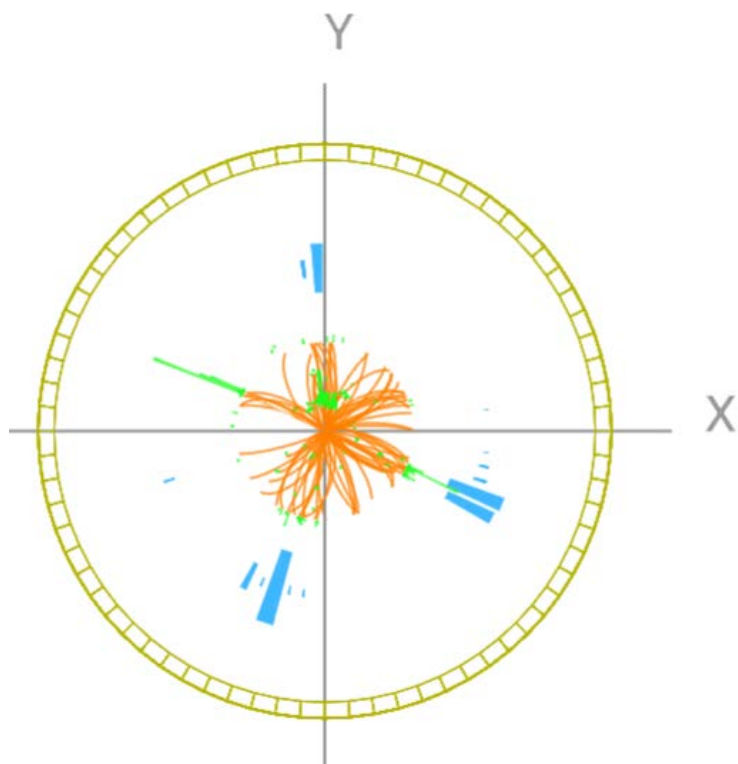
z-y view: measure θ



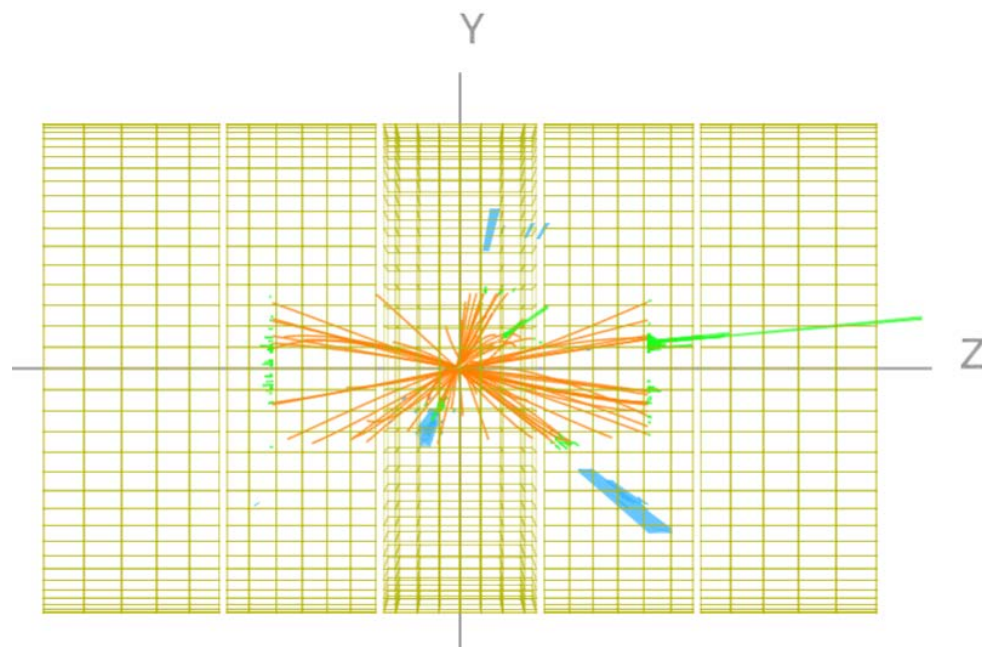
x-y view: measure ϕ



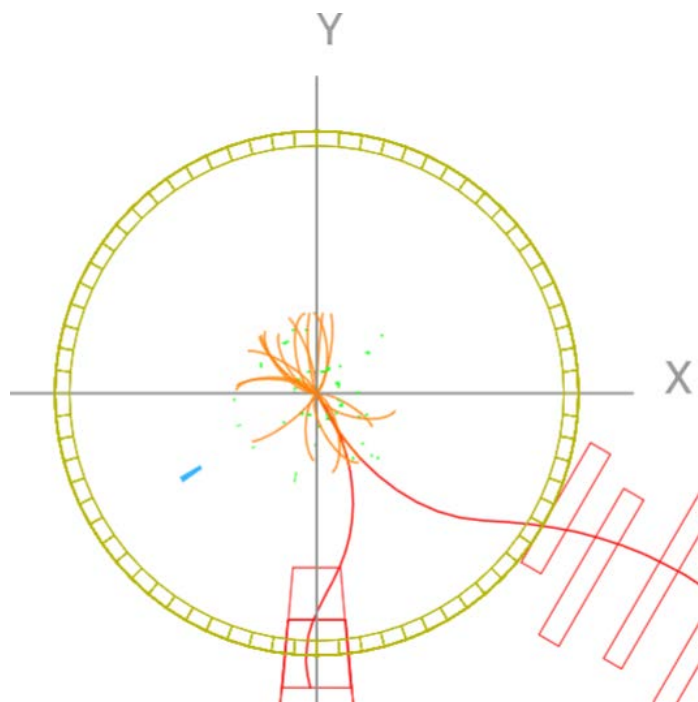
z-y view: measure θ



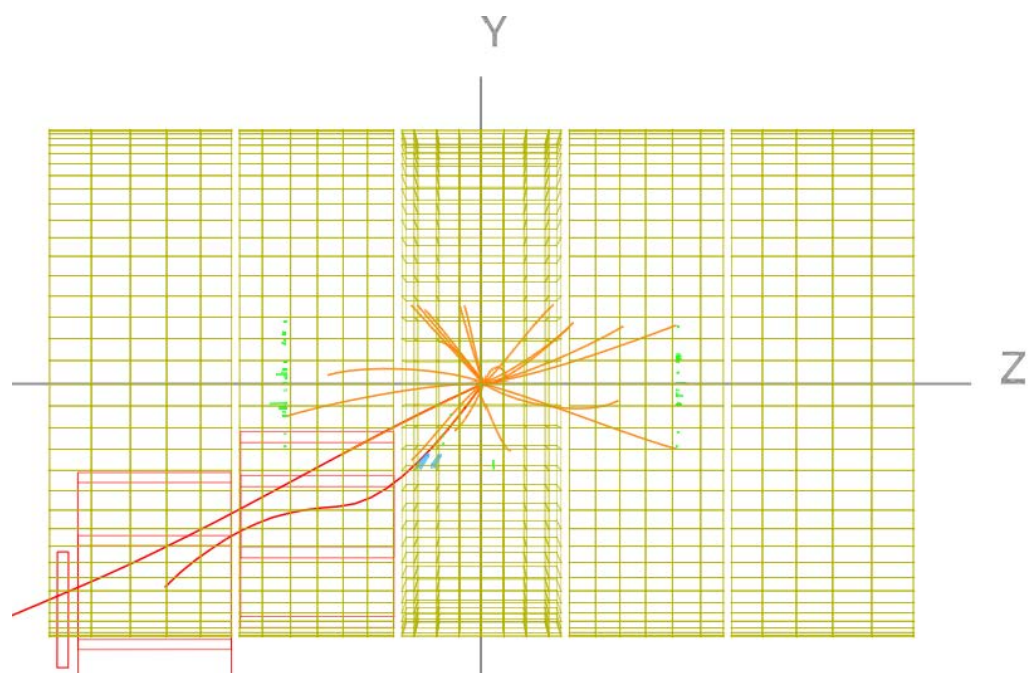
x-y view: measure ϕ



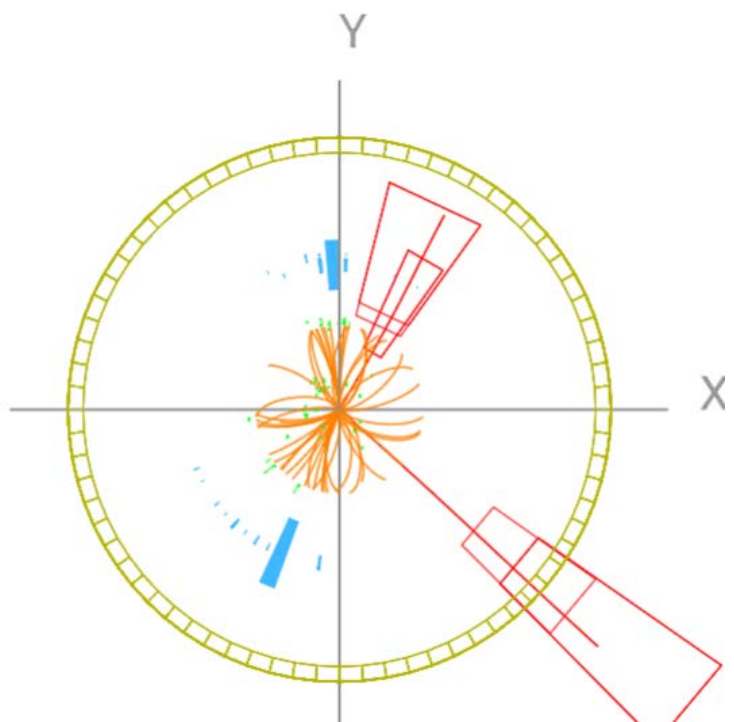
z-y view: measure θ



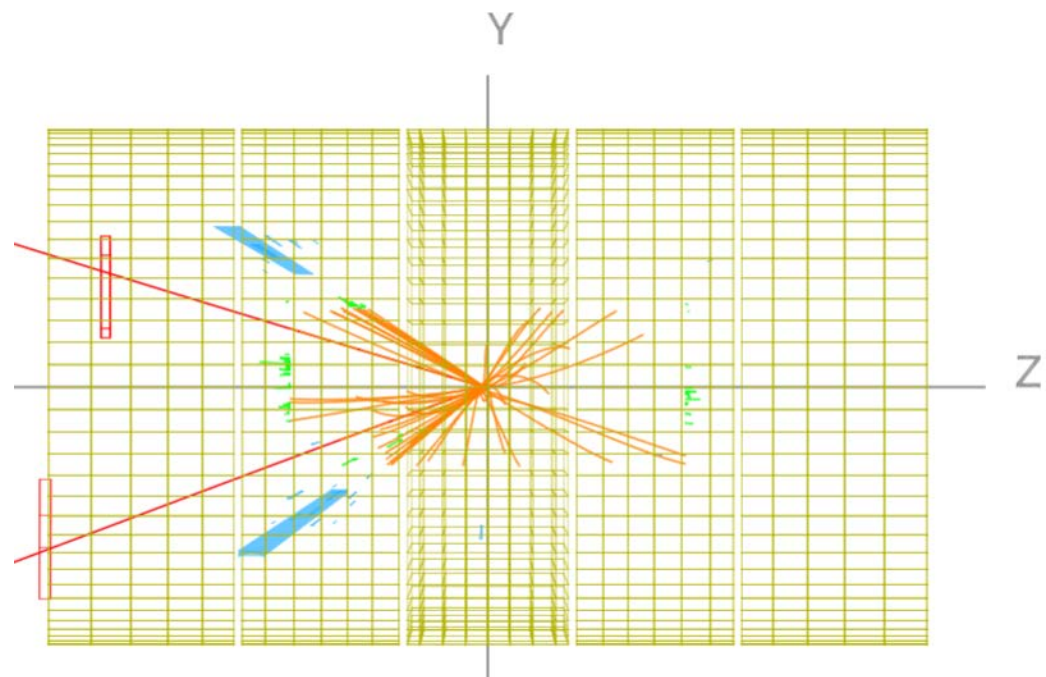
x-y view: measure ϕ



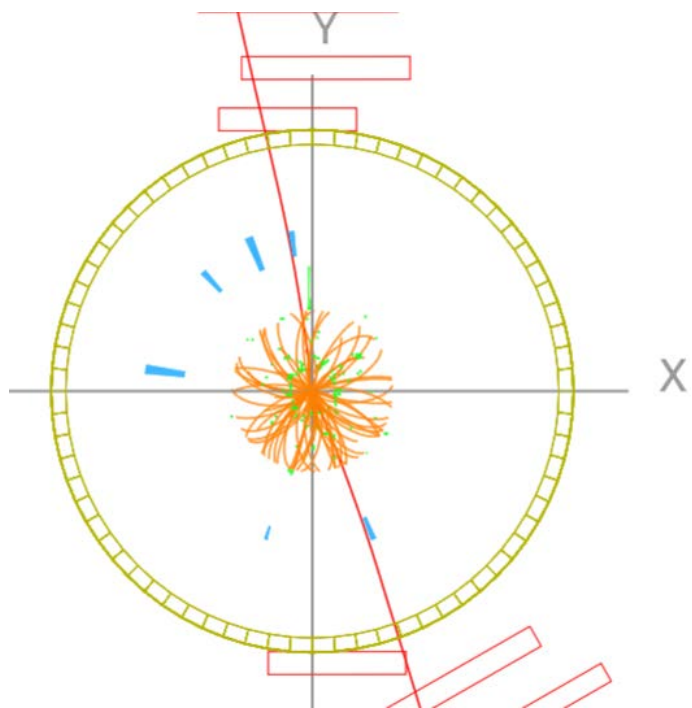
z-y view: measure θ



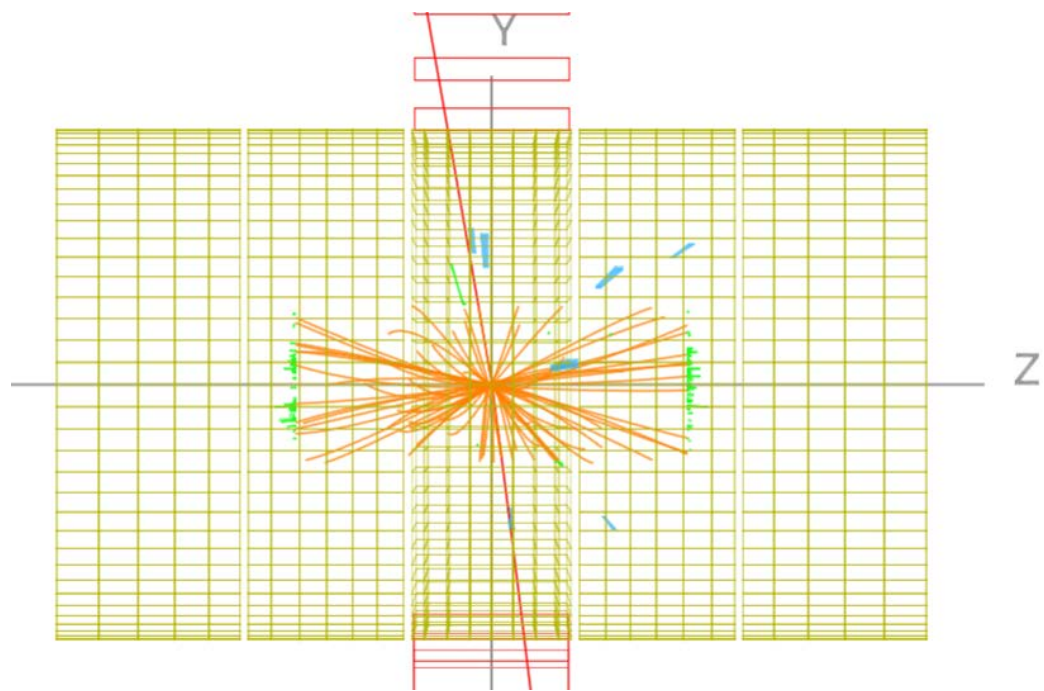
x-y view: measure ϕ



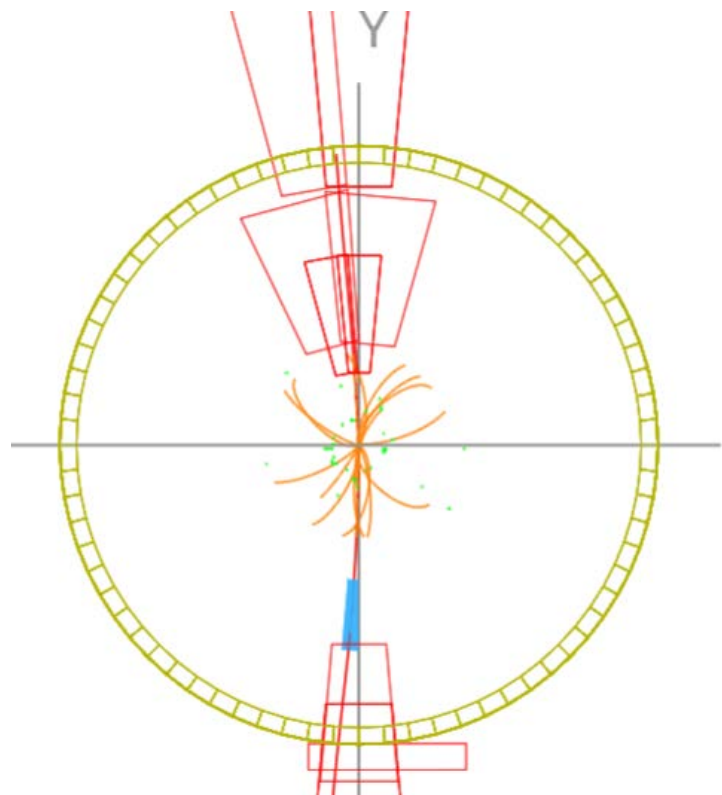
z-y view: measure θ



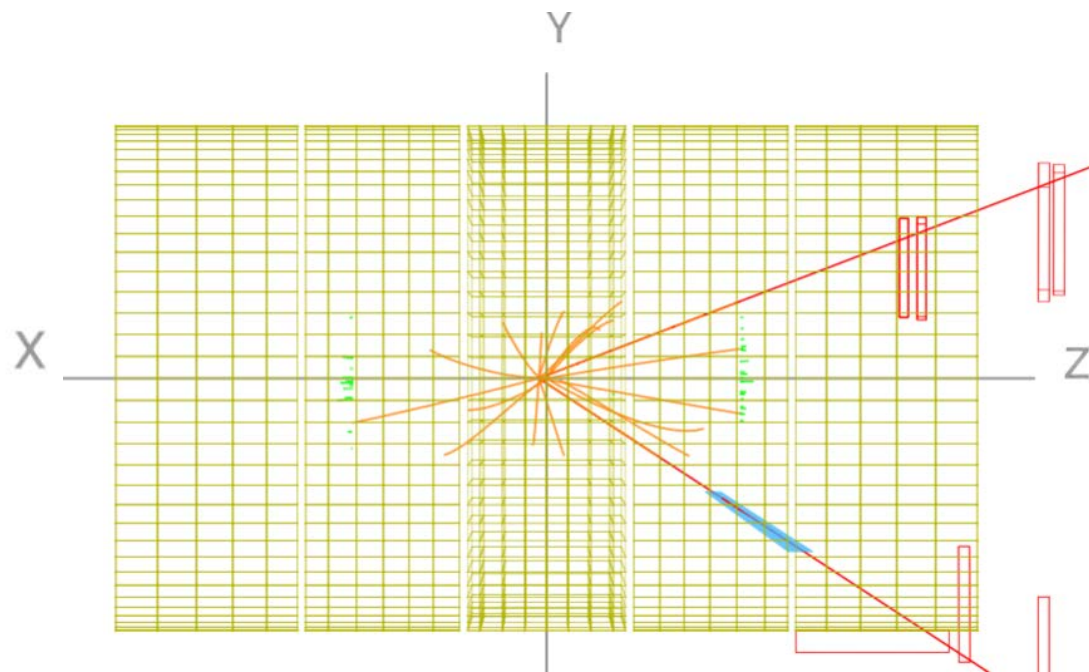
x-y view: measure ϕ



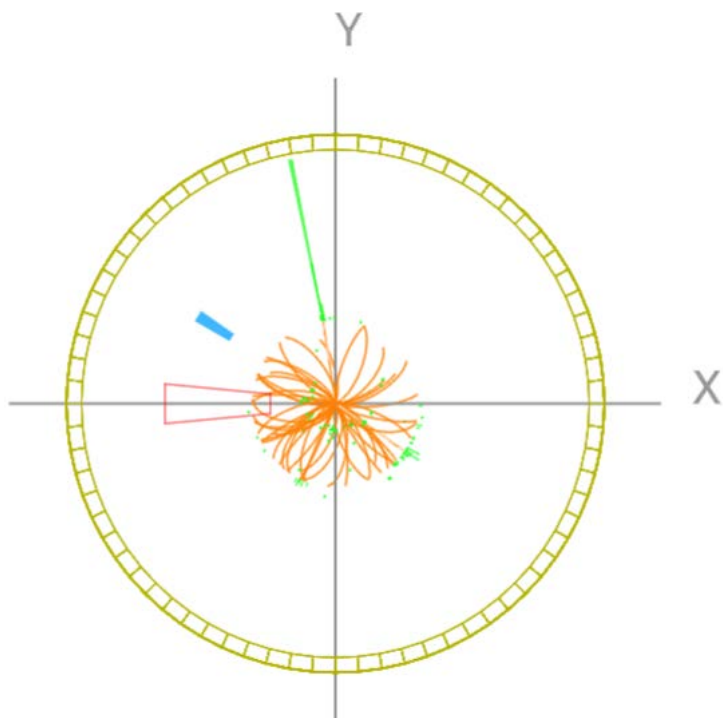
z-y view: measure θ



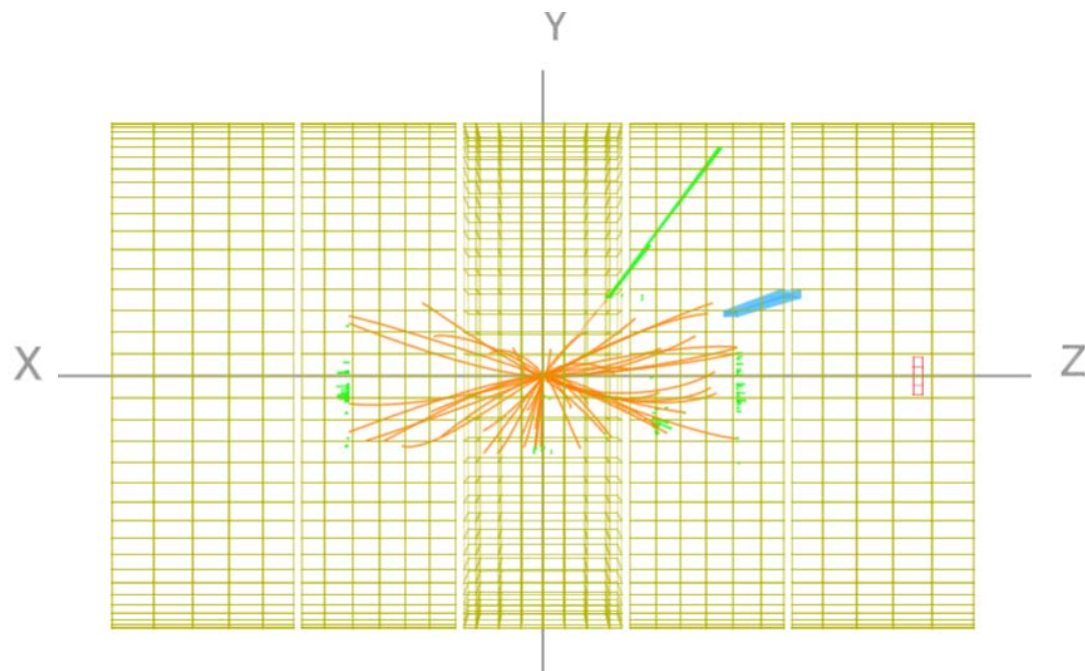
x-y view: measure ϕ



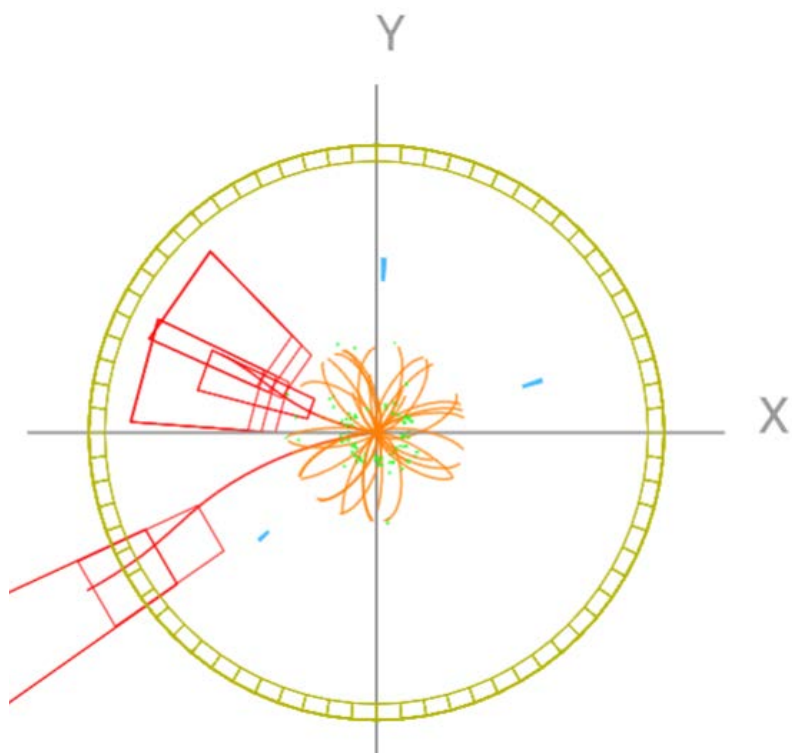
z-y view: measure θ



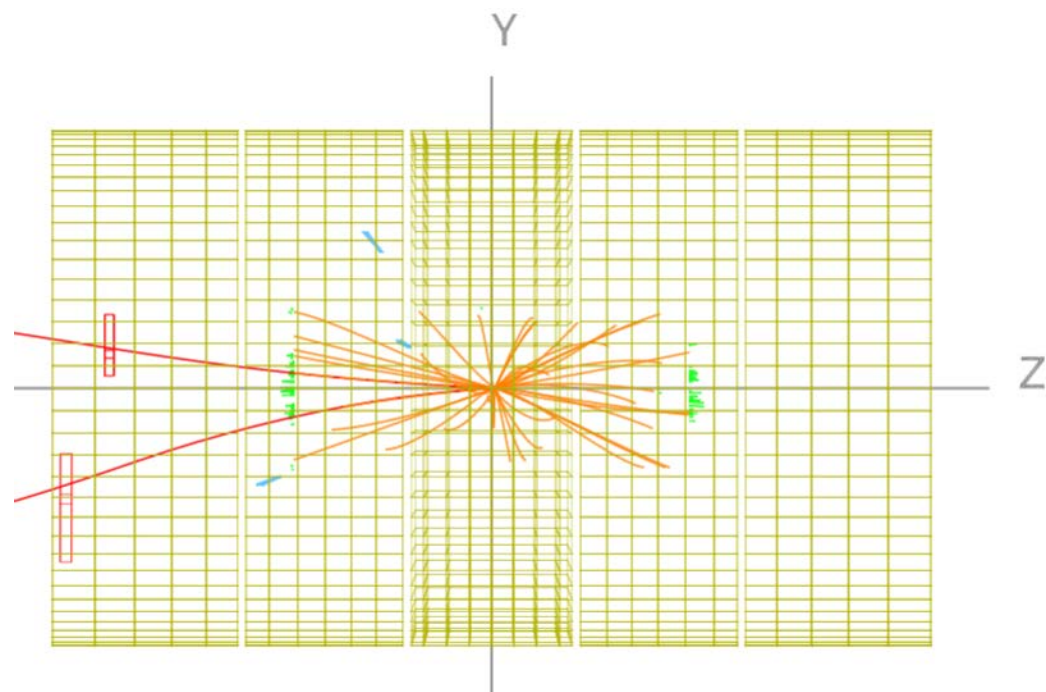
x-y view: measure ϕ



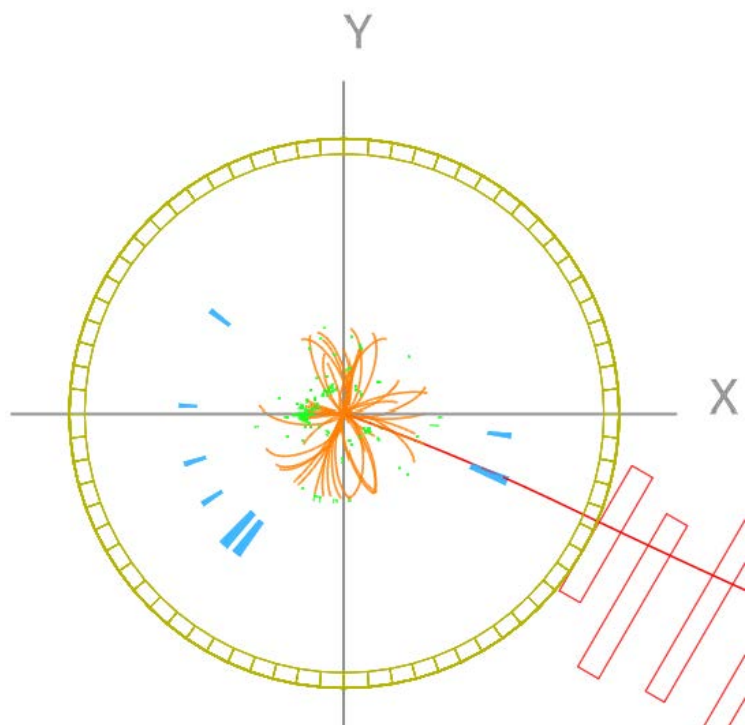
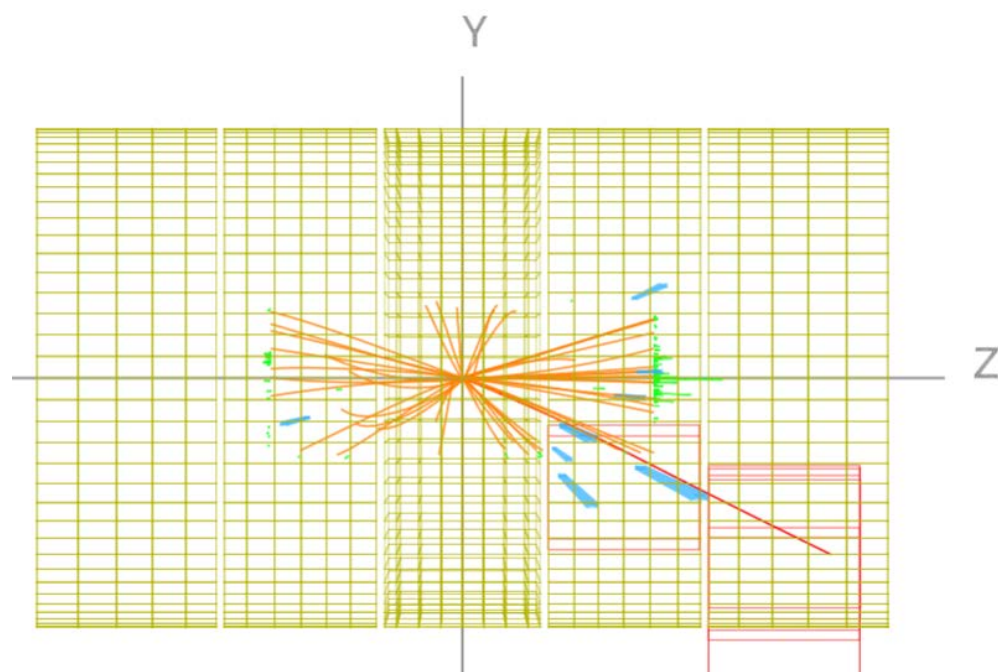
z-y view: measure θ

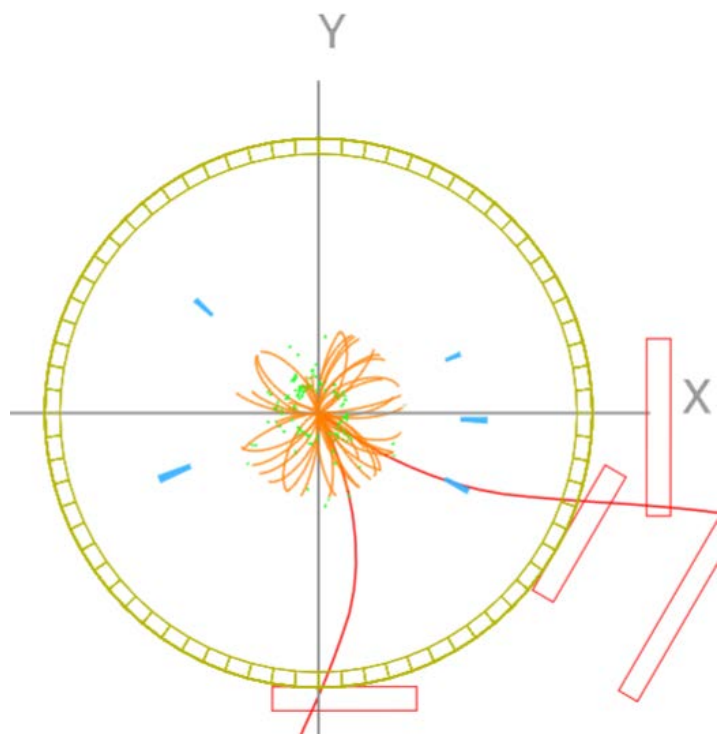


x-y view: measure ϕ

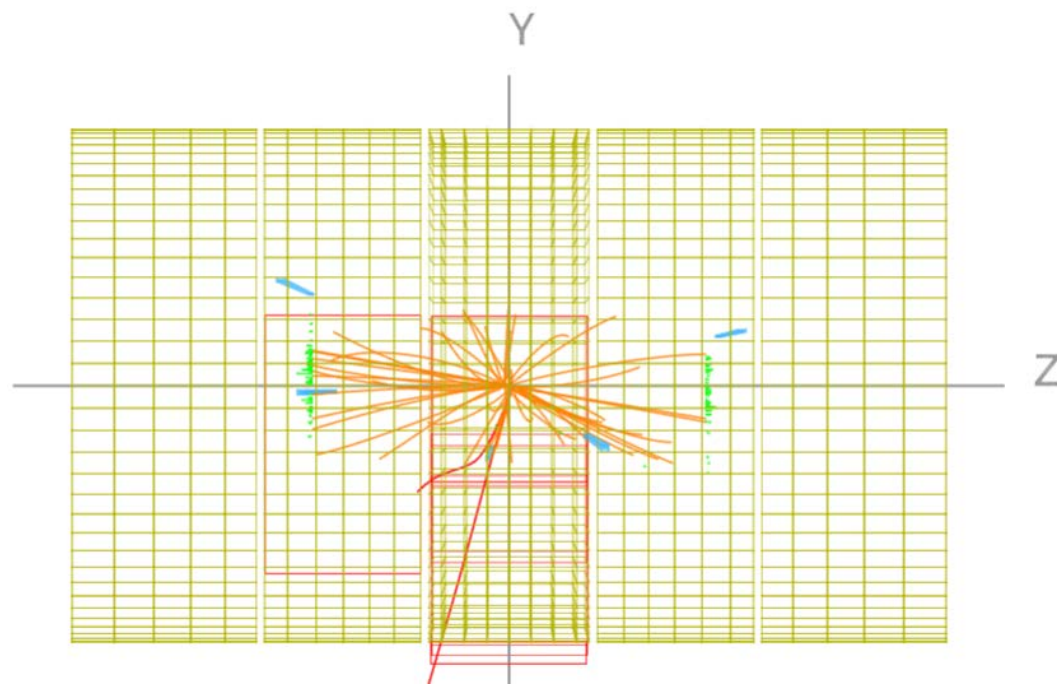


z-y view: measure θ

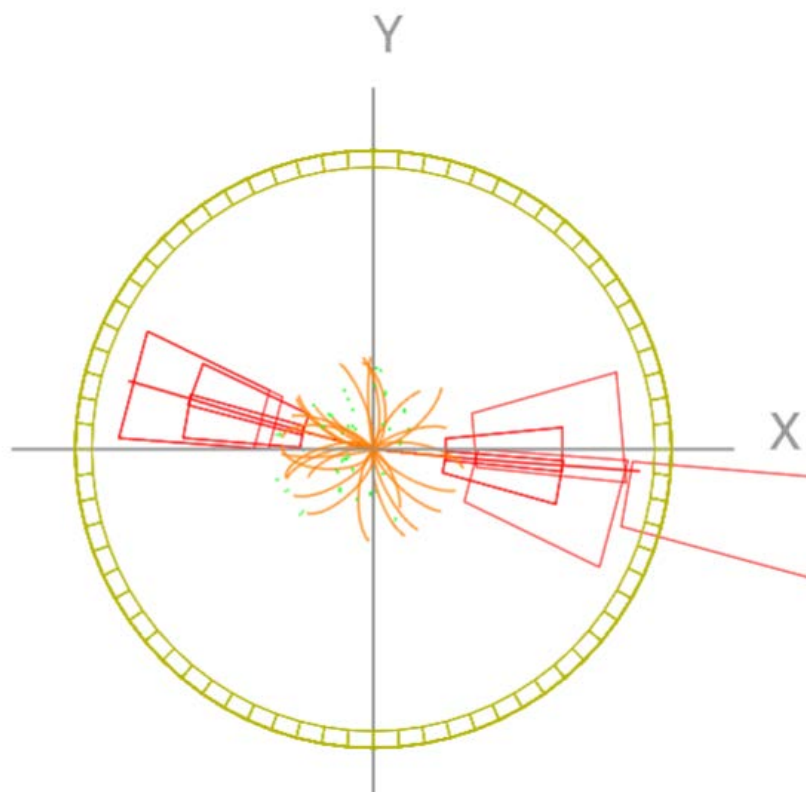
x-y view: measure ϕ z-y view: measure θ



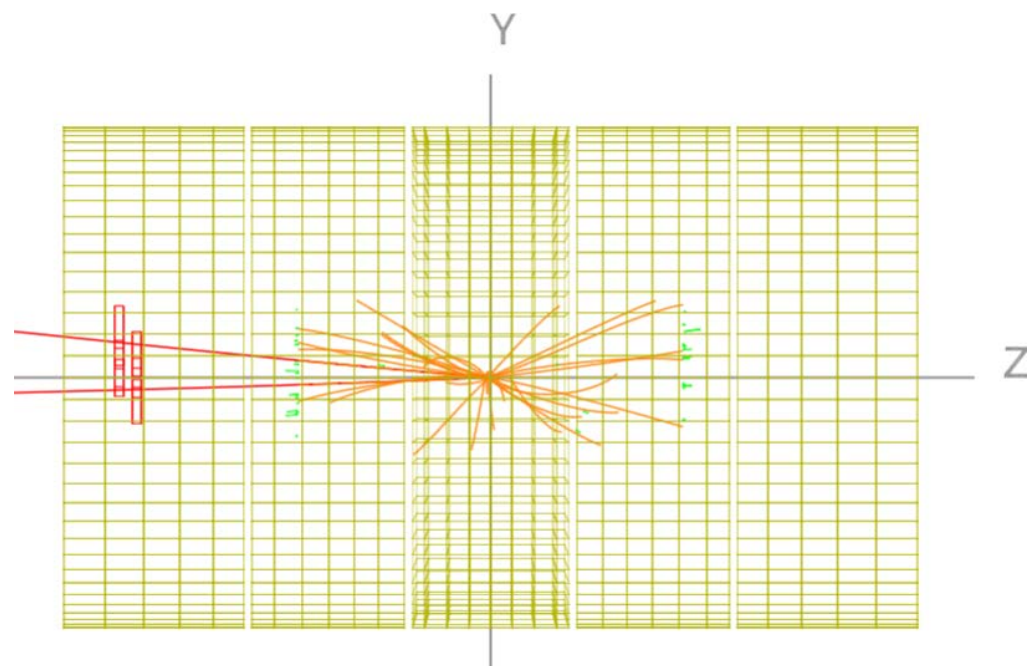
x-y view: measure ϕ



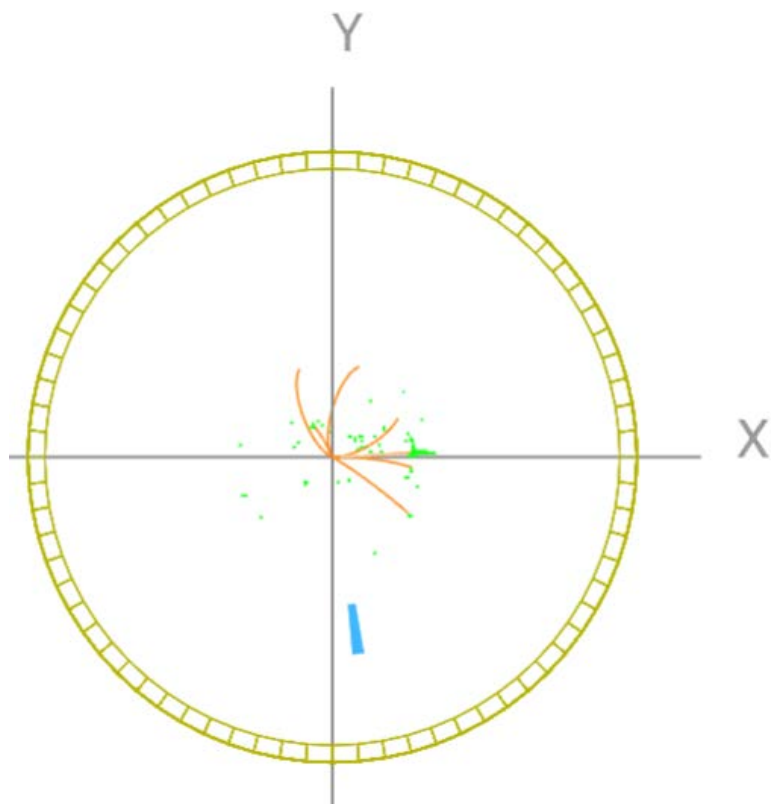
z-y view: measure θ



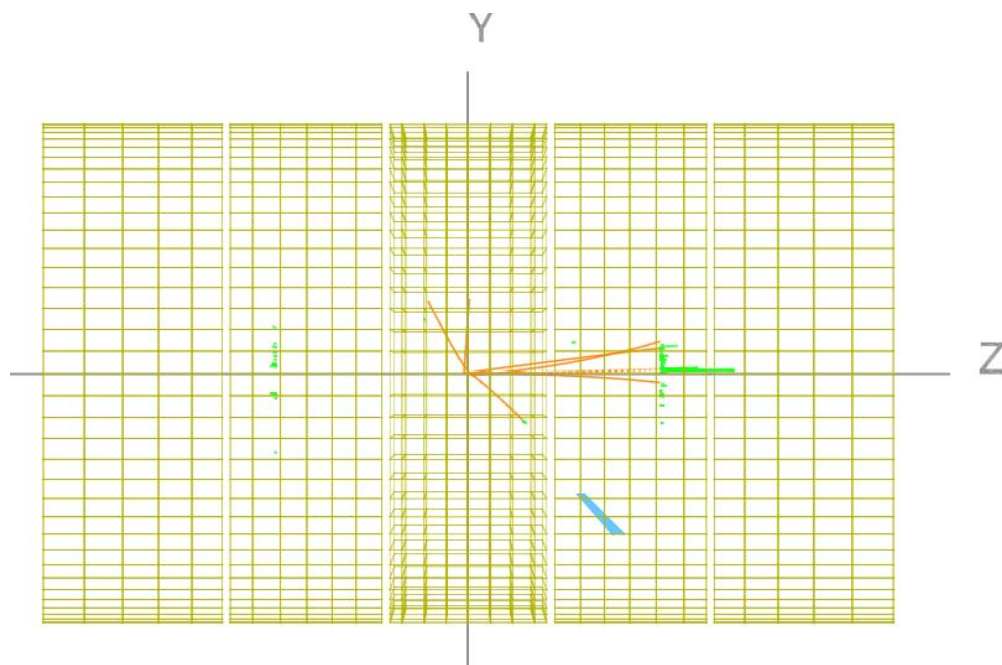
x-y view: measure ϕ



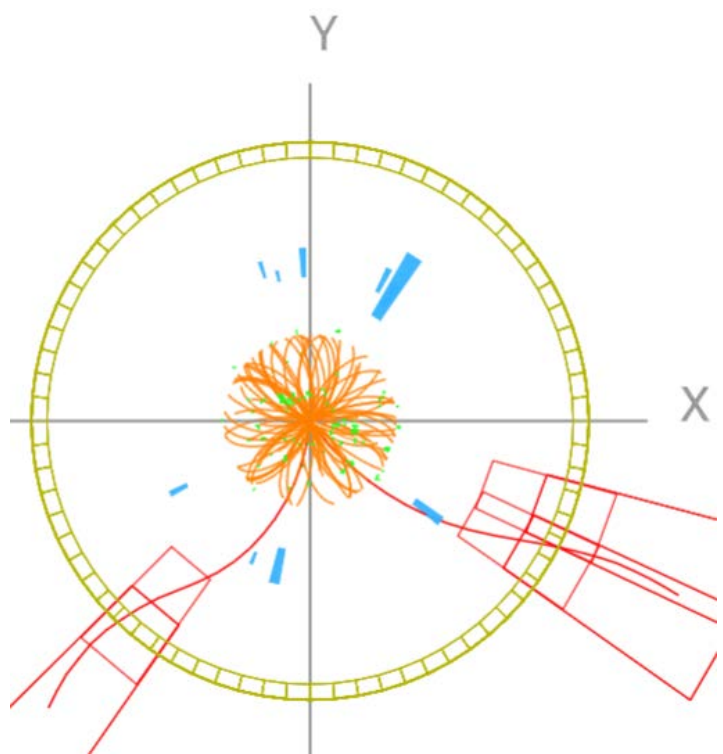
z-y view: measure θ



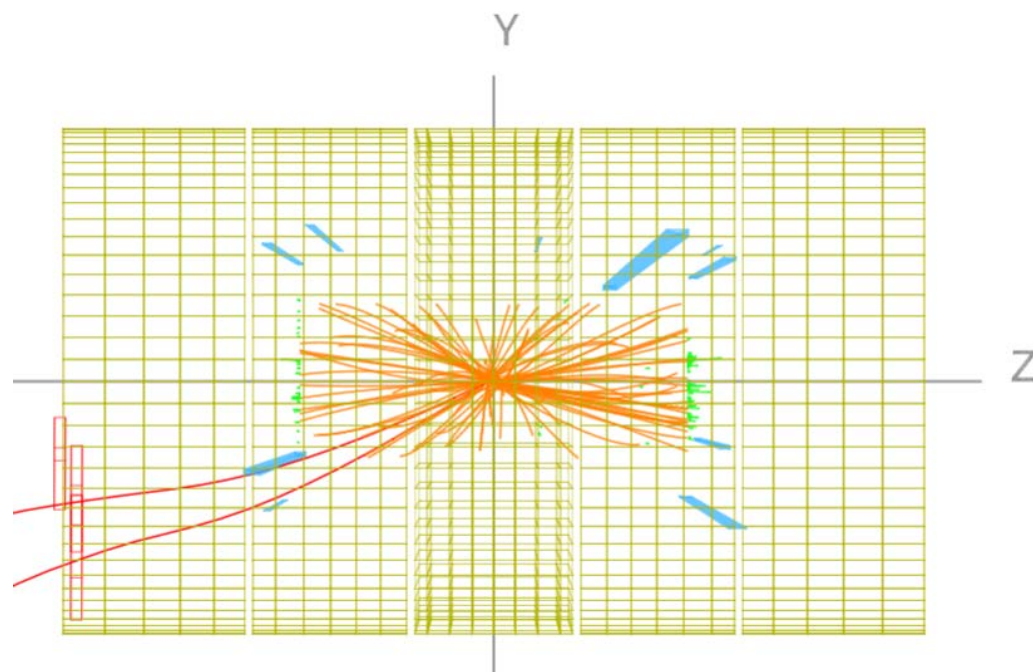
x-y view: measure ϕ



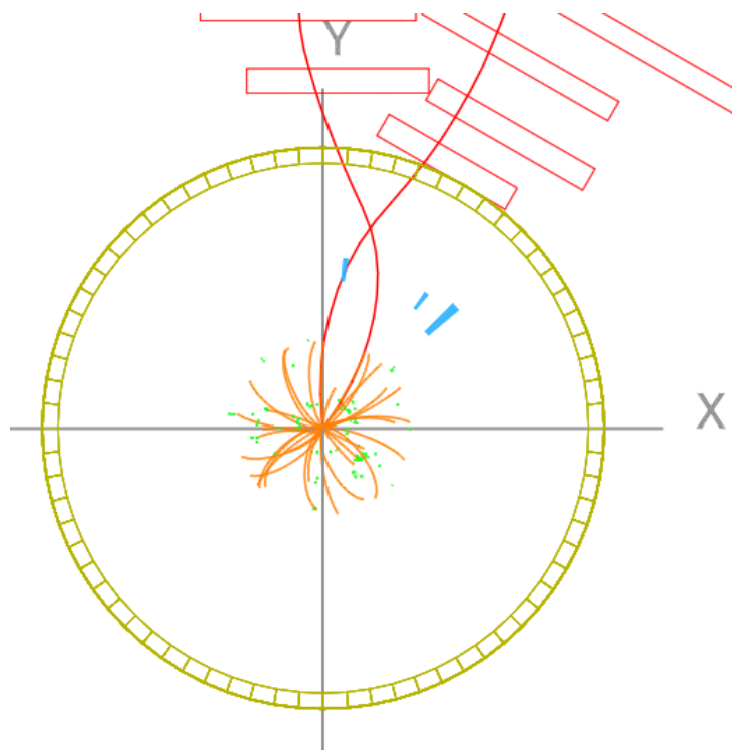
z-y view: measure θ



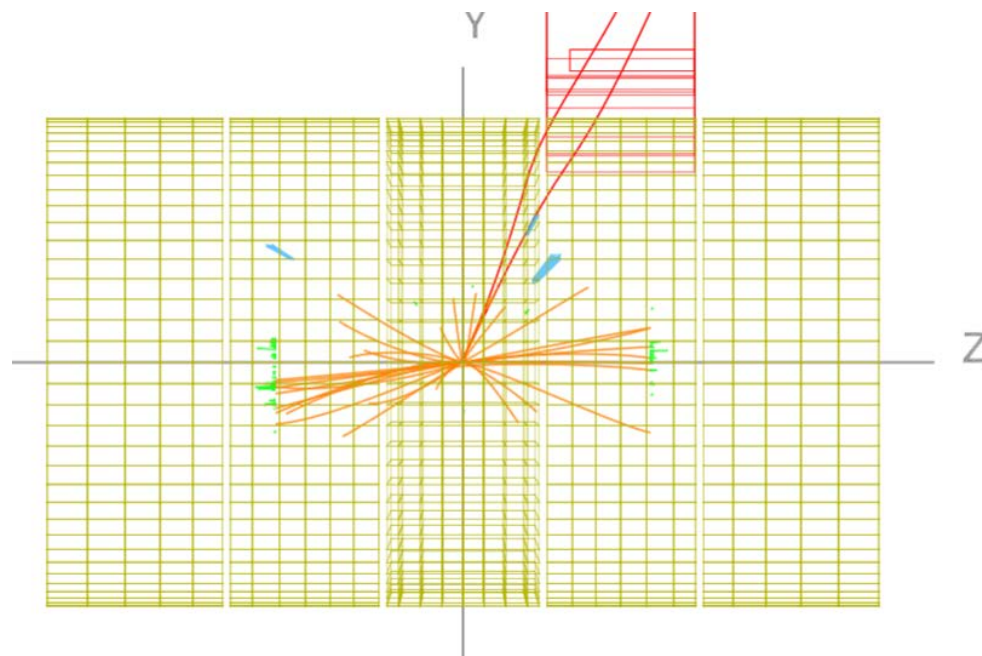
x-y view: measure ϕ



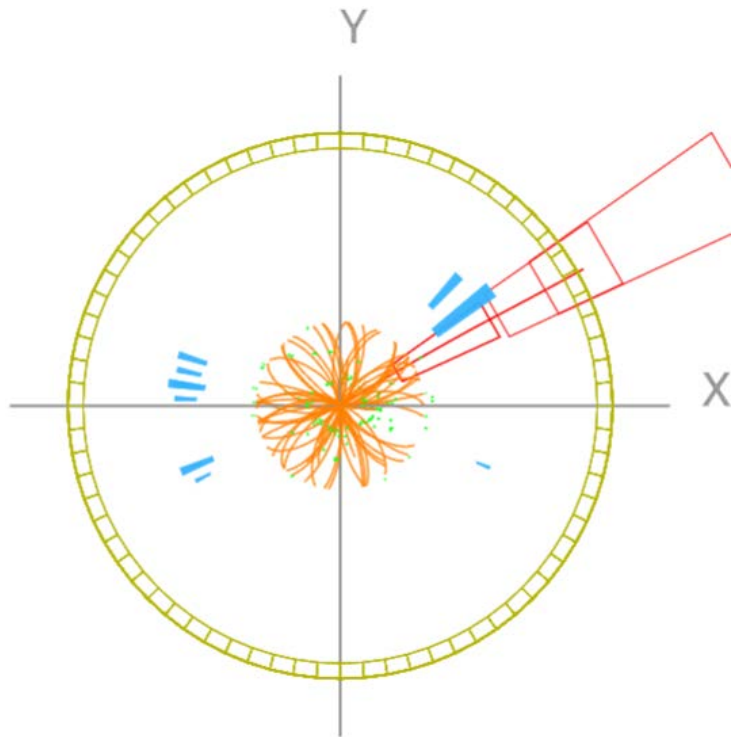
z-y view: measure θ



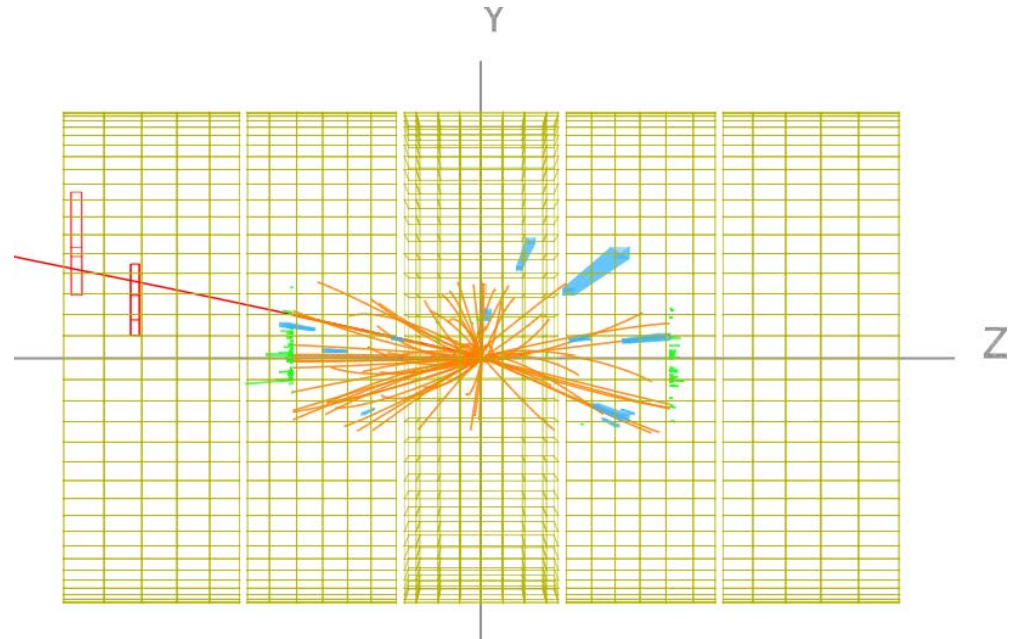
x-y view: measure ϕ



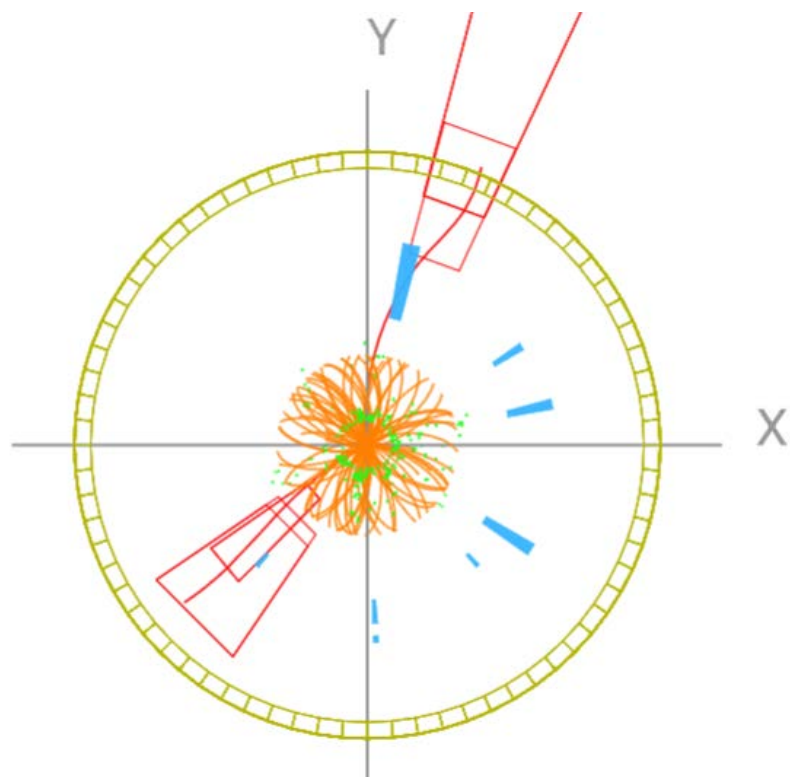
z-y view: measure θ



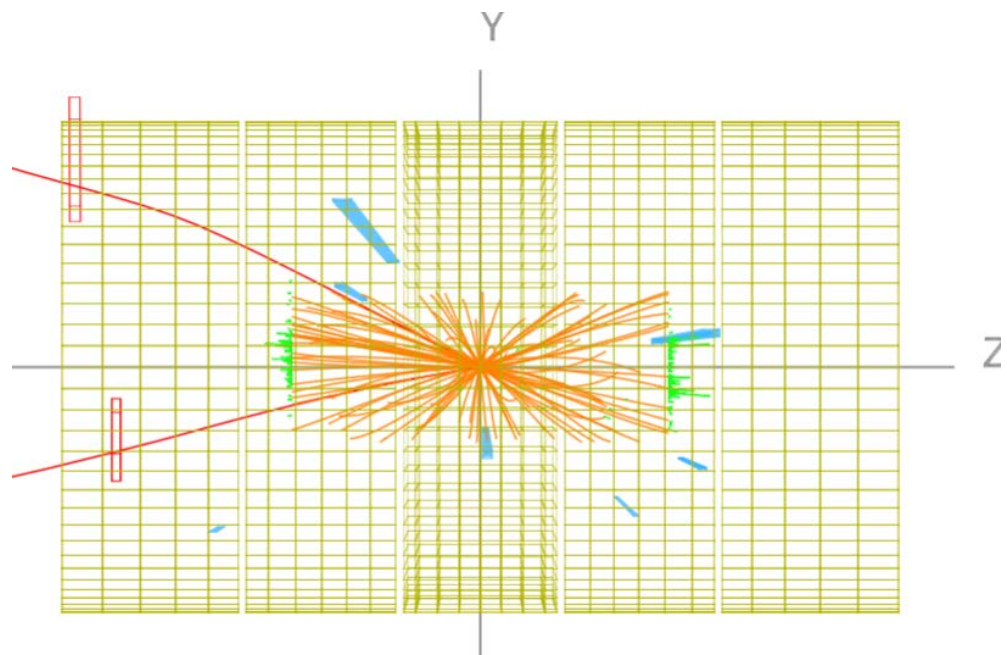
x-y view: measure ϕ



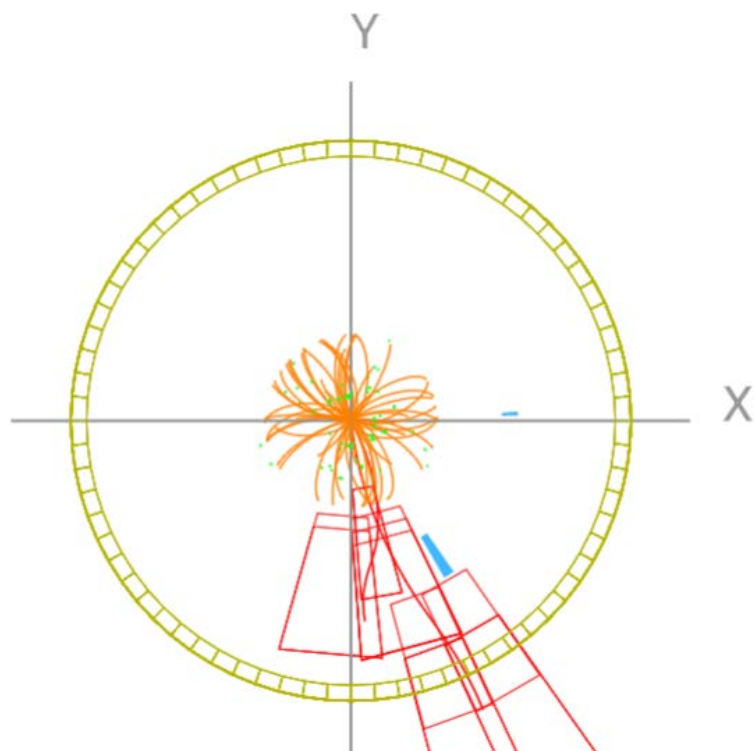
z-y view: measure θ



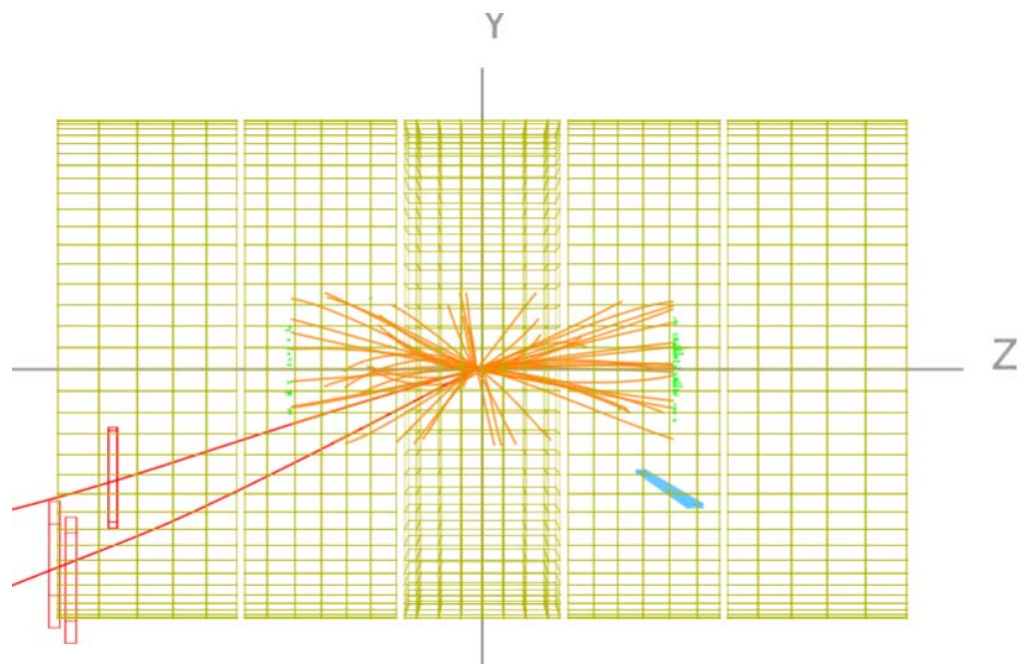
x-y view: measure ϕ



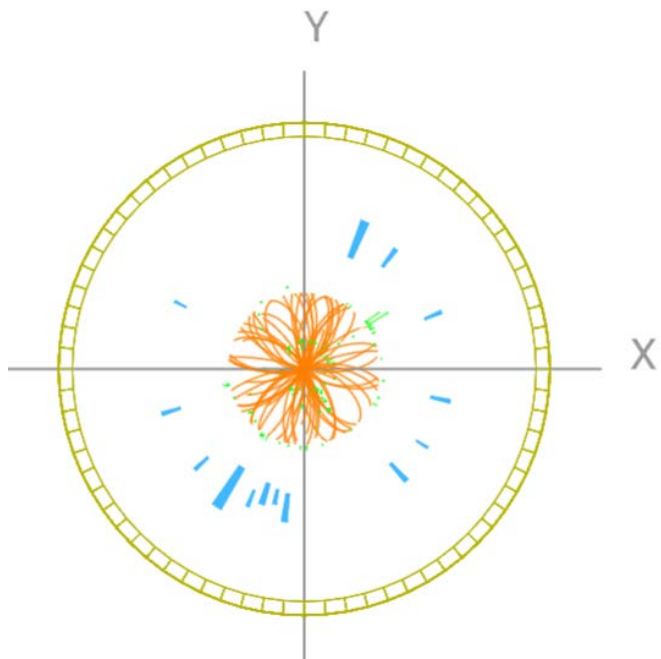
z-y view: measure θ



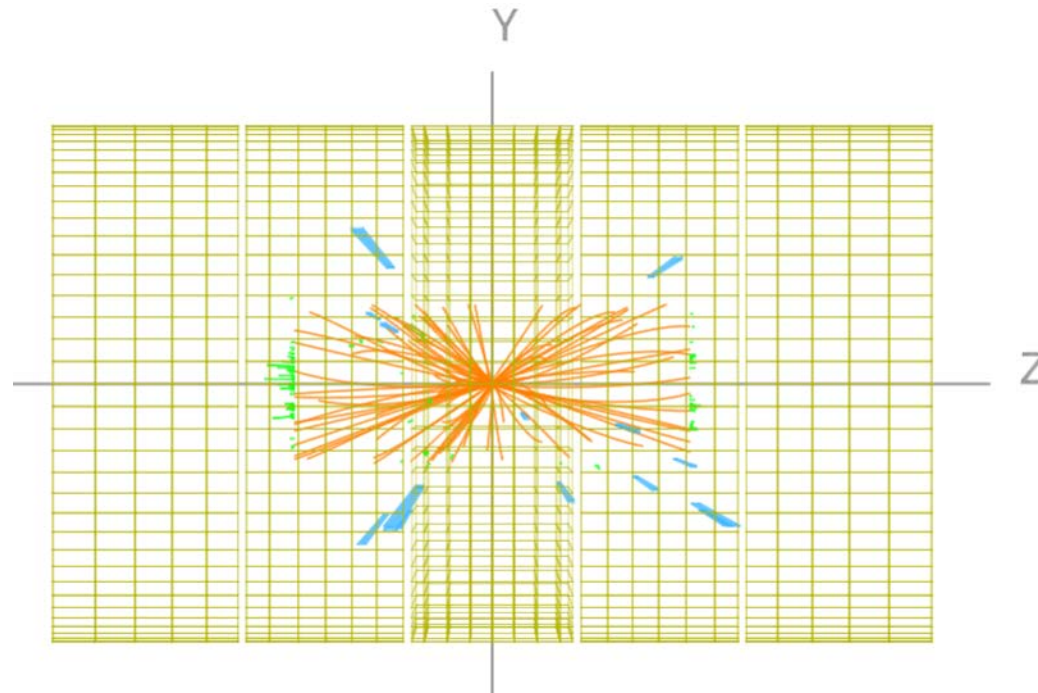
x-y view: measure ϕ



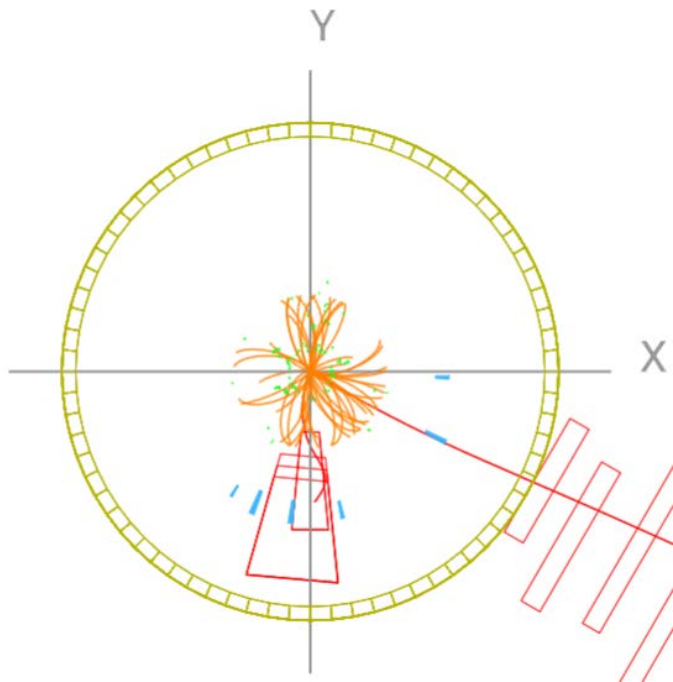
z-y view: measure θ



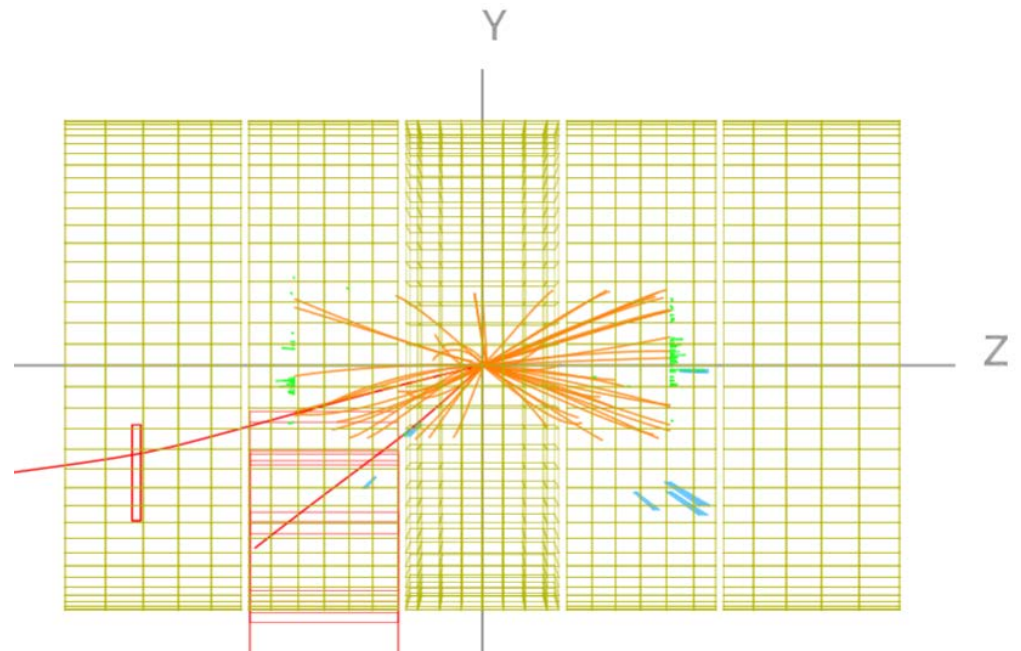
x-y view: measure ϕ



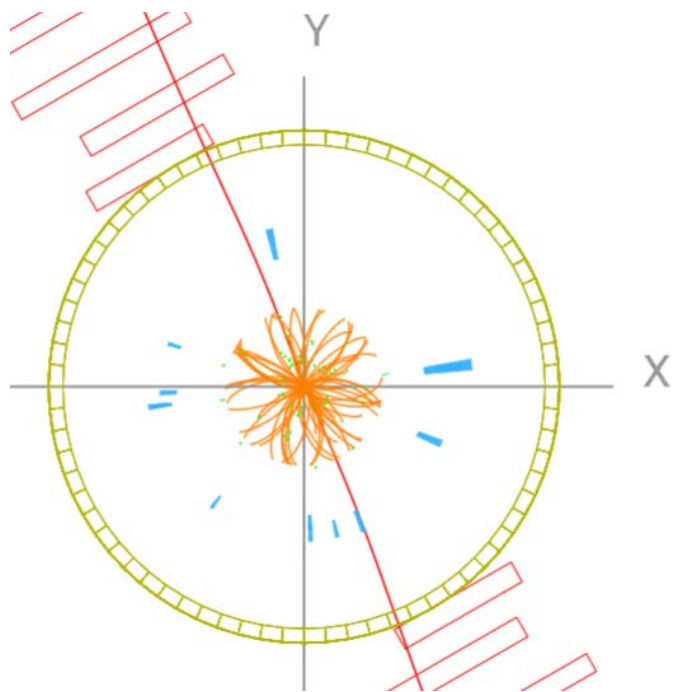
z-y view: measure θ



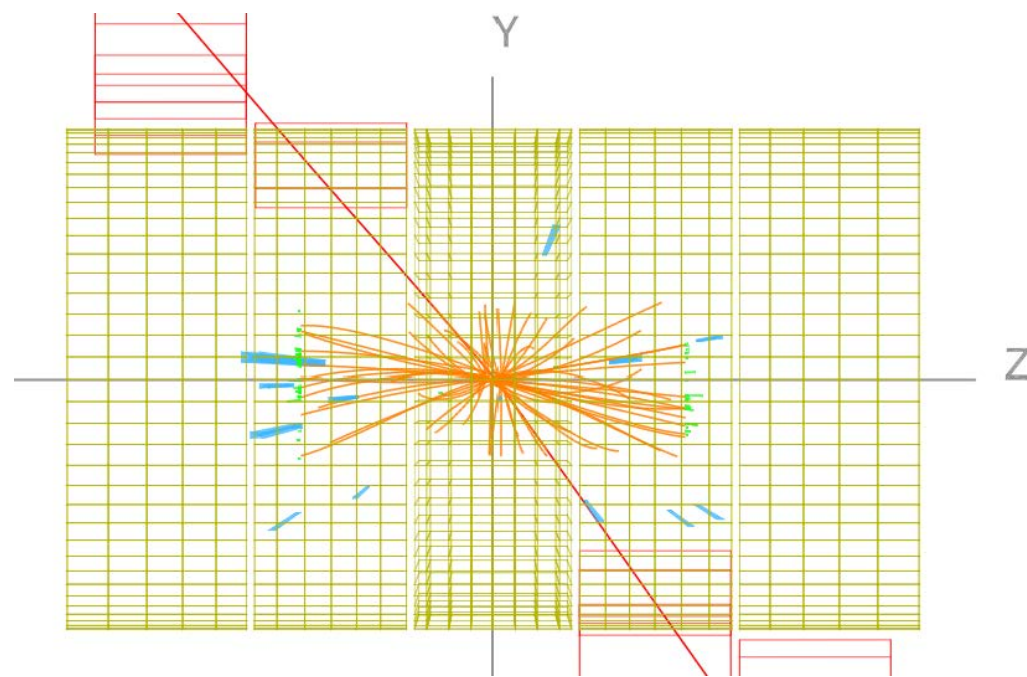
x-y view: measure ϕ



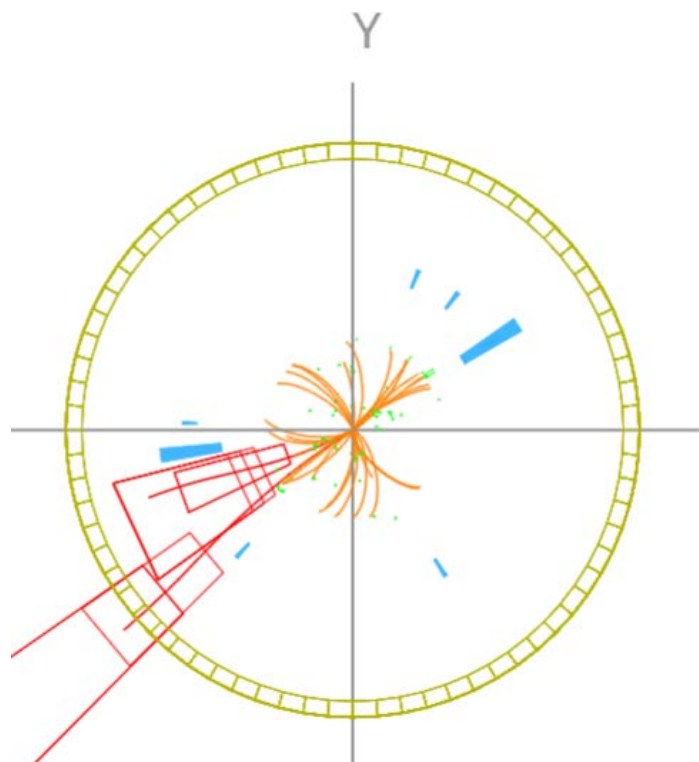
z-y view: measure θ



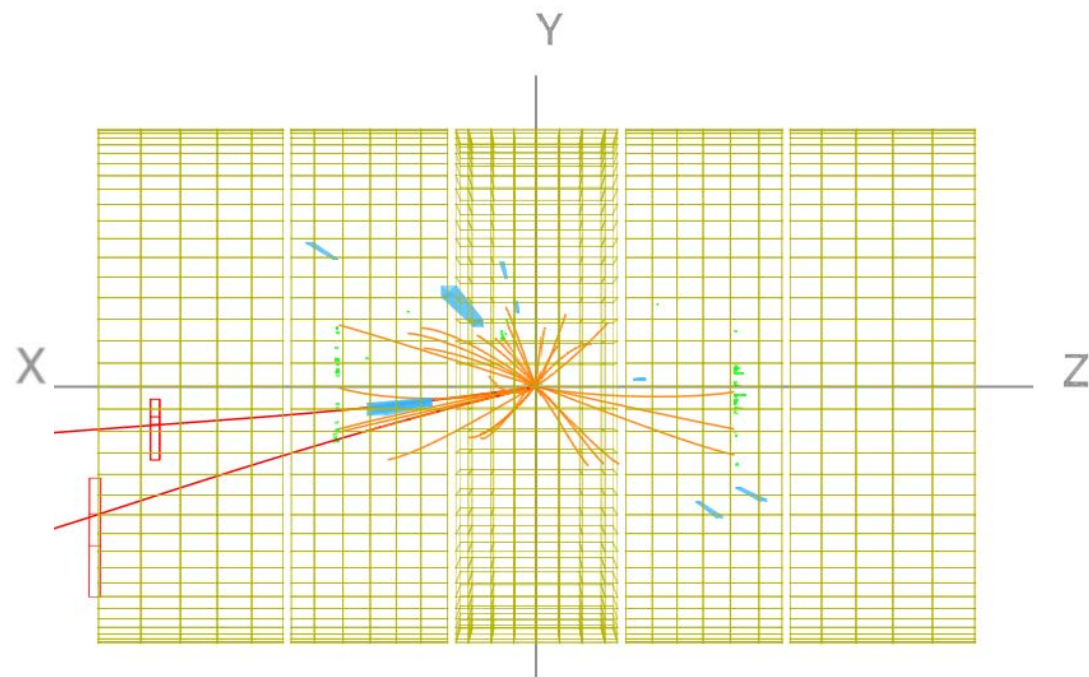
x-y view: measure ϕ



z-y view: measure θ



x-y view: measure ϕ



z-y view: measure θ